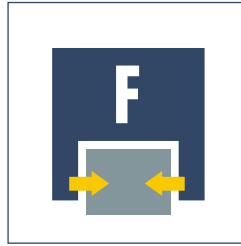




**Sizes**  
50 .. 200



**Weight**  
0.20 kg .. 11.0 kg



**Gripping force**  
260 N .. 16000 N

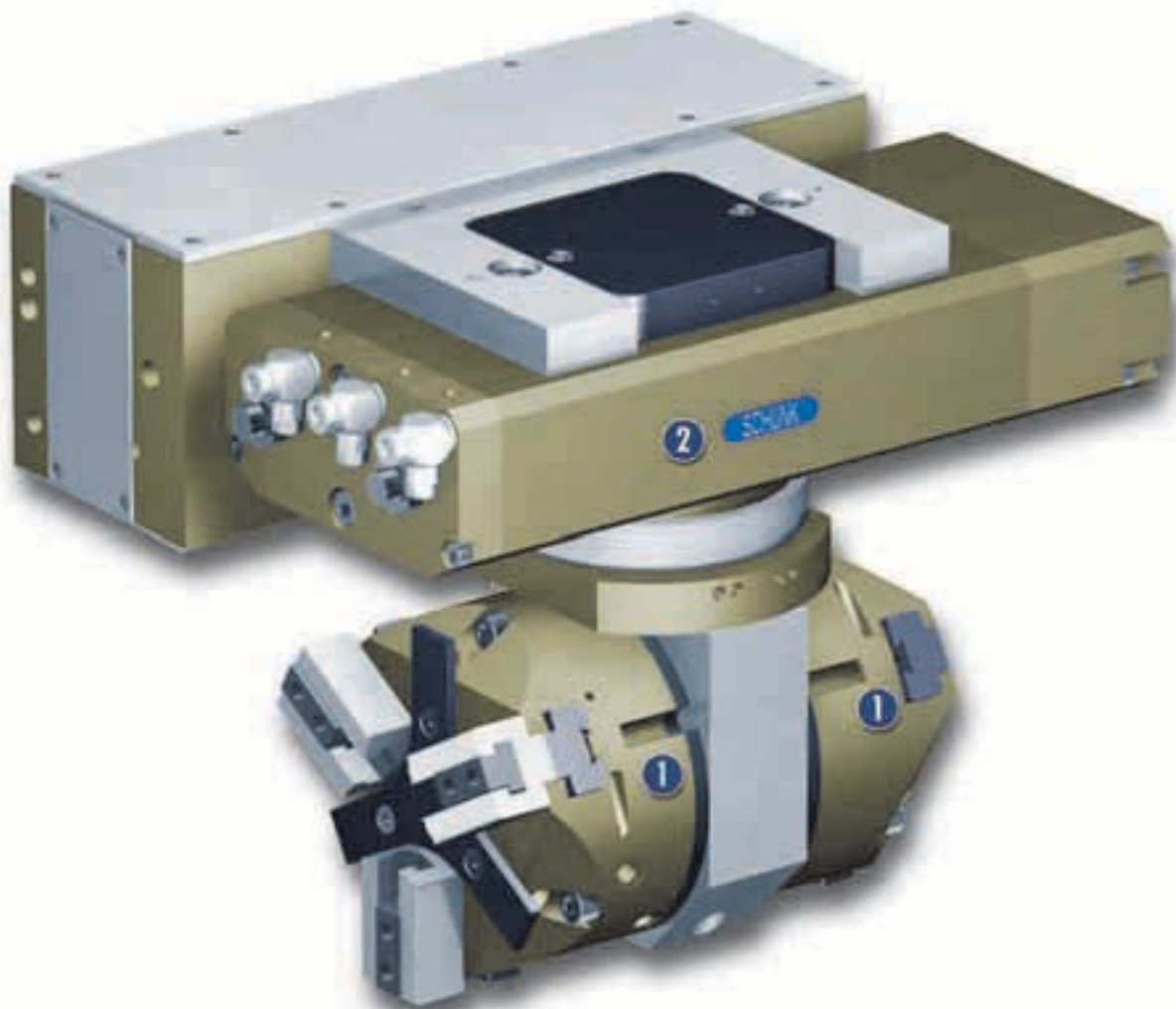


**Stroke per finger**  
2 mm .. 25 mm



**Force-fit gripping**  
1.3 kg .. 80 kg

### Application example



Handling unit for loading and unloading cylindrical blanks and finished parts into a lathe. The pressure plate is used to press the blank securely up to the stop of the chuck.

**1** 3-Finger Centric Gripper  
PZN 125 with pressure plate

**2** Rotary Actuator OSE-C 45

## Universal Gripper

Universal 3-finger centric gripper with high gripping force and robust T-slot guidance

### Area of application

For universal use in clean and slightly dirty environments

### Your advantages and benefits

#### High precision T-slot guidance

guarantees enormous versatility

#### High maximum moments possible

This makes it suitable for the use of long gripper fingers

#### High gripping forces

for a wide range of applications

#### Air supply via hose-free direct connection or via threaded joints

for flexible pressure supply in all automated systems



### General information on the series

#### Working principle

Wedge-hook kinematics

#### Housing material

Aluminum alloy, hard-anodized

#### Base jaws material

Steel

#### Actuation

Pneumatic, via filtered compressed air (10 µm): Dry, lubricated or non-lubricated  
Pressure medium: Requirement on the quality class of compressed air according to DIN ISO 8573-1: Quality class 4

#### Warranty

24 months

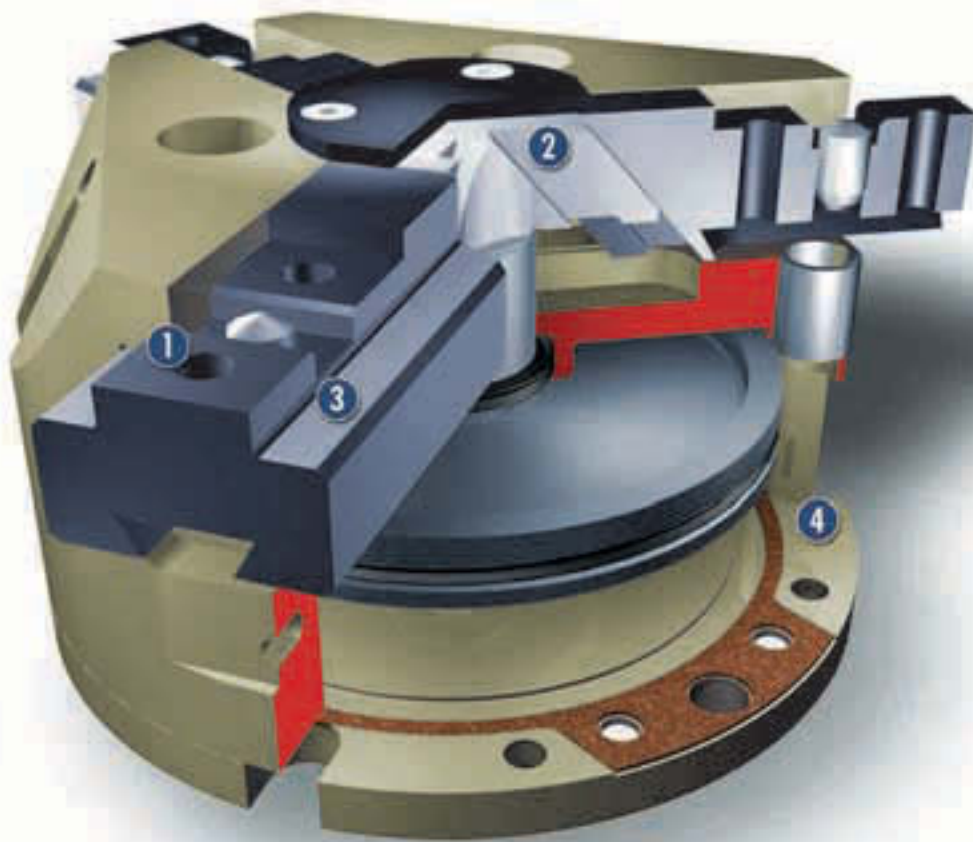
#### Scope of delivery

Brackets for proximity switches, dowel pins, O-rings for direct connection, assembly and operating manual with manufacturer's declaration

#### Gripping force safety device

Possible using versions with mechanical gripping force safety device or pressure maintenance valve SDV-P

### Sectional diagram



**1 Base jaws**  
for the mounting of workpiece-specific gripper fingers

**2 Kinematics**  
wedge hook design for high power transmission and synchronized gripping

**3 T-slot guidance**  
robust T-slot base jaw guide with minimum play

**4 Housing**  
weight-reduced thanks to the use of a high-strength aluminum alloy

### Functional description

The piston is pressed up or down by compressed air. Via its slanted working surfaces, the wedge hook redirects this vertical movement into a horizontal, synchronous gripping motion of the three base jaws.

### Options and special information

Please use the PZN only for **ordering replacements**; for **new designs**, please use the successor model **PZN-plus**.

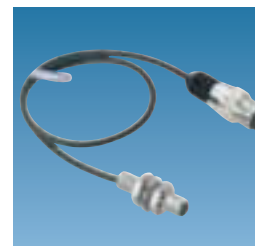
## Accessories

SCHUNK accessories — the suitable complement for the highest level of functionality, reliability and controlled production of all automation modules.

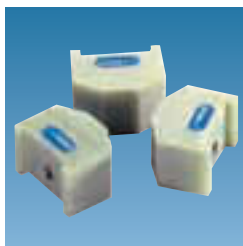
### Fittings



### Inductive proximity switches IN



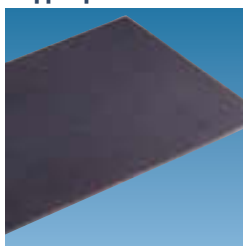
### Plastic inserts – Quentes



### Sensor cables W/WK/KV/GK



### Gripper pads HKI



### V sensor distributor



### Pressure maintenance valves SDV-P



### Finger blanks



### Flexible position sensor FPS



① Please refer to the additional views at the end of each size for the specific size of the required accessory, availability for the gripper size, the description and the ID No. You can find more detailed information on our range of accessories in the "Accessories" catalog section.

## General information on the series

### Gripping force

is the arithmetic total of the gripping force applied to each base jaw at distance P (see illustration) measured from the upper edge of the gripper.

### Finger length

is measured from the upper edge of the gripper housing in the direction of the main axis.

### Repeat accuracy

is defined as the variance of the end position after 100 consecutive strokes.

### Workpiece weight

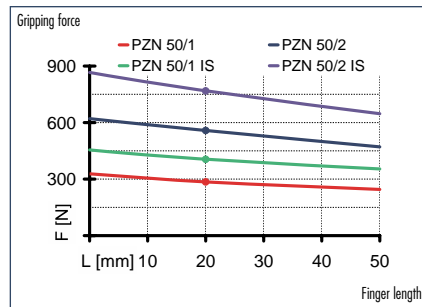
The recommended workpiece weight is calculated for force-fit gripping with a friction coefficient of 0.1 and a safety of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit clamping.

### Closing and opening times

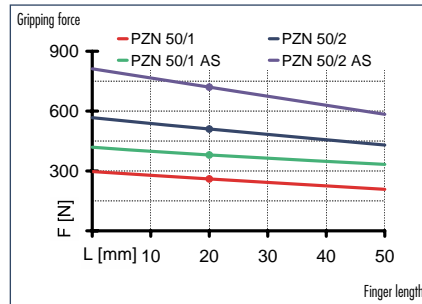
Closing and opening times are the pure movement times of the base jaws or fingers. Valve switching times, hose filling times or PLC reaction times are not included and must be taken into consideration when determining cycle times.



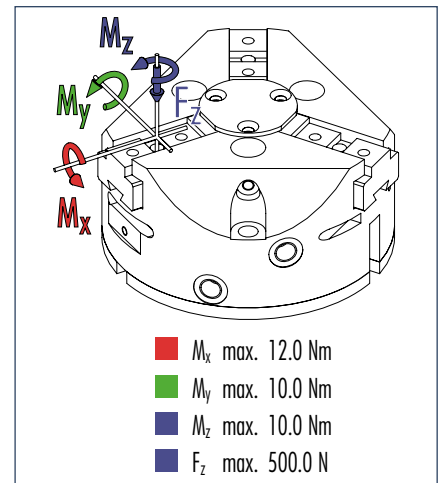
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping



### Finger load

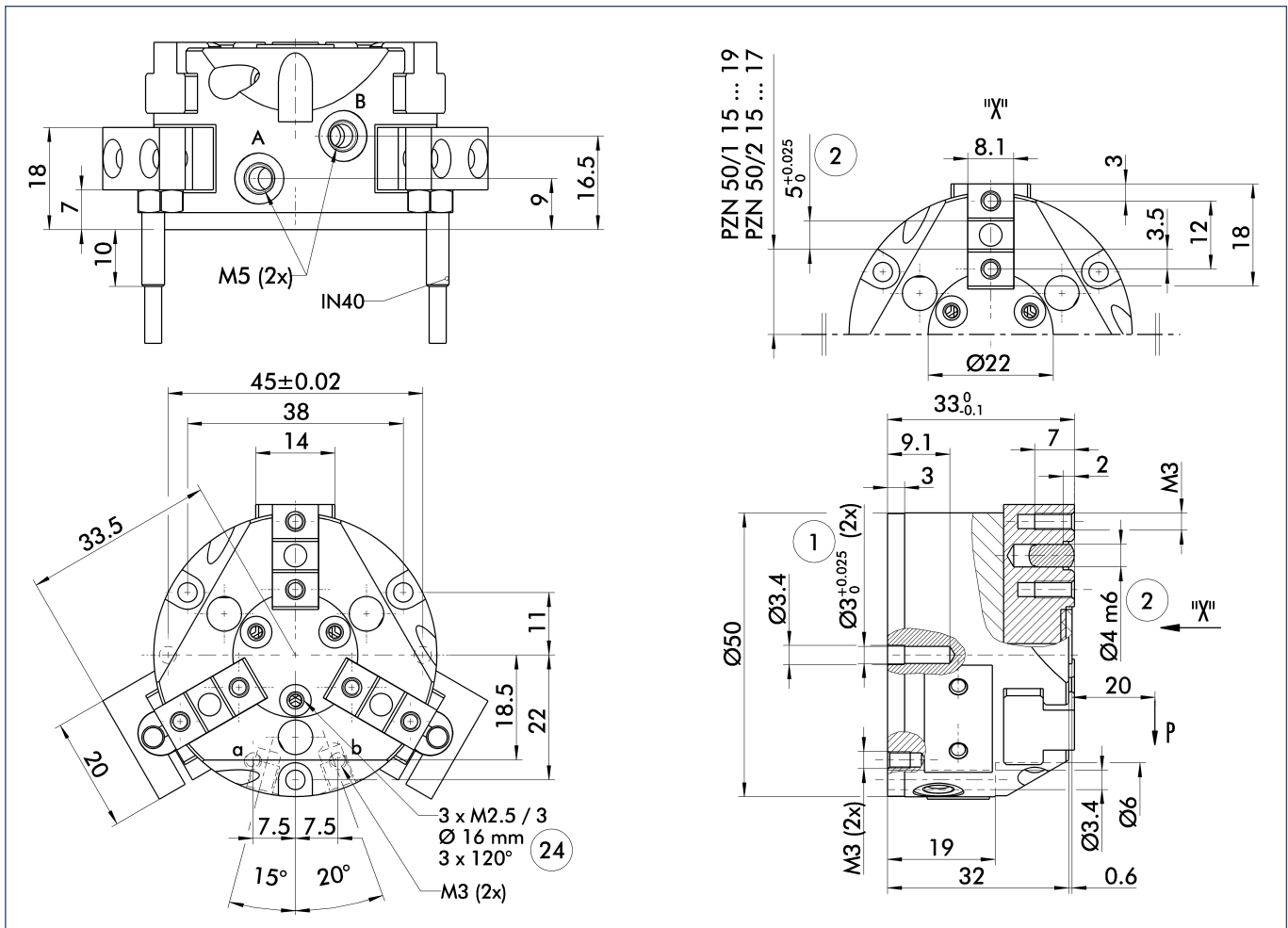


① Moments and forces apply per base jaw and may occur simultaneously.  $M_y$  may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. The tool life may be reduced.

