

Hand in hand for tomorrow



# **Product data sheet**

Sealed universal gripper DPZ-plus

# Fully encapsulated. Reliable. Precise.

# Sealed gripper DPZ-plus

Despite the high moment load of the base jaws, this sealed 3-finger centric gripper meets the requirements of IP67 and does not permit the ingress of any substances from the working environment into the interior of the component.

## Field of application

The gripper is ideally suitable for handling of rough or dirty workpieces. Its field of application extends from the loading and unloading of machines, such as in the case of sanitary blocks, grinding machines, lathes or milling machines, to handling tasks in painting plants, in powder-processing or underwater.

## **Advantages – Your benefits**

**Robust interior multi-tooth guidance** for the precise handling of different workpieces

**Lip seal at the outside round guidance** for permanent, secure gripper sealing

**High maximum moments possible** suitable for using long gripper fingers

**Sealed 3-finger centric gripper** complies to IP67 requirements despite a high moment load

**Fastening at one gripper side in two screw directions** for universal and flexible gripper assembly

Maximum gripping forces at a compact design for a wide range of applications

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

**Compact dimensions** for minimal interfering contours in handling







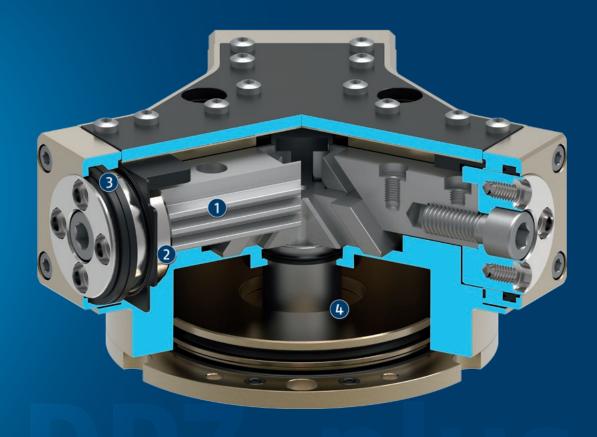






# **Functional description**

The piston is moved up and down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



- ① Inner base jaw with multi-tooth guidance for high moment loads
- ② External round base jaw providing a sealable, round surface

- 3 Lip seal for permanent, secure gripper sealing
- Round piston with rod and wedge-hook for power generation

## General notes about the series

**Operating principle:** Wedge-hook kinematics **Housing material:** Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per

ISO 8573-1:2010 [7:4:4]. **Warranty:** 36 months

Service life characteristics: on request

**Scope of delivery:** Centering sleeves, centering pins, 0-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

**Gripping force maintenance:** possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

**Finger length:** is measured from the reference surface as the distance P in direction to the main axis. The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

**Note – tightness:** Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

**Gripping force:** is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

**Repeat accuracy:** is defined as a distribution of the end Position for 100 consecutive strokes.

**Workpiece weight:** is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are movement times of the base jaws only, without application–specific gripper fingers. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

## **Application example**

Insertion tool for assembly of small to medium-sized workpieces. The tool can be used in both clean and dirty environments. Due to its quick-change system, other tools can alternately be fixed to the robot flange.

- 1 3-finger centric gripper DPZ-plus
- 2 Automatic tool changers CPS



## SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.





Compensation unit



Tolerance compensation unit



Pressure maintenance valve



Universal intermediate jaw



Magnetic switches



Intermediate jaw



Jaw quick-change system

① For more information on these products can be found on the following product pages or at schunk.com.

## Options and special information

**Gripping force maintenance version AS/IS:** The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

Power booster version KVZ: if higher gripping forces are required

ATEX version EX: for explosive environments

**Additional versions:** Various options can be combined with each other. Numerous additional options are also available – just tell us what your task is!

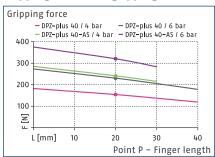
Integrated air purge connection: impedes the ingress of dirt into the inside of the gripper

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

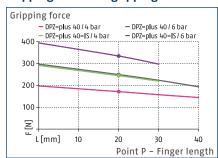
**Food-grade lubrication:** The product contains food-compliant lubricants as standard. The requirements of EN 1672–2:2020 are not fully met. The relevant NSF certificates are available at https://info.nsf.org/USDA/Listings.asp using the lubricant information in the operating manual.