## Technical data

Designation		PZN 50-1	PZN 50-2	PZN 50-1 AS	PZN 50-2 AS	PZN 50-1 IS	PZN 50-2 IS
	ID	0300309	0300409	0300509	0300609	0300539	0300639
Stroke per jaw	[mm]	4.0	2.0	4.0	2.0	4.0	2.0
Closing force	[N]	260.0	510.0	380.0	720.0		
Opening force	[N]	285.0	550.0			380.0	720.0
Min. spring force	[N]			90.0	170.0	90.0	170.0
Weight	[kg]	0.2	0.2	0.23	0.23	0.23	0.23
Recommended workpiece weight	[kg]	1.3	2.5	1.3	2.5	1.3	2.5
Air consumption per double stroke	[cm <sup>3</sup> ]	15.0	15.0	15.0	15.0	15.0	15.0
Minimum pressure	[bar]	2.0	2.0	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal operating pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.03	0.03	0.02	0.02	0.04	0.04
Opening time	[s]	0.03	0.03	0.04	0.04	0.02	0.02
Max. permitted finger length	[mm]	50.0	50.0	50.0	50.0	50.0	50.0
Max. permitted weight per finger	[kg]	0.15	0.15	0.15	0.15	0.15	0.15
IP class		40	40	40	40	40	40
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Max. ambient temperature	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01

### Main views

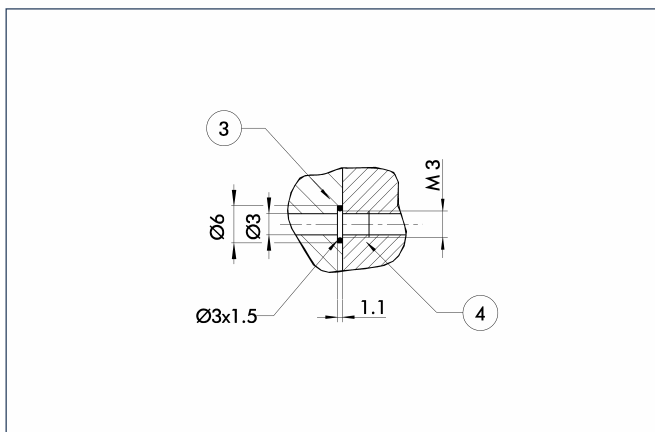


The illustration shows the gripper in the basic version with closed jaws, without taking into account the measurements of the optional extras described below.

- ① As an alternative to or in addition to the spring-mounted, mechanical gripping force safety device, the pressure maintenance valve SDV-P can also be used for I.D. or O.D. gripping (see the "Accessories" catalog section).

- A,a Main connection, direct connection – Open gripper  
 B,b Main connection, direct connection – Close gripper  
 ① Gripper connection  
 ② Finger connection  
 ②④ Screw pitch circle

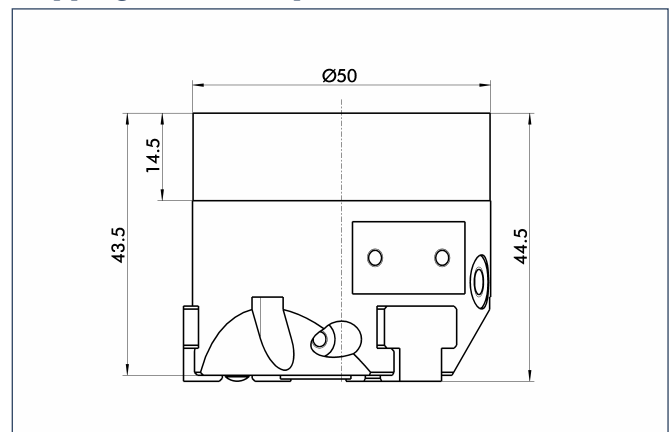
### Hose-free direct connection



- ③ Adapter  
 ④ Gripper

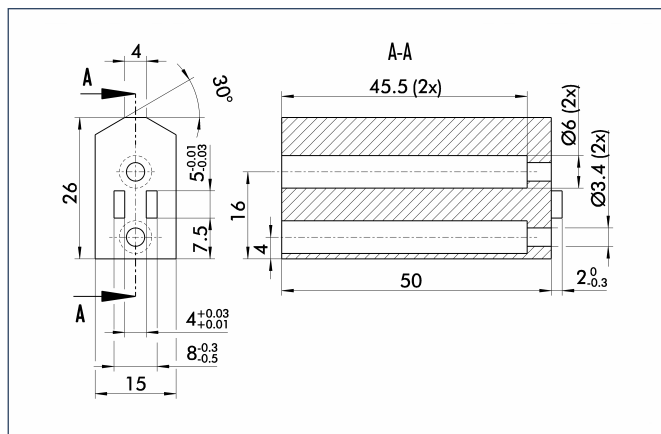
The direct connection supplies pressure to the gripper without a failure-prone hose system. Instead, the pressure medium is guided through holes in the mounting plate.

### Gripping force safety device AS/IS



The mechanical gripping force safety device ensures a minimum gripping force, even with a drop in pressure. This works as a closing force for the AS version; for the IS version it works as an opening force. In addition, the gripping force safety device can also be used to increase the grip force or for single actuated gripping.

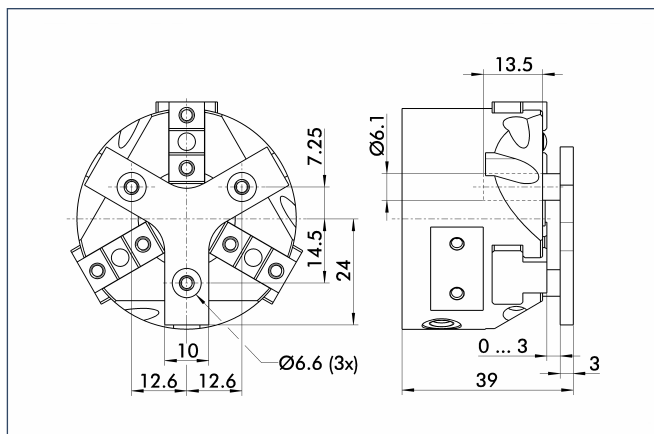
### Finger blanks



Finger blanks for customer-specific reworking, incl. screw connection diagram

Designation	Material	Scope of delivery	ID
ABR 50	Aluminum	1	0300714
SBR 50	1.6 MnCr 5	1	0300715

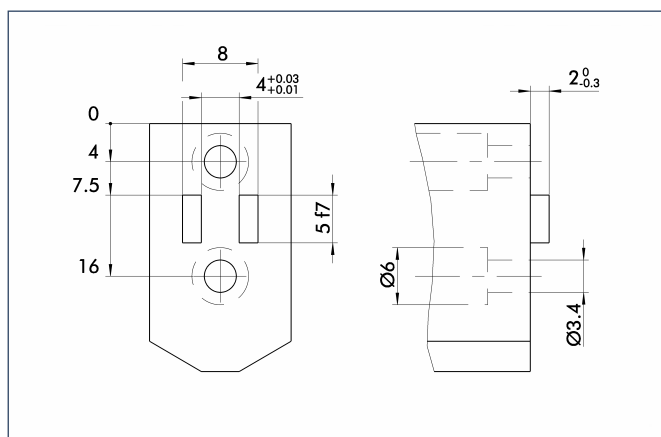
### Spring-loaded pressure plate



For spring-mounted positioning of the workpiece against the stop after the gripper has opened. Developed especially for the loading of machining centers.

Designation	Stroke	Min. total force	ID
A-PZN 50	3 mm	9 N	0300719

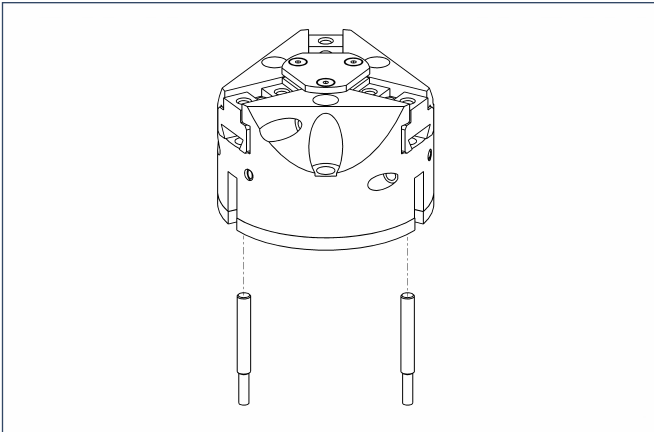
### Finger design



Suggestion for connection dimensions — Gripper fingers



### Sensor systems



- ① To be considered when using proximity switch IN 80 instead of IN 40  
The proximity switches can also be mounted using the brackets supplied but without using the eccentric sleeves. Please bear in mind that when using IN 80 instead of IN 40 sensors, the switch position is not adjustable.

#### End position monitoring:

##### Inductive proximity switches, for direct mounting

Designation	ID	Recommended product
IN 40/O-M12	0301584	
IN 40/O-M8	0301484	•
IN 40/S-M12	0301574	
IN 40/S-M8	0301474	•
IN 80/O-M12	0301588	
IN 80/O-M8	0301488	
IN 80/S-M12	0301578	
IN 80/S-M8	0301478	
INK 40/O	0301556	
INK 40/S	0301555	
INK 80/O	0301551	
INK 80/S	0301550	

- ① Two sensors are required per gripper; an NO contact (/S) and an NC contact (/O), as well as an optional extension cable.

#### Extension cables for proximity switches/magnetic switches

Designation	ID
GK 3-M8	0301622
KV 10-M12	0301596
KV 10-M8	0301496
KV 20-M12	0301597
KV 20-M8	0301497
KV 3-M12	0301595
KV 3-M8	0301495
W 3-M12	0301503
W 5-M12	0301507
WK 3-M8	0301594
WK 5-M8	0301502

- ① For the sensor cables, observe the minimum permitted bending radii. Generally, these are 35 mm.

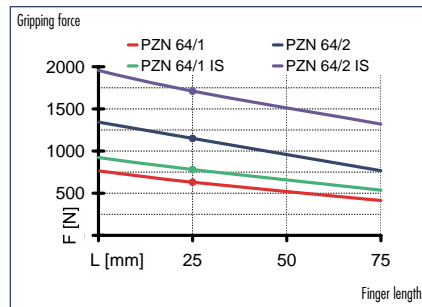


You can find detailed information and components of the specified accessory in the "Accessories" catalog section.

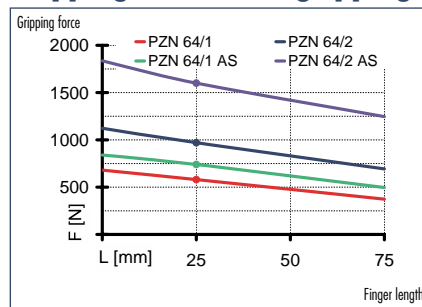




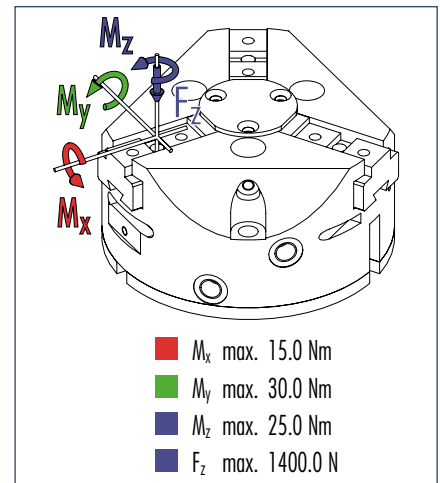
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping



### Finger load

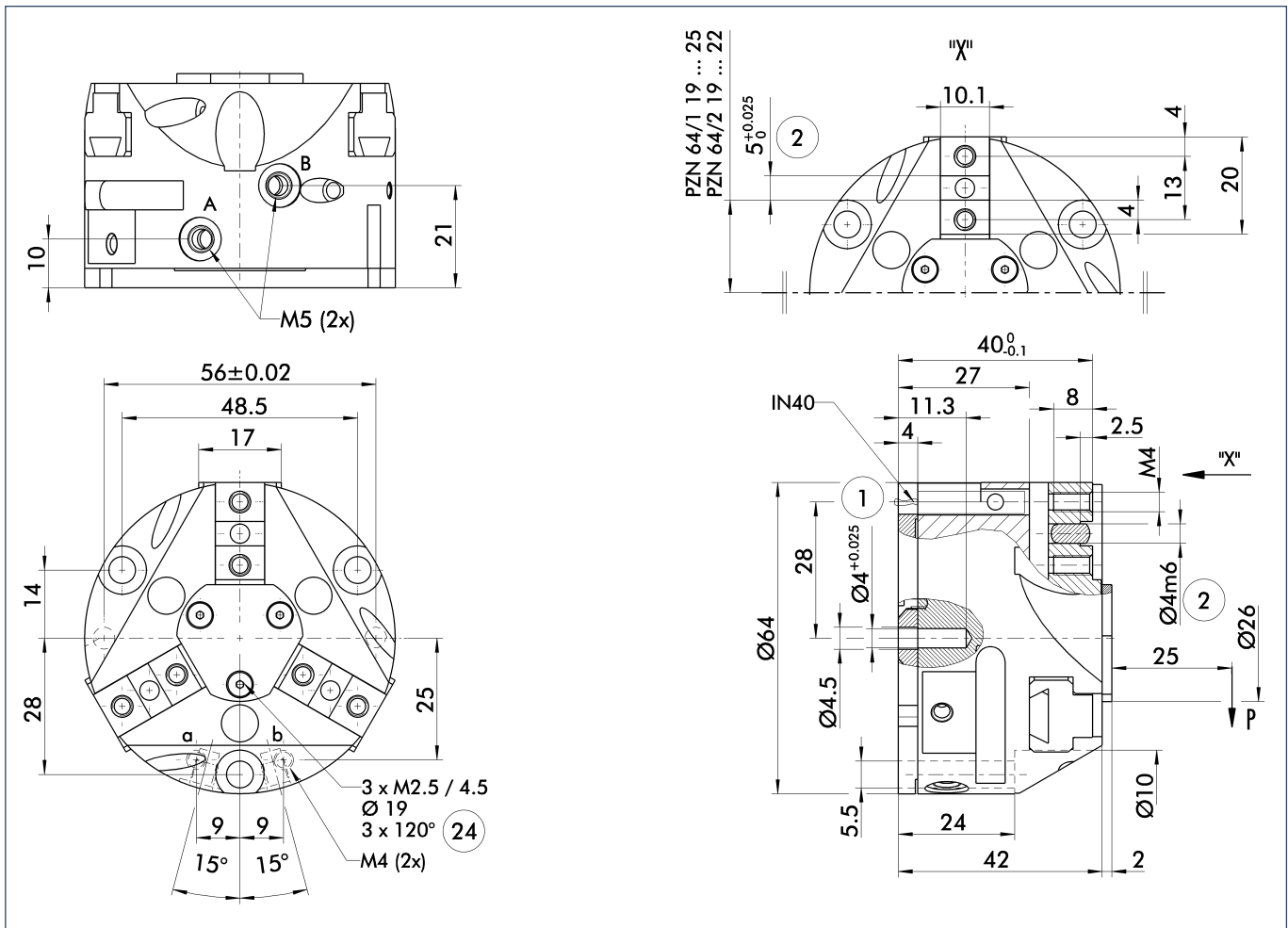


① Moments and forces apply per base jaw and may occur simultaneously.  $M_y$  may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. The tool life may be reduced.

### Technical data

Designation		PZN 64-1	PZN 64-2	PZN 64-1 AS	PZN 64-2 AS	PZN 64-1 IS	PZN 64-2 IS
	ID	0300310	0300410	0300510	0300610	0300540	0300640
Stroke per jaw	[mm]	6.0	3.0	6.0	3.0	6.0	3.0
Closing force	[N]	580.0	970.0	740.0	1600.0		
Opening force	[N]	630.0	1150.0			720.0	1500.0
Min. spring force	[N]			200.0	320.0	200.0	320.0
Weight	[kg]	0.4	0.4	0.57	0.57	0.65	0.65
Recommended workpiece weight	[kg]	3.0	5.0	3.0	5.0	3.0	5.0
Air consumption per double stroke	[cm <sup>3</sup> ]	25.0	25.0	25.0	25.0	25.0	25.0
Minimum pressure	[bar]	2.0	2.0	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal operating pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.01	0.01	0.03	0.03	0.04	0.04
Opening time	[s]	0.01	0.01	0.04	0.04	0.03	0.03
Max. permitted finger length	[mm]	64.0	64.0	64.0	64.0	64.0	64.0
Max. permitted weight per finger	[kg]	0.3	0.3	0.3	0.3	0.3	0.3
IP class		40	40	40	40	40	40
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Max. ambient temperature	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01

### Main views

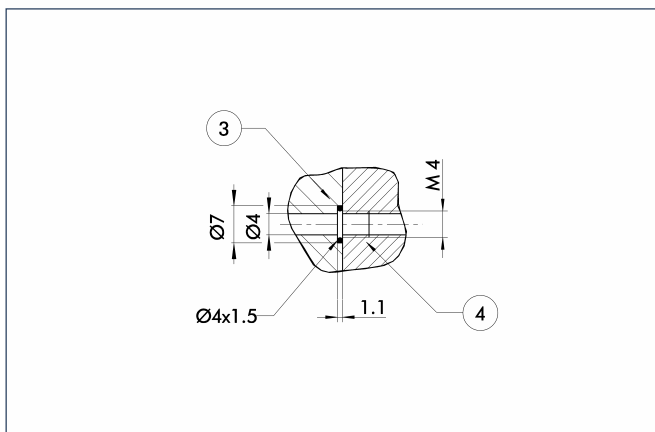


The illustration shows the gripper in the basic version with closed jaws, without taking into account the measurements of the optional extras described below.

- ① As an alternative to or in addition to the spring-mounted, mechanical gripping force safety device, the pressure maintenance valve SDV-P can also be used for I.D. or O.D. gripping (see the "Accessories" catalog section).

- A,a Main connection, direct connection – Open gripper  
 B,b Main connection, direct connection – Close gripper  
 ① Gripper connection  
 ② Finger connection  
 ②④ Screw pitch circle

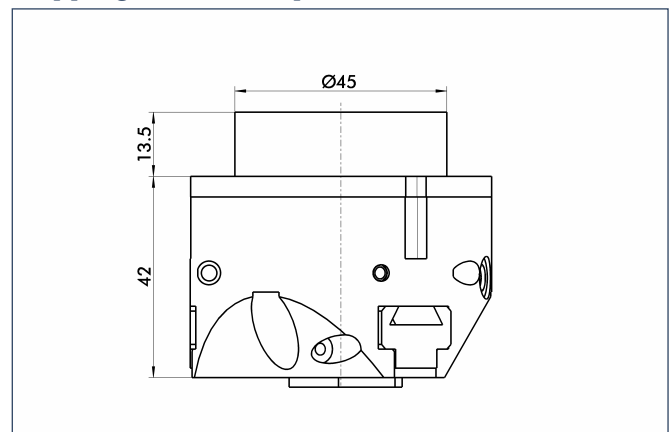
### Hose-free direct connection



- ③ Adapter  
 ④ Gripper

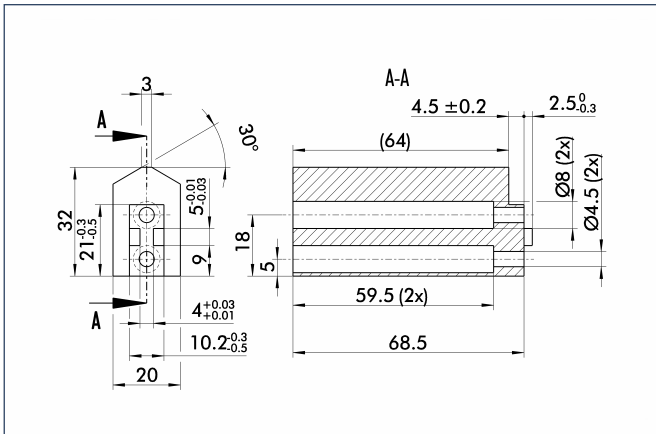
The direct connection supplies pressure to the gripper without a failure-prone hose system. Instead, the pressure medium is guided through holes in the mounting plate.

### Gripping force safety device AS/IS



The mechanical gripping force safety device ensures a minimum gripping force, even with a drop in pressure. This works as a closing force for the AS version; for the IS version it works as an opening force. In addition, the gripping force safety device can also be used to increase the grip force or for single actuated gripping.

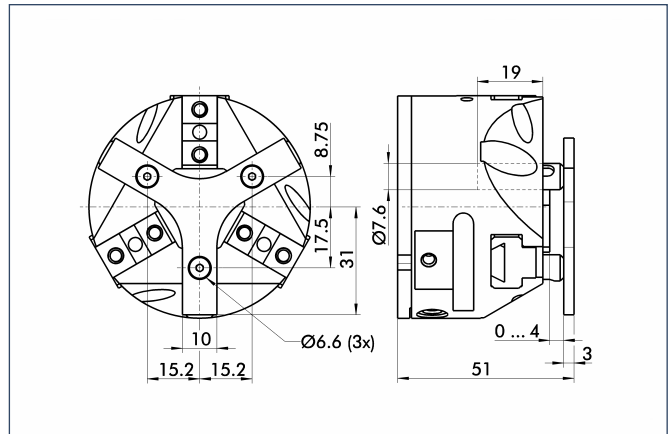
### Finger blanks



Finger blanks for customer-specific reworking, incl. screw connection diagram

Designation	Material	Scope of delivery	ID
ABR 64	Aluminum	1	0300725
SBR 64	16 MnCr 5	1	0300734

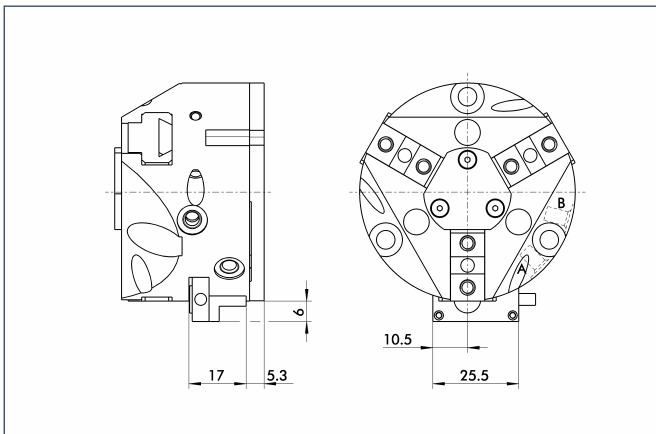
### Spring-loaded pressure plate



For spring-mounted positioning of the workpiece against the stop after the gripper has opened. Developed especially for the loading of machining centers.

Designation	Stroke	Min. total force	ID
A-PZN 64	4 mm	18 N	0300720

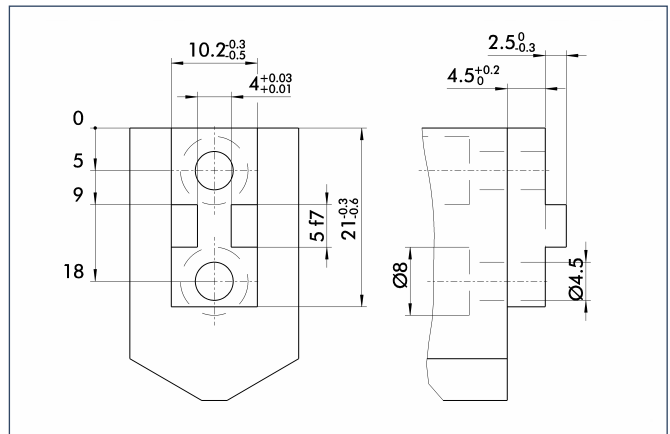
### Mounting kit for FPS



The flexible position sensor FPS can distinguish between five freely programmable areas or switching points for the stroke of a gripper and can be used in conjunction with a PC as a measuring system.

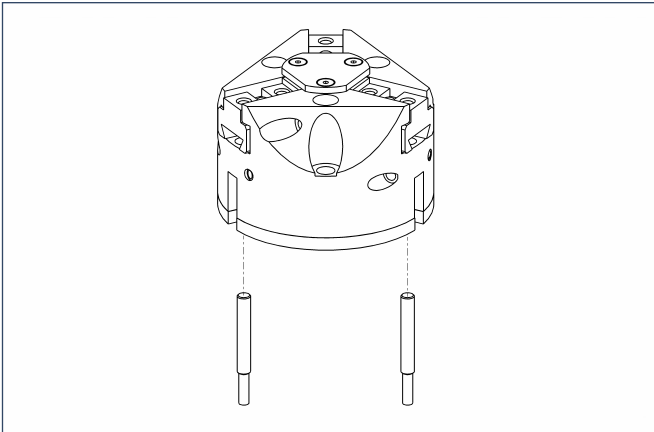
Designation	ID
AS-PZN 64	0301712

### Finger design



Suggestion for connection dimensions – Gripper fingers

### Sensor systems

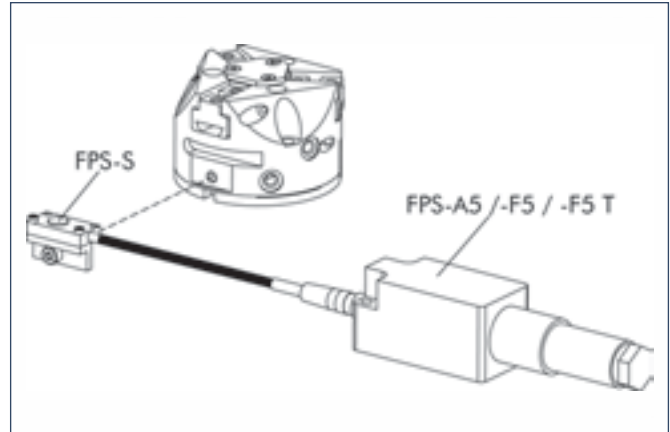


#### End position monitoring:

Inductive proximity switches, for direct mounting

Designation	ID	Recommended product
IN 40/S-M12	0301574	
IN 40/S-M8	0301474	•
INK 40/S	0301555	

- ① Two sensors (NO contacts/S) are required per gripper as well as an optional extension cable.



#### Measuring system:

Position monitoring FPS

Designation	ID
AS-PZN 64	0301712
FPS-A5	0301802
FPS-F5	0301805
FPS-F5 T	0301807
FPS-S 13	0301705

When using an FPS system, an FPS sensor (FPS-S) and an electronic processor (FPS-F5/ F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as optional extras in the "Accessories" catalog section.

#### Extension cables for proximity switches/magnetic switches

Designation	ID
GK 3-M8	0301622
KV 10-M12	0301596
KV 10-M8	0301496
KV 20-M12	0301597
KV 20-M8	0301497
KV 3-M12	0301595
KV 3-M8	0301495
W 3-M12	0301503
W 5-M12	0301507
WK 3-M8	0301594
WK 5-M8	0301502

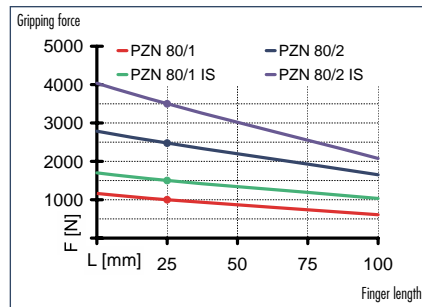
- ① For the sensor cables, observe the minimum permitted bending radii. Generally, these are 35 mm.



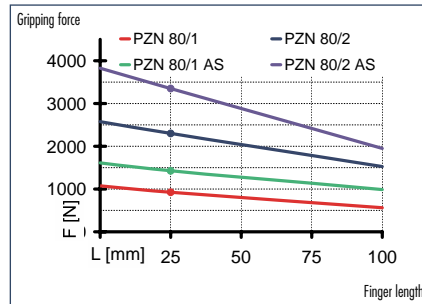
You can find detailed information and components of the specified accessory in the "Accessories" catalog section.