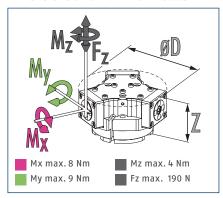
#### Gripping force 0.D. gripping



## **Gripping force I.D. gripping**



#### **Dimensions and maximum loads**



The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

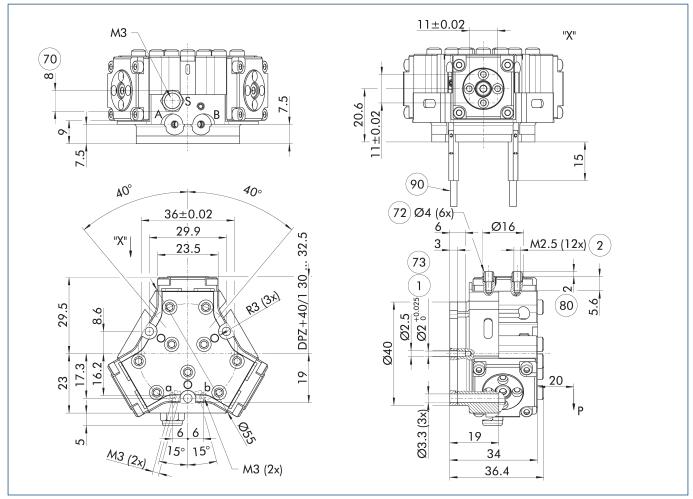
#### **Technical data**

Description		DPZ-plus 40	DPZ-plus 40-AS	DPZ-plus 40-IS
ID		1316263	1316265	1316267
Stroke per jaw	[mm]	2.5	2.5	2.5
Closing/opening force	[N]	230/250	320/-	-/355
Min. spring force	[N]		90	105
Weight	[kg]	0.2	0.25	0.25
Recommended workpiece weight	[kg]	1.15	1.15	1.15
Cylinder volume per double stroke	[cm³]	5	9	9
Min./nom./max. operating pressure	[bar]	2.5/6/8	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	0.03/0.03	0.03/0.05	0.03/0.05
Max. permissible finger length	[mm]	40	30	30
Max. permissible weight per finger	[kg]	0.1	0.1	0.1
IP protection class		67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01
Cleanroom class ISO 14644-1		5	5	5
Dimensions Ø D x Z	[mm]	63 x 34	63 x 42	63 x 42
Options and their characteristics				
High-temperature version		1321291	1321292	1321293
Min./max. ambient temperature	[°C]	5/130	5/130	5/130

① Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

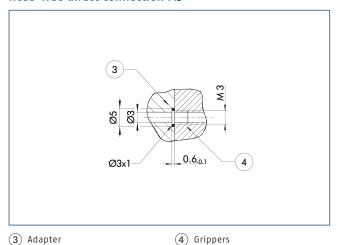
#### Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

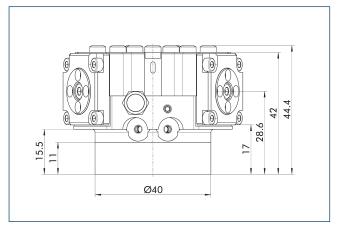
- ① As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S, E Air purge connection, or deaeration bore
- 1 Gripper connection
- (2) Finger connection
- 70 Wrench size
- 72 Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

#### Hose-free direct connection M3



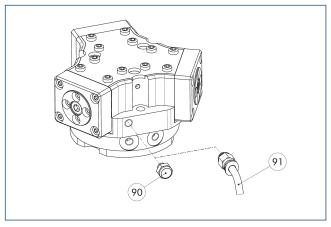
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

#### **Gripping force maintenance version AS/IS**



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

#### Connect the air purge connection

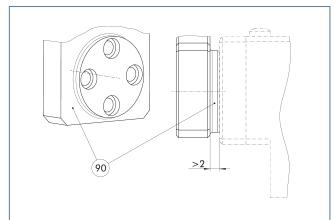


90 Sinter filter

(91) Hose for ventilation or air purge connection

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

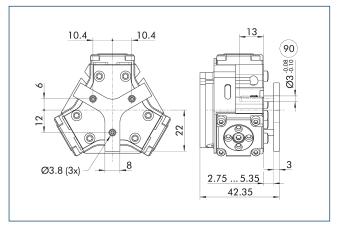
## Proposed jaw design



90 Step

In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

## Spring-loaded pressure piece

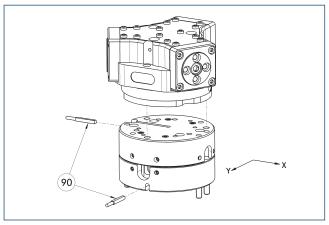


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description ID		Stroke	Min. force
		[mm]	[N]
Spring-loaded p	ressure piece		
A-DPZ-plus 40	0303730	2.6	11

## Compensation unit AGE-F

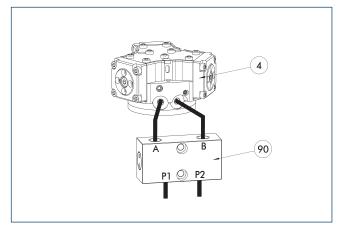


90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-031-1	0324900	± 1.5	1.5	
AGE-F-XY-031-2	0324901	± 1.5	4	
AGE-F-XY-031-3	0324902	± 1.5	5.5	•

#### SDV-P pressure maintenance valve



4 Grippers

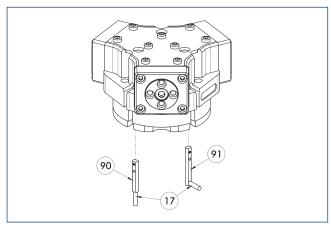
90 SDV-P pressure maintenance

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter	
		[mm]	
Pressure maintenance valve			
SDV-P 04	0403130	6	
Pressure maintenance valve with air bleed screw			
SDV-P 04-E	0300120	6	