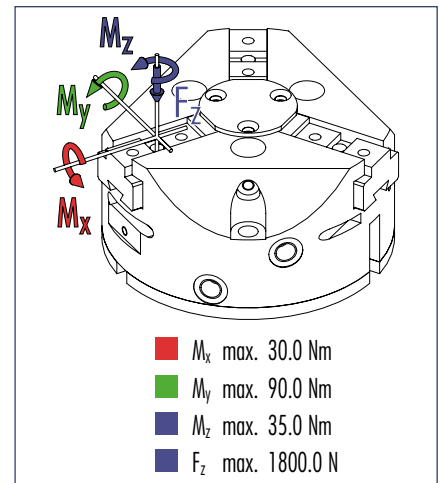
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping



### Finger load

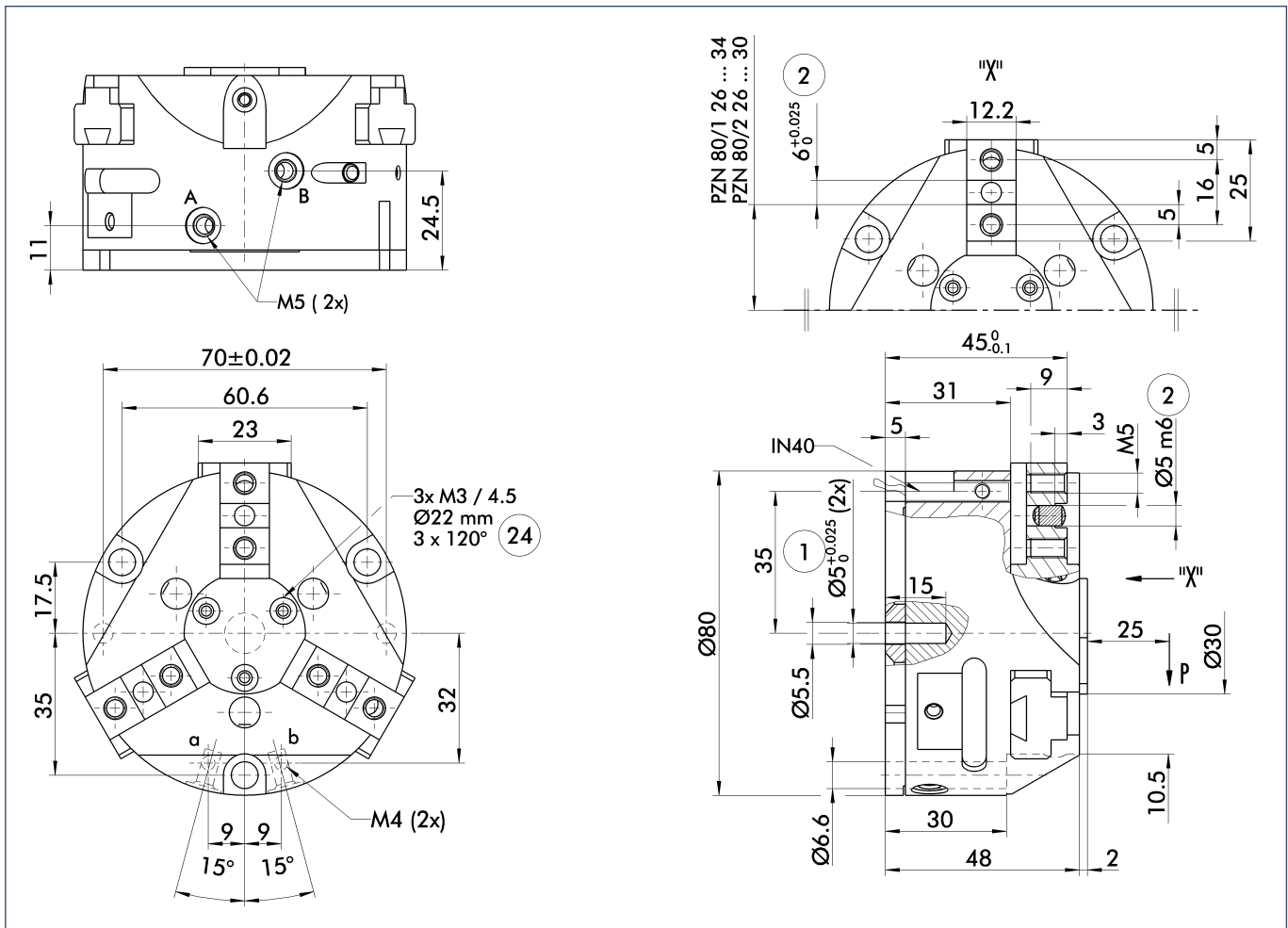


① Moments and forces apply per base jaw and may occur simultaneously.  $M_y$  may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. The tool life may be reduced.

## Technical data

Designation		PZN 80-1	PZN 80-2	PZN 80-1 AS	PZN 80-2 AS	PZN 80-1 IS	PZN 80-2 IS
	ID	0300311	0300411	0300511	0300611	0300541	0300641
Stroke per jaw	[mm]	8.0	4.0	8.0	4.0	8.0	4.0
Closing force	[N]	925.0	2300.0	1600.0	3400.0		
Opening force	[N]	1000.0	2470.0			1650.0	3500.0
Min. spring force	[N]			330.0	770.0	330.0	770.0
Weight	[kg]	0.75	0.75	0.95	0.95	1.05	1.05
Recommended workpiece weight	[kg]	4.6	11.5	4.6	11.5	4.6	11.5
Air consumption per double stroke	[cm <sup>3</sup> ]	60.0	60.0	60.0	60.0	60.0	60.0
Minimum pressure	[bar]	2.0	2.0	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal operating pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.06	0.06	0.05	0.05	0.08	0.08
Opening time	[s]	0.05	0.05	0.08	0.08	0.05	0.05
Max. permitted finger length	[mm]	80.0	80.0	80.0	80.0	80.0	80.0
Max. permitted weight per finger	[kg]	0.5	0.5	0.5	0.5	0.5	0.5
IP class		40	40	40	40	40	40
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Max. ambient temperature	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01

### Main views

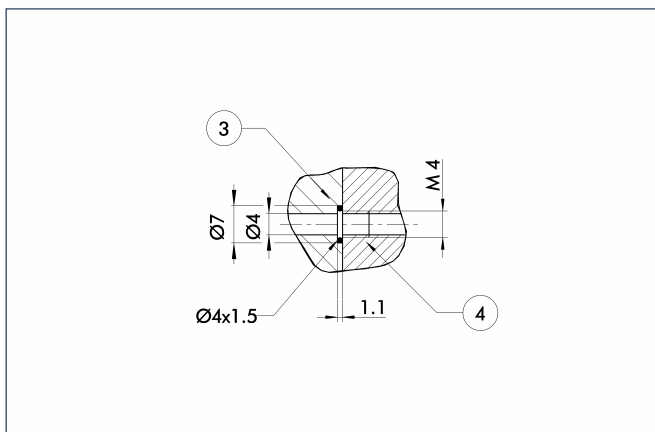


The illustration shows the gripper in the basic version with closed jaws, without taking into account the measurements of the optional extras described below.

- ① As an alternative to or in addition to the spring-mounted, mechanical gripping force safety device, the pressure maintenance valve SDV-P can also be used for I.D. or O.D. gripping (see the "Accessories" catalog section).

- A,a Main connection, direct connection – Open gripper
- B,b Main connection, direct connection – Close gripper
- ① Gripper connection
- ② Finger connection
- ②④ Screw pitch circle

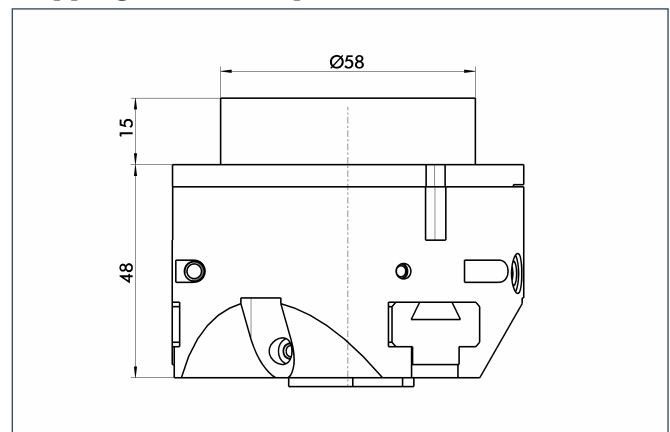
### Hose-free direct connection



- ③ Adapter
- ④ Gripper

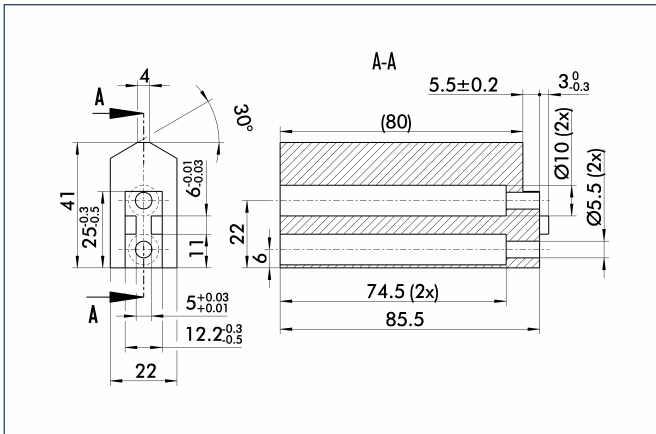
The direct connection supplies pressure to the gripper without a failure-prone hose system. Instead, the pressure medium is guided through holes in the mounting plate.

### Gripping force safety device AS/IS



The mechanical gripping force safety device ensures a minimum gripping force, even with a drop in pressure. This works as a closing force for the AS version; for the IS version it works as an opening force. In addition, the gripping force safety device can also be used to increase the grip force or for single actuated gripping.

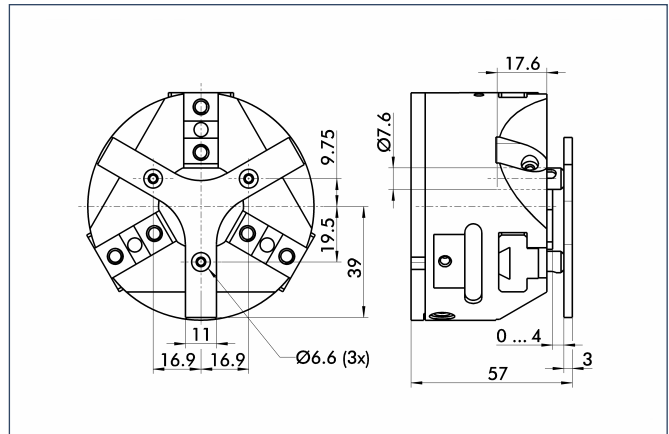
### Finger blanks



Finger blanks for customer-specific reworking, incl. screw connection diagram

Designation	Material	Scope of delivery	ID
ABR 80	Aluminum	1	0300726
SBR 80	16 MnCr 5	1	0300735

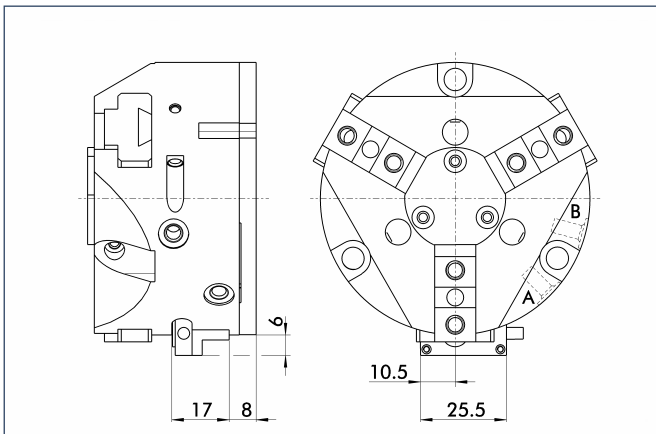
### Spring-loaded pressure plate



For spring-mounted positioning of the workpiece against the stop after the gripper has opened. Developed especially for the loading of machining centers.

Designation	Stroke	Min. total force	ID
A-PZN 80	4 mm	17 N	0300721

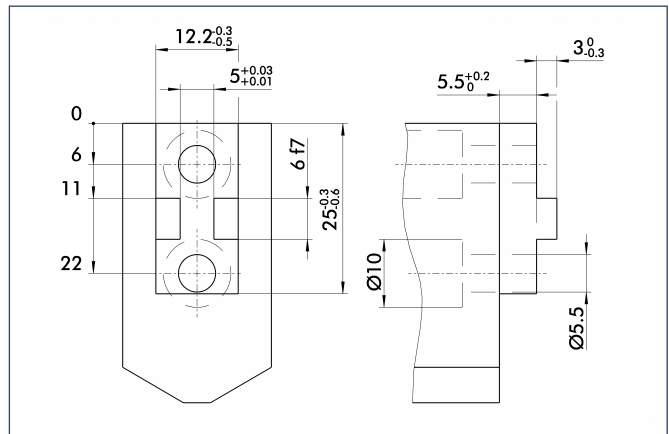
### Mounting kit for FPS



The flexible position sensor FPS can distinguish between five freely programmable areas or switching points for the stroke of a gripper and can be used in conjunction with a PC as a measuring system.

Designation	ID
AS-PZN 80-100	0301713

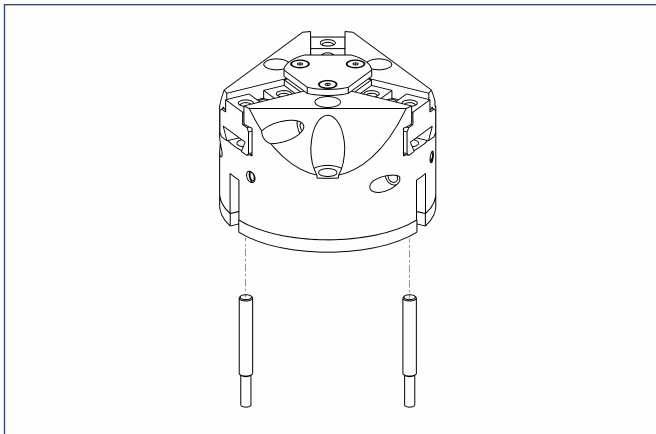
### Finger design



Suggestion for connection dimensions – Gripper fingers



### Sensor systems

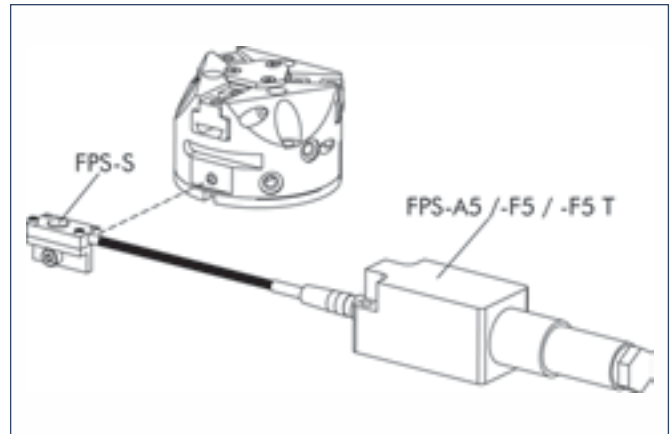


#### End position monitoring:

Inductive proximity switches, for direct mounting

Designation	ID	Recommended product
IN 40/S-M12	0301574	
IN 40/S-M8	0301474	•
INK 40/S	0301555	

- ① Two sensors (NO contacts/S) are required per gripper as well as an optional extension cable.



#### Measuring system:

Position monitoring FPS

Designation	ID
AS-PZN 80-100	0301713
FPS-A5	0301802
FPS-F5	0301805
FPS-F5 T	0301807
FPS-S 13	0301705

When using an FPS system, an FPS sensor (FPS-S) and an electronic processor (FPS-F5/ F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as optional extras in the "Accessories" catalog section.

### Extension cables for proximity switches/magnetic switches

Designation	ID
GK 3-M8	0301622
KV 10-M12	0301596
KV 10-M8	0301496
KV 20-M12	0301597
KV 20-M8	0301497
KV 3-M12	0301595
KV 3-M8	0301495
W 3-M12	0301503
W 5-M12	0301507
WK 3-M8	0301594
WK 5-M8	0301502

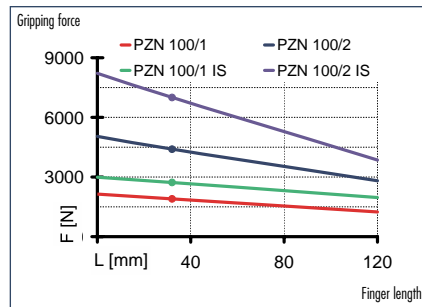
- ① For the sensor cables, observe the minimum permitted bending radii. Generally, these are 35 mm.



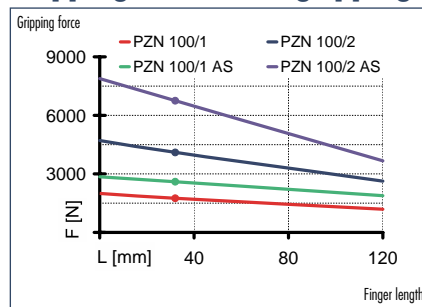
You can find detailed information and components of the specified accessory in the "Accessories" catalog section.



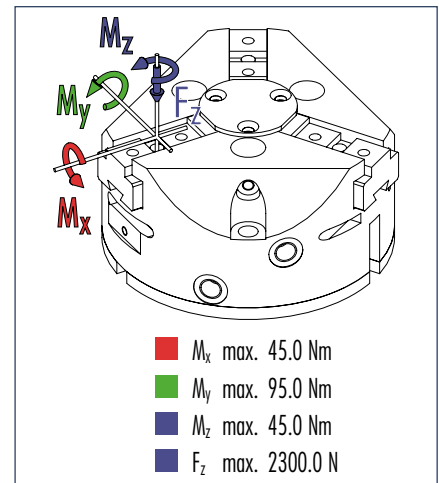
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping



### Finger load

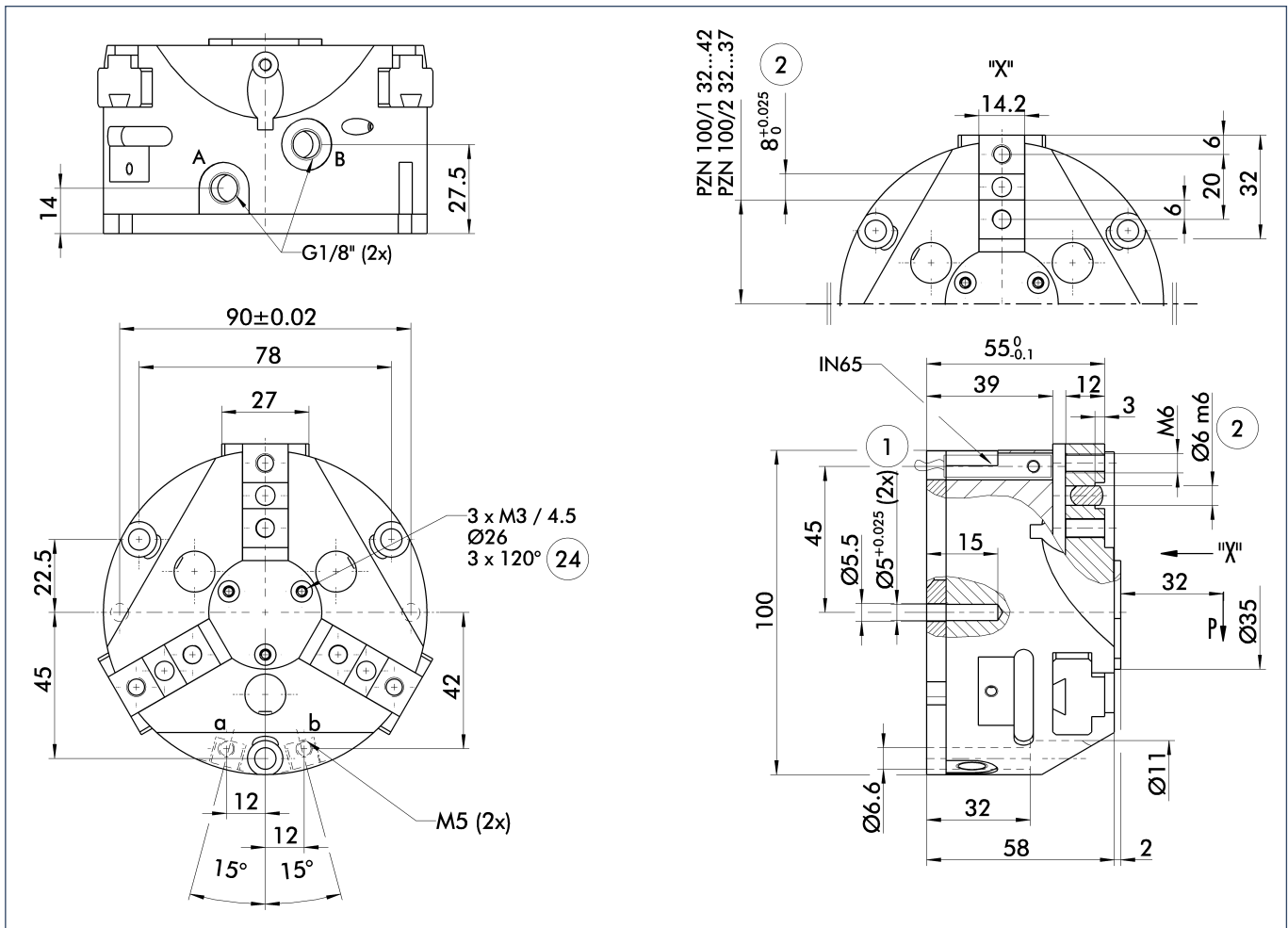


① Moments and forces apply per base jaw and may occur simultaneously.  $M_y$  may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. The tool life may be reduced.

## Technical data

Designation		PZN 100-1	PZN 100-2	PZN 100-1 AS	PZN 100-2 AS	PZN 100-1 IS	PZN 100-2 IS
	ID	0300312	0300412	0300512	0300612	0300542	0300642
Stroke per jaw	[mm]	10.0	5.0	10.0	5.0	10.0	5.0
Closing force	[N]	1800.0	4000.0	2650.0	6500.0		
Opening force	[N]	1900.0	4400.0			2500.0	6000.0
Min. spring force	[N]			600.0	1350.0	600.0	1350.0
Weight	[kg]	1.35	1.35	1.9	1.9	2.1	2.1
Recommended workpiece weight	[kg]	9.0	20.0	9.0	20.0	9.0	20.0
Air consumption per double stroke	[cm <sup>3</sup> ]	120.0	120.0	120.0	120.0	120.0	120.0
Minimum pressure	[bar]	2.0	2.0	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal operating pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.08	0.08	0.1	0.1	0.18	0.18
Opening time	[s]	0.07	0.07	0.18	0.18	0.1	0.1
Max. permitted finger length	[mm]	100.0	100.0	100.0	100.0	100.0	100.0
Max. permitted weight per finger	[kg]	0.95	0.95	0.95	0.95	0.95	0.95
IP class		40	40	40	40	40	40
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Max. ambient temperature	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01

### Main views

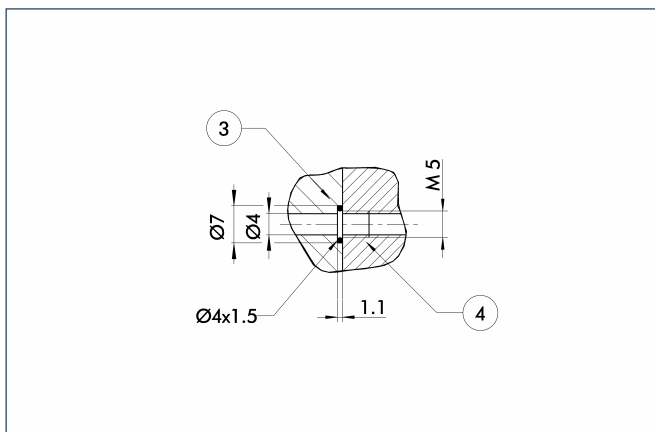


The illustration shows the gripper in the basic version with closed jaws, without taking into account the measurements of the optional extras described below.

- ① As an alternative to or in addition to the spring-mounted, mechanical gripping force safety device, the pressure maintenance valve SDV-P can also be used for I.D. or O.D. gripping (see the "Accessories" catalog section).

- A,a Main connection, direct connection – Open gripper  
 B,b Main connection, direct connection – Close gripper  
 ① Gripper connection  
 ② Finger connection  
 ②④ Screw pitch circle

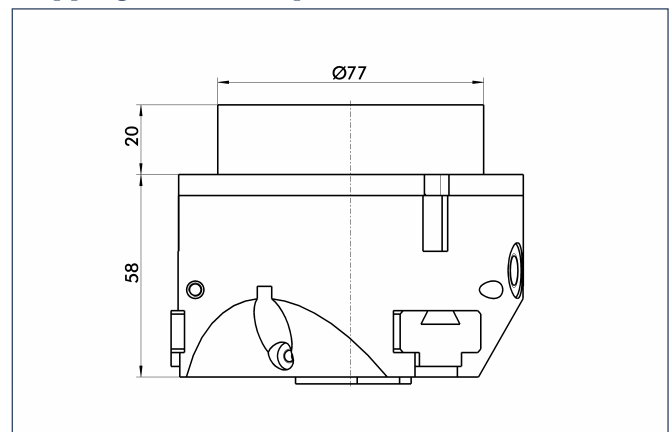
### Hose-free direct connection



- ③ Adapter  
 ④ Gripper

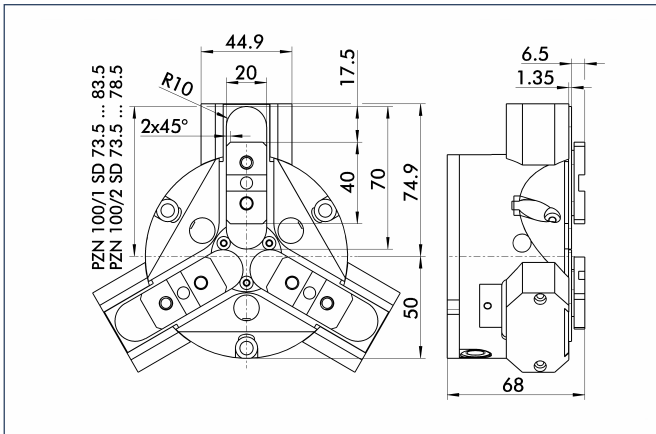
The direct connection supplies pressure to the gripper without a failure-prone hose system. Instead, the pressure medium is guided through holes in the mounting plate.

### Gripping force safety device AS/IS



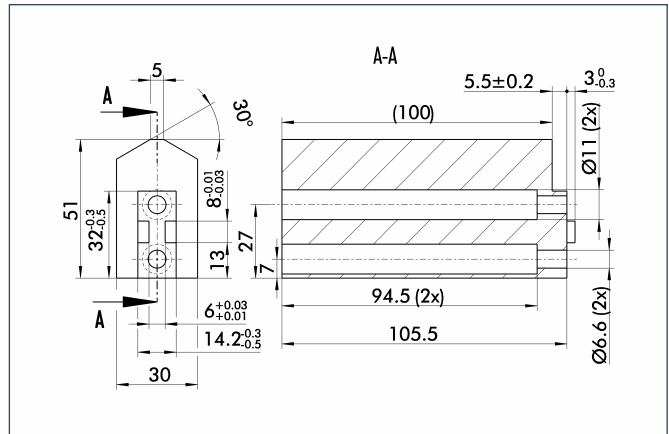
The mechanical gripping force safety device ensures a minimum gripping force, even with a drop in pressure. This works as a closing force for the AS version; for the IS version it works as an opening force. In addition, the gripping force safety device can also be used to increase the grip force or for single actuated gripping.

### Dust protection



The "Dust-proof" option increases the degree of protection against penetrating substances. The screw connection diagram moves by the height of the intermediate jaw. The finger length must still be measured from the upper edge of the gripper housing.

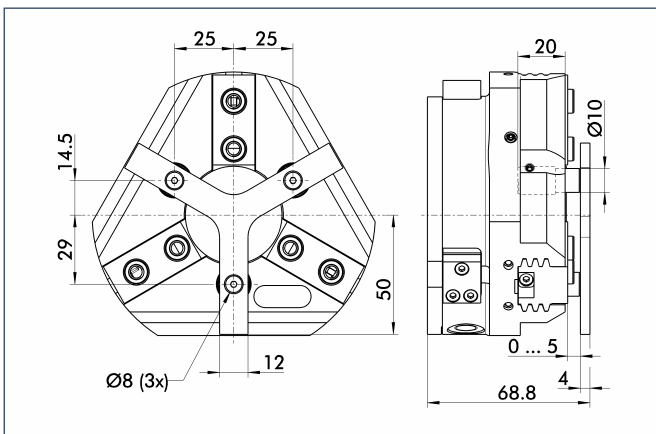
### Finger blanks



Finger blanks for customer-specific reworking, incl. screw connection diagram

Designation	Material	Scope of delivery	ID
ABR 100	Aluminum	1	0300727
SBR 100	16 MnCr 5	1	0300736

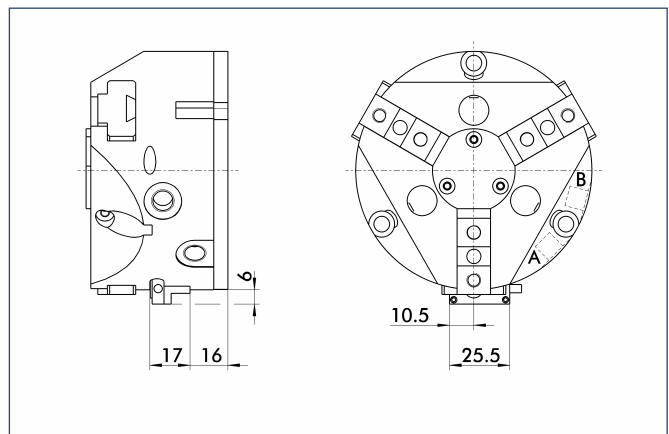
### Spring-loaded pressure plate



For spring-mounted positioning of the workpiece against the stop after the gripper has opened. Developed especially for the loading of machining centers.

Designation	Stroke	Min. total force	ID
A-PZN 100	5 mm	35 N	0300722

### Mounting kit for FPS



The flexible position sensor FPS can distinguish between five freely programmable areas or switching points for the stroke of a gripper and can be used in conjunction with a PC as a measuring system.

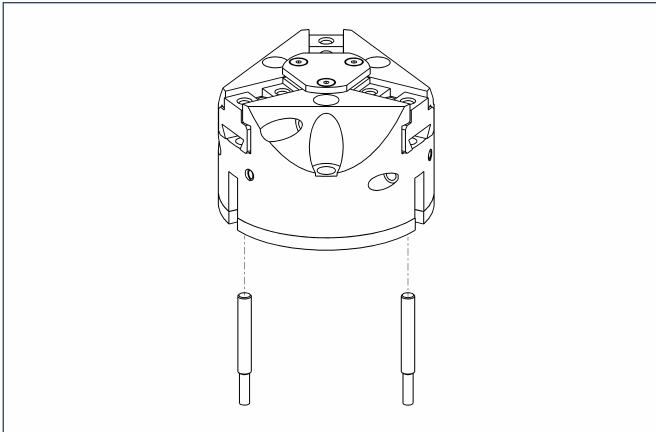
Designation	ID
AS-PZN 80-100	0301713



You can find detailed information and components of the specified accessory in the "Accessories" catalog section.



### Sensor systems

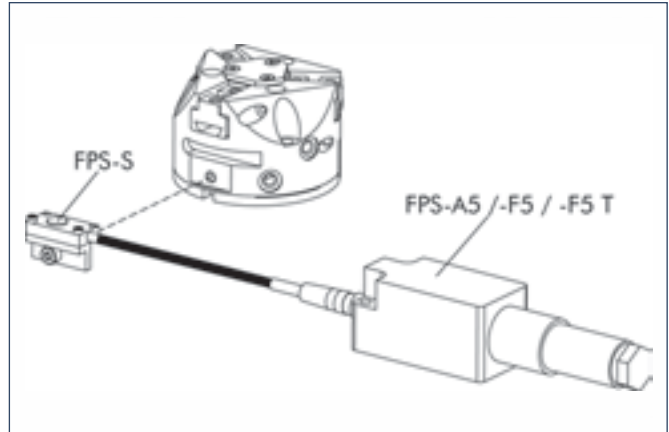


#### End position monitoring:

Inductive proximity switches, for direct mounting

Designation	ID	Recommended product
IN 65/S-M12	0301576	
IN 65/S-M8	0301476	•
INK 65/S	0301554	

- ① Two sensors (NO contacts/S) are required per gripper as well as an optional extension cable.



#### Measuring system:

Position monitoring FPS

Designation	ID
AS-PZN 80-100	0301713
FPS-A5	0301802
FPS-F5	0301805
FPS-F5 T	0301807
FPS-S 13	0301705

When using an FPS system, an FPS sensor (FPS-S) and an electronic processor (FPS-F5/ F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as optional extras in the "Accessories" catalog section.

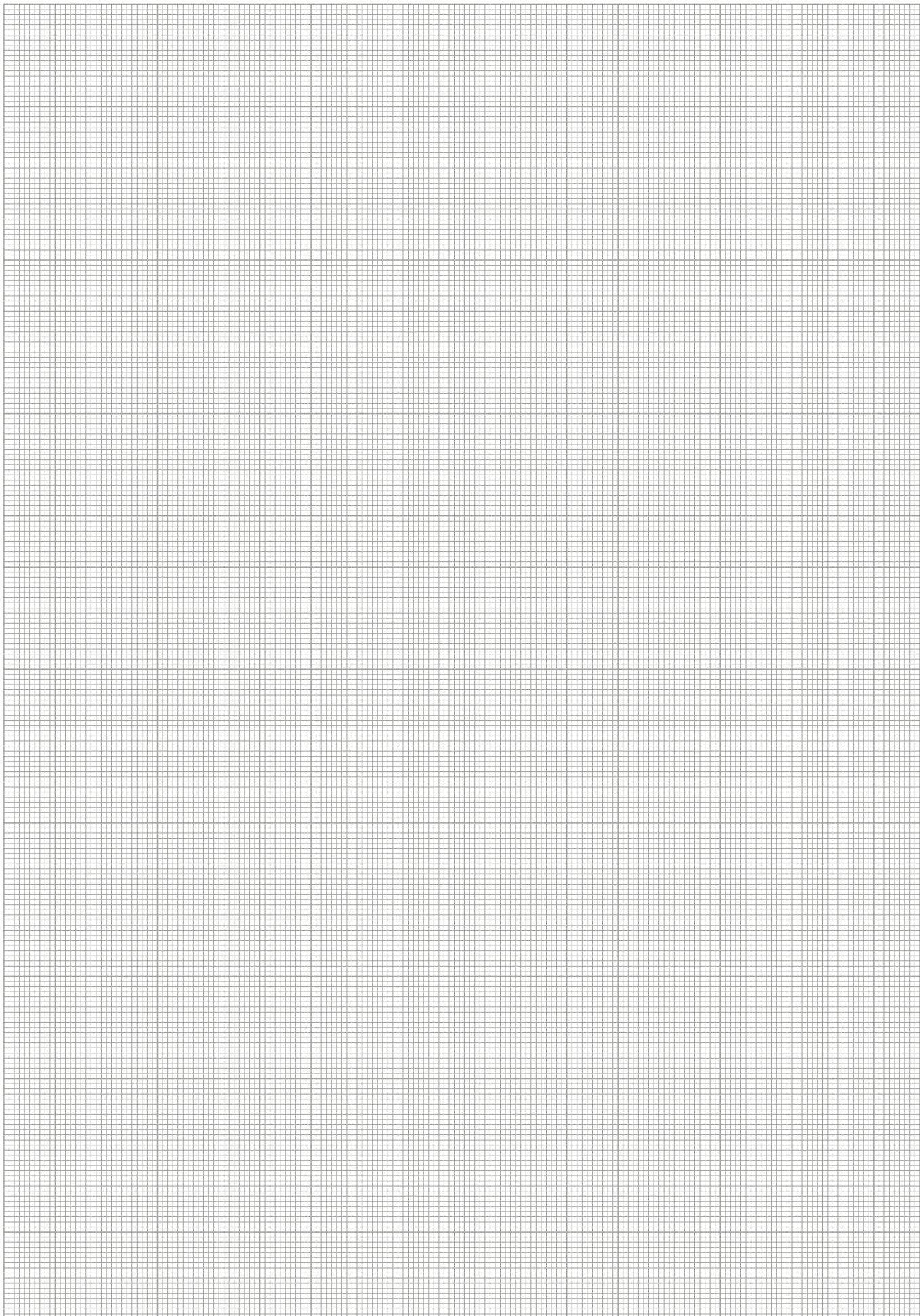
#### Extension cables for proximity switches/magnetic switches

Designation	ID
GK 3-M8	0301622
KV 10-M12	0301596
KV 10-M8	0301496
KV 20-M12	0301597
KV 20-M8	0301497
KV 3-M12	0301595
KV 3-M8	0301495
W 3-M12	0301503
W 5-M12	0301507
WK 3-M8	0301594
WK 5-M8	0301502

- ① For the sensor cables, observe the minimum permitted bending radii. Generally, these are 35 mm.



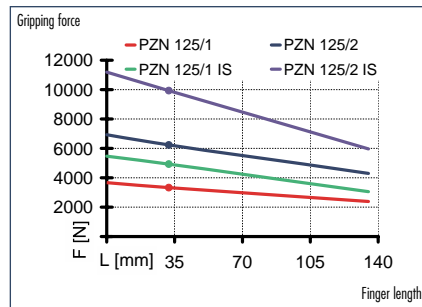
You can find detailed information and components of the specified accessory in the "Accessories" catalog section.



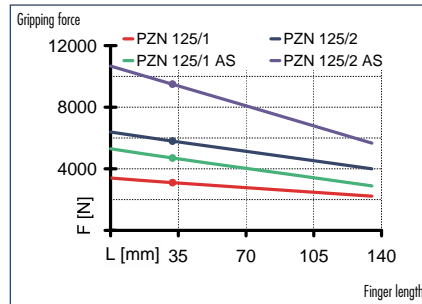




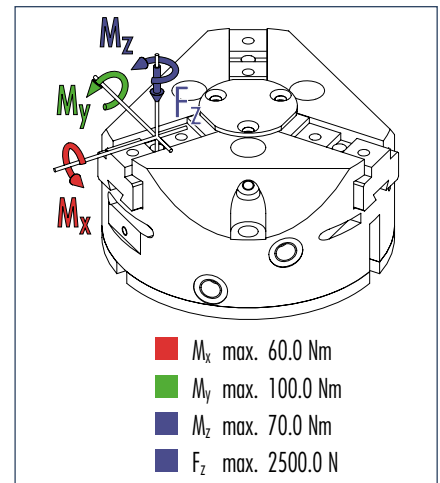
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping



### Finger load



① Moments and forces apply per base jaw and may occur simultaneously.  $M_y$  may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. The tool life may be reduced.

## Technical data

Designation		PZN 125-1	PZN 125-2	PZN 125-1 AS	PZN 125-2 AS	PZN 125-1 IS	PZN 125-2 IS
	ID	0300313	0300413	0300513	0300613	0300543	0300643
Stroke per jaw	[mm]	13.0	6.0	13.0	6.0	13.0	6.0
Closing force	[N]	3100.0	5800.0	4700.0	9500.0		
Opening force	[N]	3330.0	6230.0			4800.0	9700.0
Min. spring force	[N]			1050.0	1950.0	1050.0	1950.0
Weight	[kg]	2.35	2.35	3.4	3.4	3.7	3.7
Recommended workpiece weight	[kg]	15.5	29.0	15.5	29.0	15.5	29.0
Air consumption per double stroke	[cm <sup>3</sup> ]	230.0	230.0	230.0	230.0	230.0	230.0
Minimum pressure	[bar]	2.0	2.0	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal operating pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.17	0.17	0.15	0.15	0.32	0.32
Opening time	[s]	0.17	0.17	0.32	0.32	0.15	0.15
Max. permitted finger length	[mm]	125.0	125.0	125.0	125.0	125.0	125.0
Max. permitted weight per finger	[kg]	1.75	1.75	1.75	1.75	1.75	1.75
IP class		40	40	40	40	40	40
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Max. ambient temperature	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.02	0.02	0.02	0.02	0.02	0.02

[illegible]

A,a Main connection, direct connection – Open gripper  
B,b Main connection, direct connection – Close gripper  
① Gripper connection  
② Finger connection  
②4 Screw pitch circle

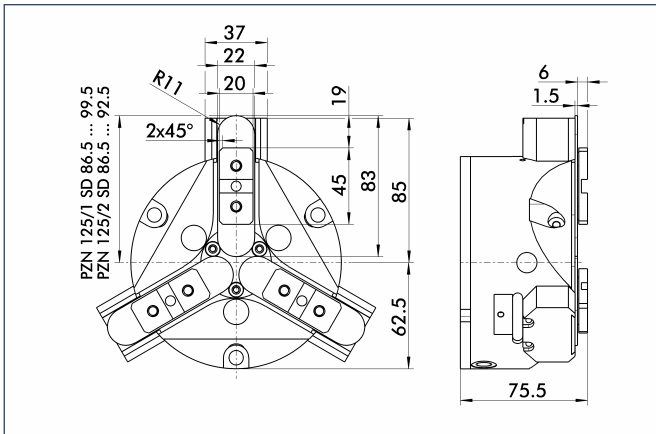
Technical drawing of a mechanical part, likely a cross-section of a shaft or a similar component. The drawing includes the following dimensions and callouts:

- Callout 3:** Points to a vertical feature on the left side of the part.
- Callout 4:** Points to a horizontal feature on the right side of the part.
- Dimensions:**
  - $\varnothing 7$  and  $\varnothing 4$  indicate diameters.
  - $M 5$  indicates a thread specification.
  - $1.1$  indicates a length or distance.
  - $\varnothing 4 \times 1.5$  indicates a hole or feature with a diameter of 4 and a length of 1.5.

- 

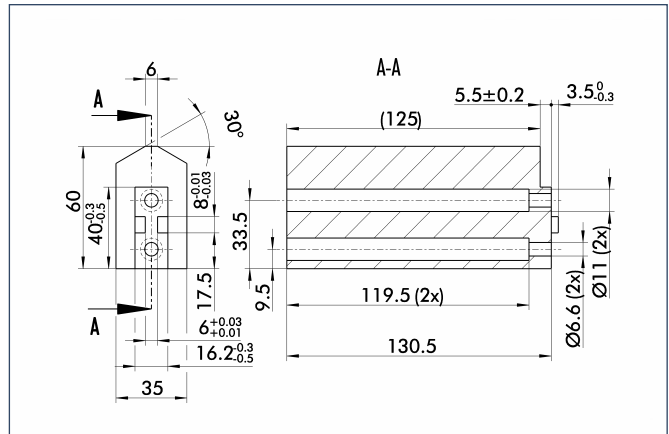
The mechanical gripping force safety device ensures a minimum gripping force, even with a drop in pressure. This works as a closing force for the AS version; for the IS version it works as an opening force. In addition, the gripping force safety device can also be used to increase the grip force or for single actuated gripping.

### Dust protection



The "Dust-proof" option increases the degree of protection against penetrating substances. The screw connection diagram moves by the height of the intermediate jaw. The finger length must still be measured from the upper edge of the gripper housing.

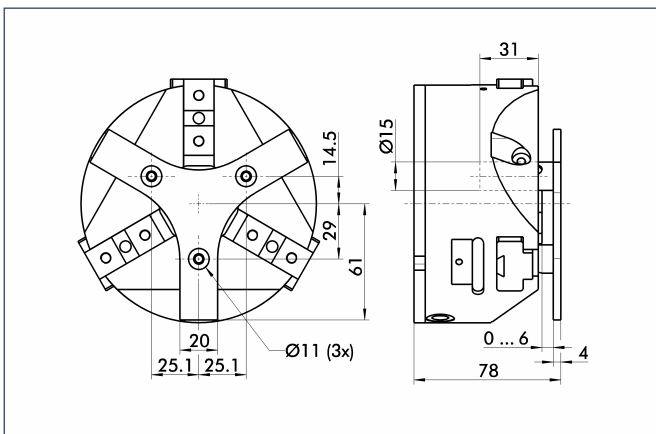
### Finger blanks



Finger blanks for customer-specific reworking, incl. screw connection diagram

Designation	Material	Scope of delivery	ID
ABR 125	Aluminum	1	0300728
SBR 125	16 MnCr 5	1	0300737

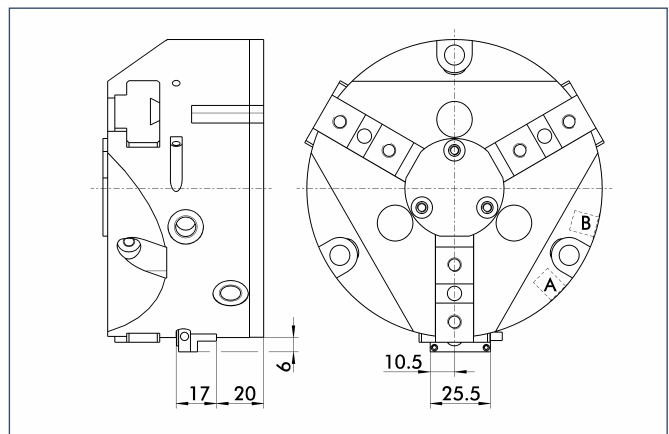
### Spring-loaded pressure plate



For spring-mounted positioning of the workpiece against the stop after the gripper has opened. Developed especially for the loading of machining centers.

Designation	Stroke	Min. total force	ID
A-PZN 125	6 mm	130 N	0300723

### Mounting kit for FPS



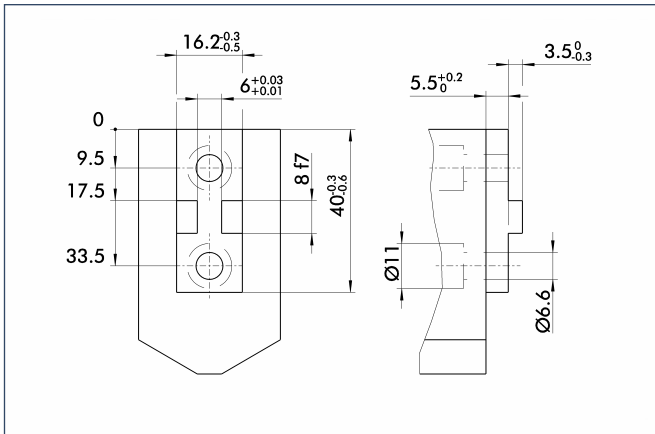
The flexible position sensor FPS can distinguish between five freely programmable areas or switching points for the stroke of a gripper and can be used in conjunction with a PC as a measuring system.

Designation	ID
AS-PZN 125-160	0301714



You can find detailed information and components of the specified accessory in the "Accessories" catalog section.

### Finger design

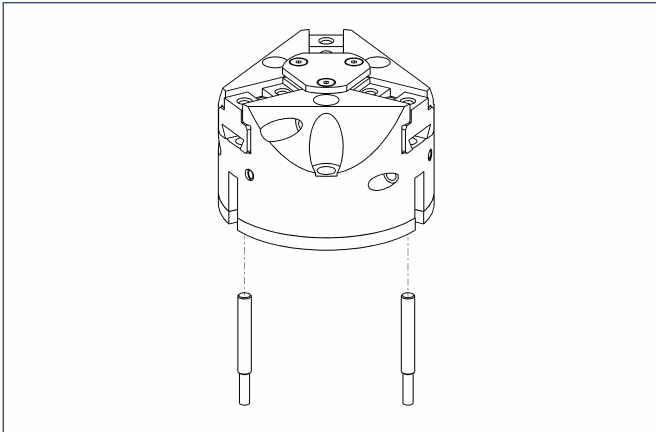


Suggestion for connection dimensions — Gripper fingers



You can find detailed information and components of the specified accessory in the "Accessories" catalog section.

### Sensor systems

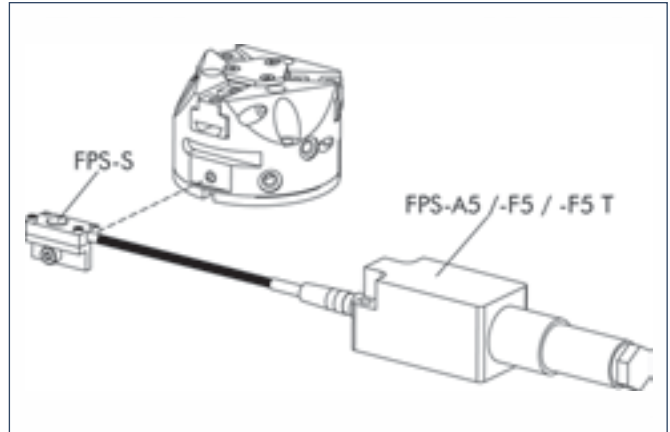


#### End position monitoring:

Inductive proximity switches, for direct mounting

Designation	ID	Recommended product
IN 80/S-M12	0301578	
IN 80/S-M8	0301478	•
INK 80/S	0301550	

- ① Two sensors (NO contacts/S) are required per gripper as well as an optional extension cable.



#### Measuring system:

Position monitoring FPS

Designation	ID
AS-PZN 125-160	0301714
FPS-A5	0301802
FPS-F5	0301805
FPS-F5 T	0301807
FPS-S 13	0301705

When using an FPS system, an FPS sensor (FPS-S) and an electronic processor (FPS-F5/ F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as optional extras in the "Accessories" catalog section.

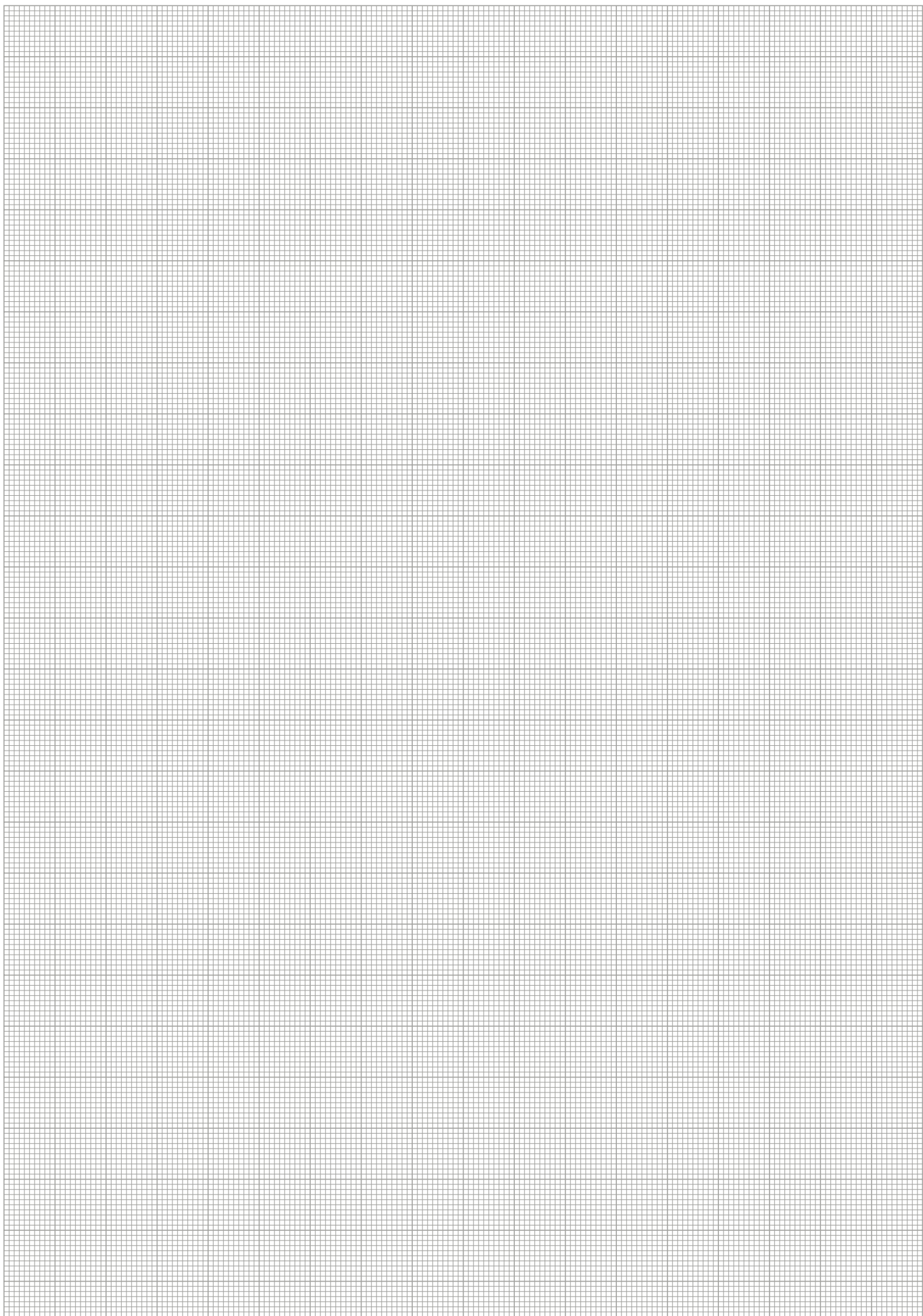
#### Extension cables for proximity switches/magnetic switches

Designation	ID
GK 3-M8	0301622
KV 10-M12	0301596
KV 10-M8	0301496
KV 20-M12	0301597
KV 20-M8	0301497
KV 3-M12	0301595
KV 3-M8	0301495
W 3-M12	0301503
W 5-M12	0301507
WK 3-M8	0301594
WK 5-M8	0301502

- ① For the sensor cables, observe the minimum permitted bending radii. Generally, these are 35 mm.

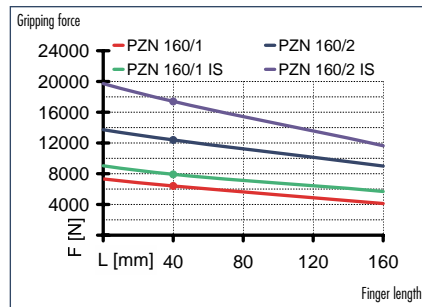


You can find detailed information and components of the specified accessory in the "Accessories" catalog section.

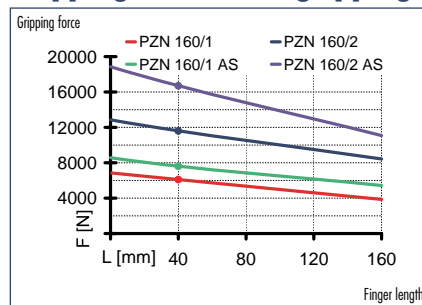




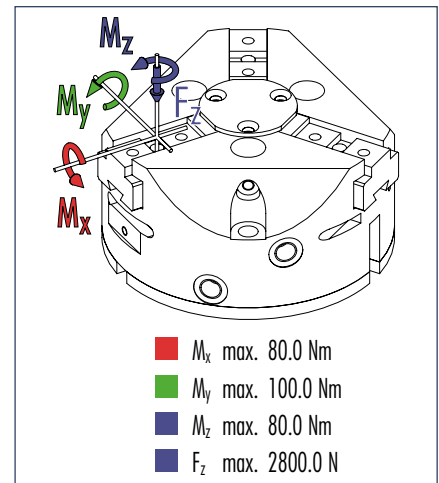
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping



### Finger load



① Moments and forces apply per base jaw and may occur simultaneously.  $M_y$  may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. The tool life may be reduced.

## Technical data

Designation		PZN 160-1	PZN 160-2	PZN 160-1 AS	PZN 160-2 AS	PZN 160-1 IS	PZN 160-2 IS
	ID	0300314	0300414	0300514	0300614	0300544	0300644
Stroke per jaw	[mm]	16.0	8.0	16.0	8.0	16.0	8.0
Closing force	[N]	6000.0	11000.0	7500.0	16000.0		
Opening force	[N]	6400.0	12380.0			7500.0	16000.0
Min. spring force	[N]			2000.0	3700.0	2000.0	3700.0
Weight	[kg]	4.5	4.5	6.6	6.6	7.2	7.2
Recommended workpiece weight	[kg]	25.0	50.0	25.0	50.0	25.0	50.0
Air consumption per double stroke	[cm <sup>3</sup> ]	520.0	520.0	520.0	520.0	520.0	520.0
Minimum pressure	[bar]	2.0	2.0	4.0	4.0	4.0	4.0
Maximum pressure	[bar]	8.0	8.0	6.5	6.5	6.5	6.5
Nominal operating pressure	[bar]	6.0	6.0	6.0	6.0	6.0	6.0
Closing time	[s]	0.4	0.4	0.35	0.35	0.75	0.75
Opening time	[s]	0.4	0.4	0.75	0.75	0.35	0.35
Max. permitted finger length	[mm]	160.0	160.0	160.0	160.0	160.0	160.0
Max. permitted weight per finger	[kg]	3.0	3.0	3.0	3.0	3.0	3.0
IP class		40	40	40	40	40	40
Min. ambient temperature	[°C]	-10.0	-10.0	-10.0	-10.0	-10.0	-10.0
Max. ambient temperature	[°C]	90.0	90.0	90.0	90.0	90.0	90.0
Repeat accuracy	[mm]	0.05	0.05	0.05	0.05	0.05	0.05



A,a Main connection, direct connection – Open gripper  
B,b Main connection, direct connection – Close gripper  
① Gripper connection  
② Finger connection  
②4 Screw pitch circle

Technical drawing of a mechanical part, likely a valve or plug, showing dimensions and callouts:

- Callout 3:** Points to the top surface of the part.
- Callout 4:** Points to the bottom surface of the part.
- Dimensions:**
  - Overall height:  $\varnothing 7$
  - Inner hole diameter:  $\varnothing 4$
  - Threaded section diameter:  $\varnothing 4 \times 1.5$
  - Threaded section length:  $1.1$
  - Thread specification:  $M 4$

- 

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PZN 160/1 SD 112 ... 128  
PZN 160/2 SD 112 ... 120

Technical drawing showing the dimensions of the PZN 160/1 SD 112 ... 128 and PZN 160/2 SD 112 ... 120 components. The drawing includes a top view and a side view.

**Top View Dimensions:**

- Overall width: 60
- Central slot width: 26
- Slot width at the bottom: 24
- Radius of the central slot: R/3
- Angle of the central slot: 2x45°
- Distance from the center to the bottom edge: 17
- Distance from the center to the top edge: 54
- Distance from the center to the side edge: 88
- Overall height: 107
- Distance from the center to the side edge (bottom): 80

**Side View Dimensions:**

- Overall width: 90
- Distance from the center to the side edge: 8.5
- Distance from the center to the bottom edge: 1.5

[illegible]

Designation	Material	Scope of delivery	ID
ABR 160	Aluminum	1	0300729
SBR 160	16 MnCr 5	1	0300738

The technical drawing shows two views of the TSP 90° 6-Port Adapter. The front view (left) is circular with a diameter of 90 mm. It features six ports arranged in three pairs around the perimeter. Each port has a width of 25 mm and a depth of 78 mm. The distance between the centers of adjacent ports is 38.5 mm. The distance from the center of the adapter to the center of each port is 44.5 mm. The distance from the outer edge of the adapter to the center of each port is 22.3 mm. The side view (right) shows the adapter's profile with a total height of 90 mm. The top flange has a thickness of 4 mm. The main body has a diameter of Ø15 mm. The distance from the top flange to the bottom of the main body is 24.5 mm. The distance from the bottom of the main body to the base is 0 ... 6 mm. The base has a diameter of Ø11 (3x).

Designation	Stroke	Min. total force	ID
A-PZN 160	6 mm	180 N	0300724

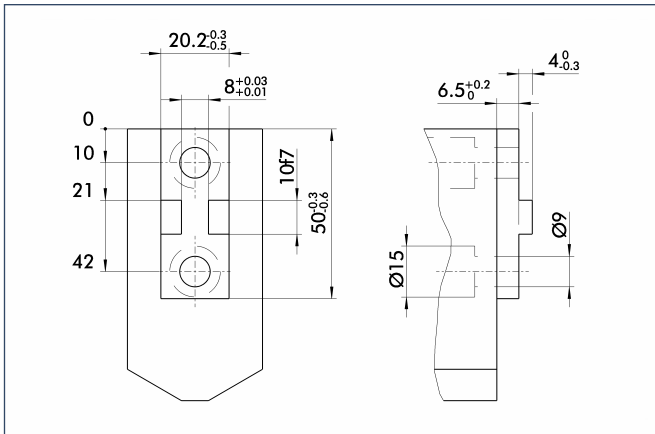
Technical drawing of a circular mechanical part, showing a side view and a top view.

**Side View (Left):** Shows the profile of the part. Key dimensions include a total width of 25, a central slot width of 17, and a small feature width of 6.

**Top View (Right):** Shows the circular face of the part. Key dimensions include a central hole diameter of 10.5, an outer diameter of 25.5, and a radial slot width of 6.

Designation	ID
AS-PZN 125-160	0301714

### Finger design

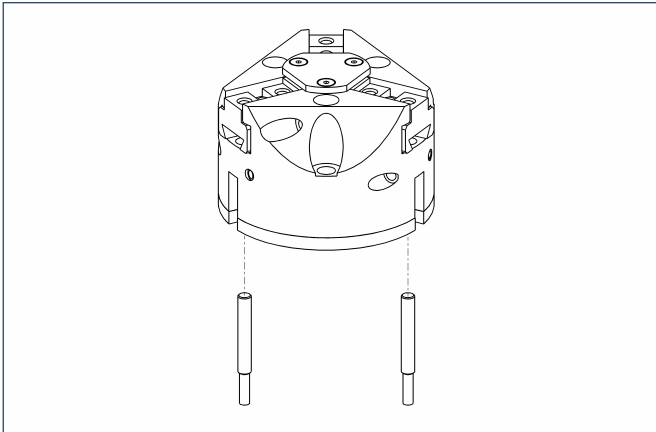


Suggestion for connection dimensions — Gripper fingers



You can find detailed information and components of the specified accessory in the "Accessories" catalog section.

### Sensor systems

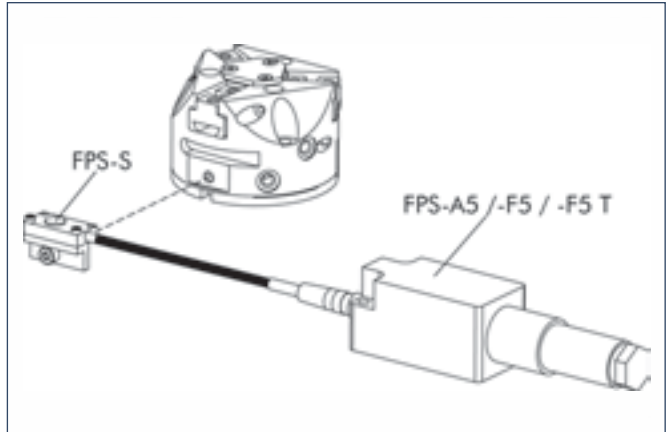


#### End position monitoring:

Inductive proximity switches, for direct mounting

Designation	ID	Recommended product
IN 80/S-M12	0301578	
IN 80/S-M8	0301478	•
INK 80/S	0301550	

- ① Two sensors (NO contacts/S) are required per gripper as well as an optional extension cable.



#### Measuring system:

Position monitoring FPS

Designation	ID
AS-PZN 125-160	0301714
FPS-A5	0301802
FPS-F5	0301805
FPS-F5 T	0301807
FPS-S 13	0301705

When using an FPS system, an FPS sensor (FPS-S) and an electronic processor (FPS-F5/ F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as optional extras in the "Accessories" catalog section.

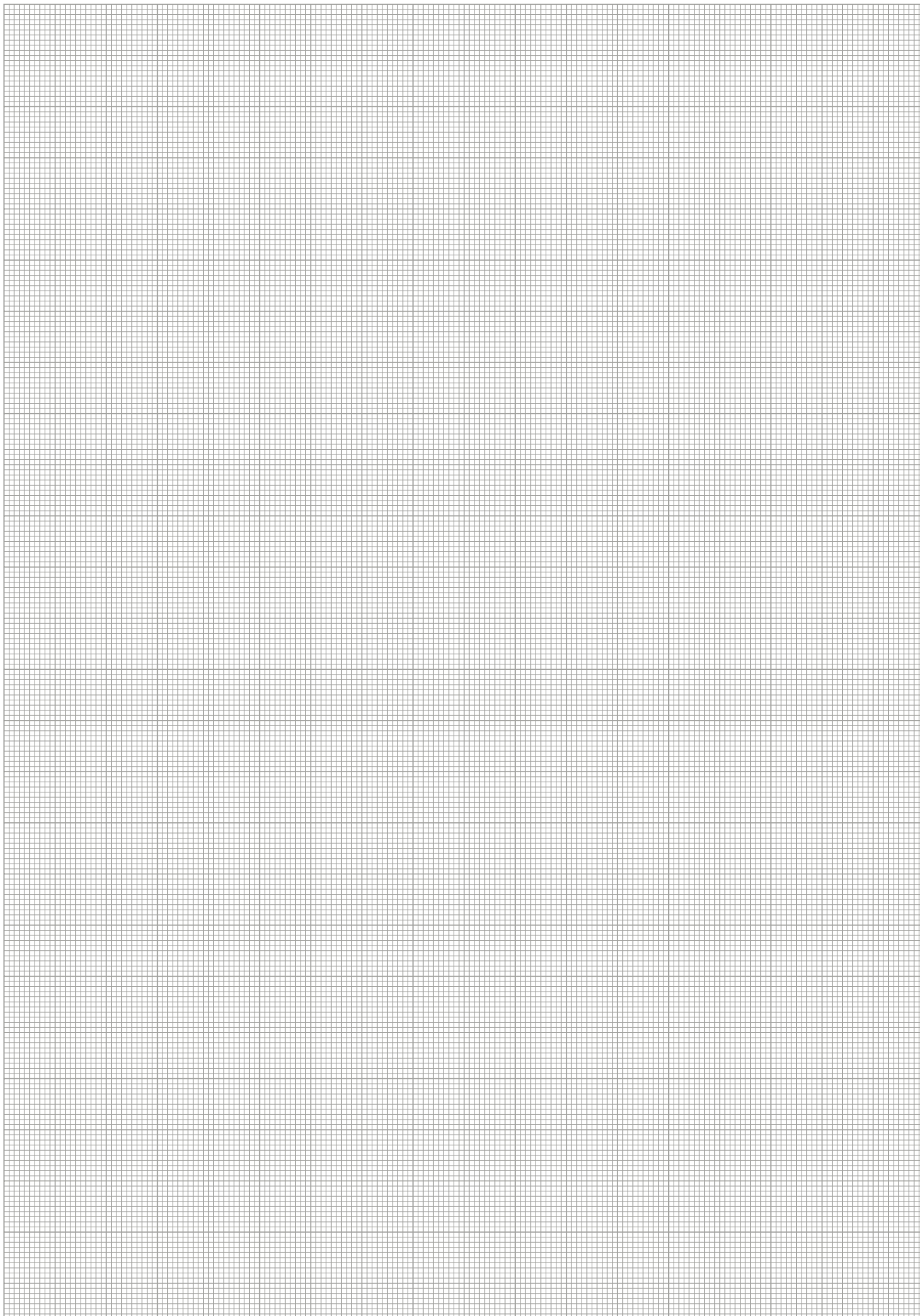
#### Extension cables for proximity switches/magnetic switches

Designation	ID
GK 3-M8	0301622
KV 10-M12	0301596
KV 10-M8	0301496
KV 20-M12	0301597
KV 20-M8	0301497
KV 3-M12	0301595
KV 3-M8	0301495
W 3-M12	0301503
W 5-M12	0301507
WK 3-M8	0301594
WK 5-M8	0301502

- ① For the sensor cables, observe the minimum permitted bending radii. Generally, these are 35 mm.

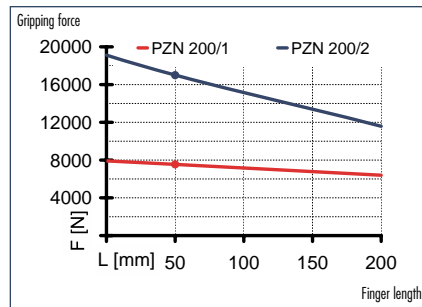


You can find detailed information and components of the specified accessory in the "Accessories" catalog section.

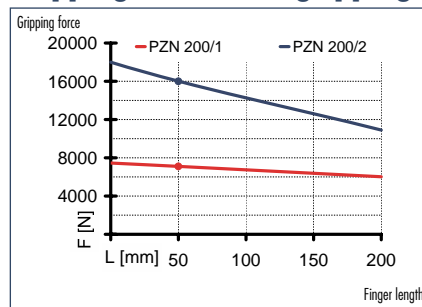




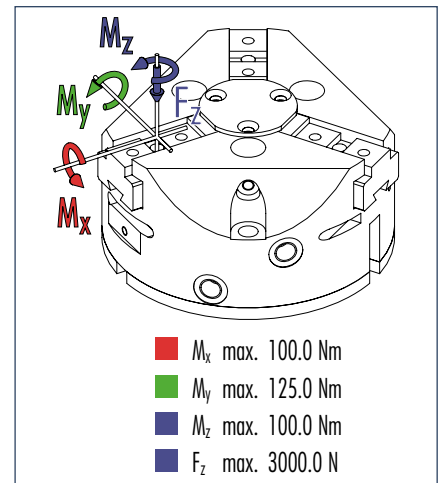
### Gripping force, I.D. gripping



### Gripping force, O.D. gripping



### Finger load



① Moments and forces apply per base jaw and may occur simultaneously.  $M_y$  may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is imperative to throttle the air pressure so that the jaw movement occurs without any hitting or bouncing. The tool life may be reduced.

## Technical data

Designation		PZN 200-1	PZN 200-2
	ID	0300315	0300415
Stroke per jaw	[mm]	25.0	10.0
Closing force	[N]	7100.0	16000.0
Opening force	[N]	7540.0	17000.0
Weight	[kg]	11.0	11.0
Recommended workpiece weight	[kg]	35.0	80.0
Air consumption per double stroke	[cm <sup>3</sup> ]	1040.0	1040.0
Minimum pressure	[bar]	2.0	2.0
Maximum pressure	[bar]	8.0	8.0
Nominal operating pressure	[bar]	6.0	6.0
Closing time	[s]	1.1	1.0
Opening time	[s]	1.1	1.0
Max. permitted finger length	[mm]	200.0	200.0
Max. permitted weight per finger	[kg]	5.5	5.5
IP class		40	40
Min. ambient temperature	[°C]	-10.0	-10.0
Max. ambient temperature	[°C]	90.0	90.0
Repeat accuracy	[mm]	0.1	0.1

[illegible]

A,a Main connection, direct connection – Open gripper  
B,b Main connection, direct connection – Close gripper  
① Gripper connection  
② Finger connection  
②4 Screw pitch circle

Technical drawing of a mechanical part, likely a cross-section of a shaft or a similar component. The drawing includes the following dimensions and callouts:

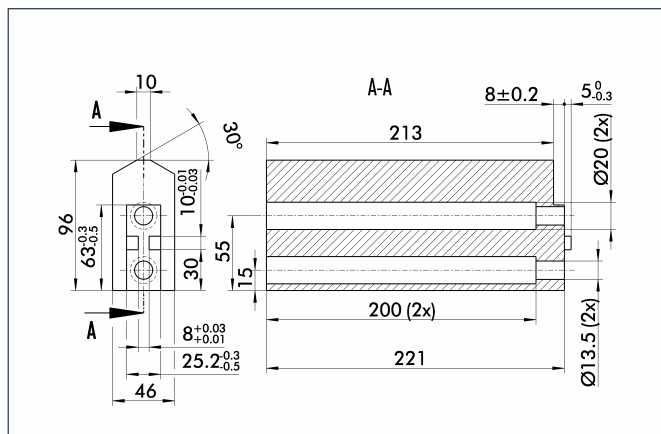
- Callout 3:** Points to a vertical feature on the left side of the part.
- Callout 4:** Points to a horizontal feature on the right side of the part.
- Dimensions:**
  - $\varnothing 7$  and  $\varnothing 4$  indicate diameters of circular features.
  - $M 5$  indicates a thread specification.
  - $1.1$  indicates a linear dimension.
  - $\varnothing 4 \times 1.5$  indicates a hole with a diameter of 4 mm and a depth of 1.5 mm.

- 
- PZN 200/1 SD 128 ... 138  
PZN 200/2 SD 128 ... 138
- 68  
33  
31  
2x45°  
71  
25  
119  
132  
100  
12.3  
1.5  
109.3

501



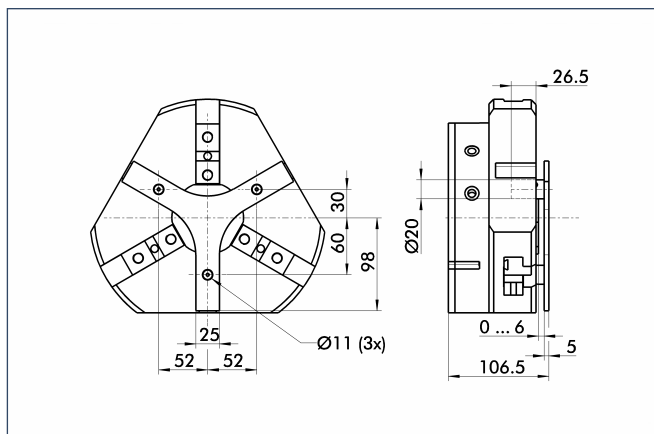
### Finger blanks



Finger blanks for customer-specific reworking, incl. screw connection diagram

Designation	Material	Scope of delivery	ID
ABR 200	Aluminum	1	0300751
SBR 200	16 MnCr 5	1	0300739

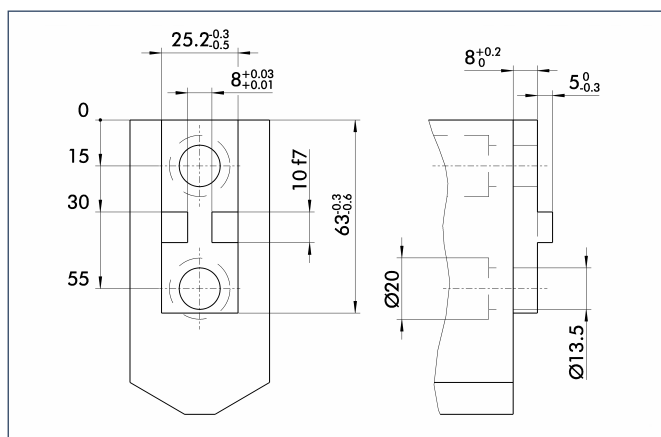
### Spring-loaded pressure plate



For spring-mounted positioning of the workpiece against the stop after the gripper has opened. Developed especially for the loading of machining centers.

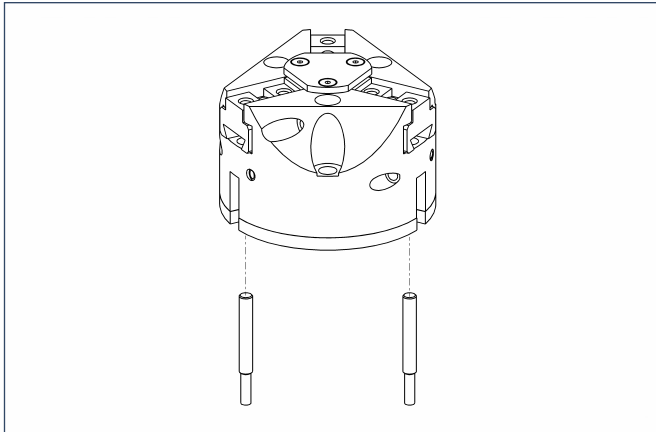
Designation	Stroke	Min. total force	ID
A-PZN 200	6 mm	280 N	0300718

### Finger design



Suggestion for connection dimensions — Gripper fingers

### Sensor systems

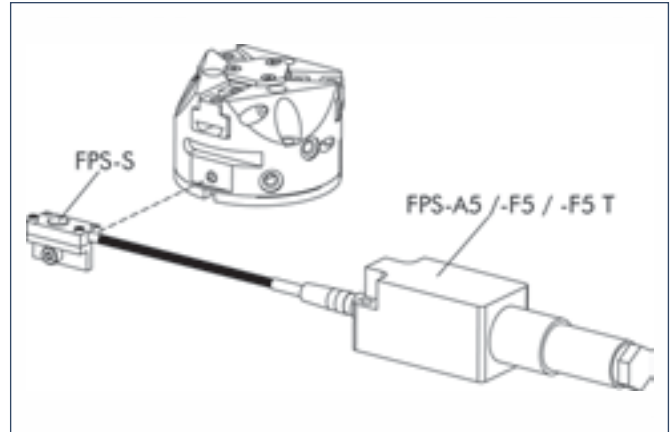


#### End position monitoring:

Inductive proximity switches, for direct mounting

Designation	ID	Recommended product
IN 80/S-M12	0301578	
IN 80/S-M8	0301478	•
INK 80/S	0301550	

- ① Two sensors (NO contacts/S) are required per gripper as well as an optional extension cable.



#### Measuring system:

Position monitoring FPS

Designation	ID
AS-PZN 200	0301719
FPS-A5	0301802
FPS-F5	0301805
FPS-F5 T	0301807
FPS-S 13	0301705

When using an FPS system, an FPS sensor (FPS-S) and an electronic processor (FPS-F5/F5 T or A5) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are available as optional extras in the "Accessories" catalog section.

### Extension cables for proximity switches/magnetic switches

Designation	ID
GK 3-M8	0301622
KV 10-M12	0301596
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KV 3-M8	0301495
W 3-M12	0301503
W 5-M12	0301507
WK 3-M8	0301594
WK 5-M8	0301502

- ① For the sensor cables, observe the minimum permitted bending radii. Generally, these are 35 mm.



You can find detailed information and components of the specified accessory in the "Accessories" catalog section.