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

## **Electronic magnetic switch MMS**



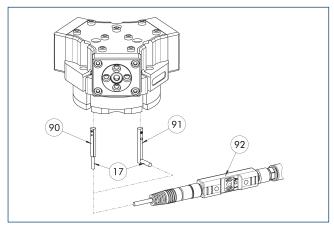
- $\widehat{17}$  Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Programmable magnetic switch MMS 22-PI1



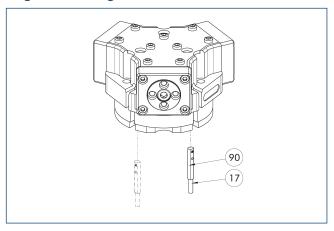
- (17) Cable outlet
- (91) Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...
- (92) Connector teaching tool ST

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	•
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI1-S-M8-PNP-SA	0301166	•
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch	with stainless	s steel housing
MMS 22-PI1-S-M8-PNP-HD	0301110	•
MMSK 22-PI1-S-PNP-HD	0301112	
Plug teaching tool		
ST-MMS 22-PI1-PNP	0301025	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

#### Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

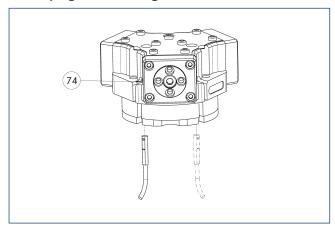
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined		
Programmable magnetic switch				
MMS 22-PI2-S-M8-PNP	0301180	•		
MMSK 22-PI2-S-PNP	0301182			
Programmable magnetic switch	with lateral c	able outlet		
MMS 22-PI2-S-M8-PNP-SA	0301186	•		
MMSK 22-PI2-S-PNP-SA	0301188			
Programmable magnetic switch with stainless steel housing				
MMS 22-PI2-S-M8-PNP-HD	0301130	•		
MMSK 22-PI2-S-PNP-HD	0301132			

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## MMS-P programmable magnetic switch



74 Limit stop for sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

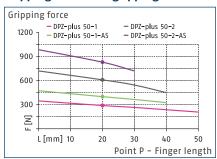
Description	ID	Often combined
Programmable magnetic switc	h	
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	•
Connection cables		
KA GLN0804-LK-00500-A	0307767	•
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
Clip for connector/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

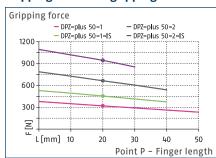
Sealed universal gripper



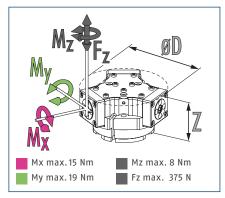
#### Gripping force 0.D. gripping



## **Gripping force I.D. gripping**



#### **Dimensions and maximum loads**



The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

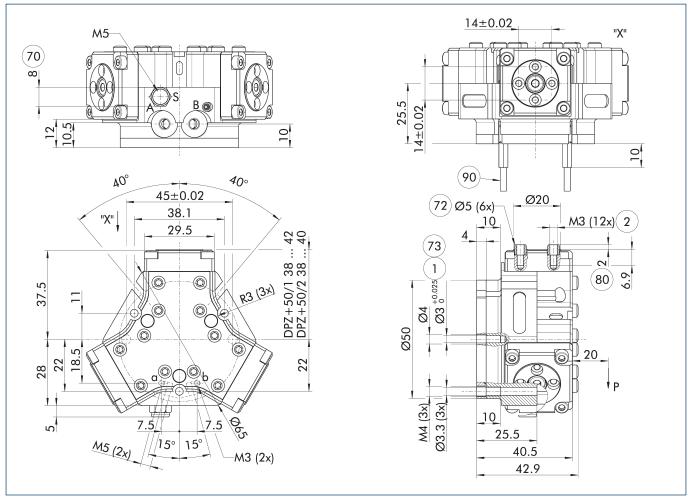
#### **Technical data**

Description		DPZ-plus 50-1	DPZ-plus 50-2	DPZ-plus 50-1-AS	DPZ-plus 50-2-AS	DPZ-plus 50-1-IS	DPZ-plus 50-2-IS
ID		1316268	1316271	1316272	1316275	1316276	1316277
Stroke per jaw	[mm]	4	2	4	2	4	2
Closing/opening force	[N]	290/320	610/665	400/-	830/-	-/455	-/945
Min. spring force	[N]			110	220	135	280
Weight	[kg]	0.37	0.37	0.45	0.45	0.45	0.45
Recommended workpiece weight	[kg]	1.45	3.06	1.45	3.06	1.45	3.06
Cylinder volume per double stroke	[cm³]	9	9	18	18	18	18
Min./nom./max. operating pressure	[bar]	2.5/6/8	2.5/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	0.03/0.03	0.03/0.03	0.03/0.05	0.03/0.05	0.05/0.03	0.05/0.03
Max. permissible finger length	[mm]	50	40	40	30	40	30
Max. permissible weight per finger	[kg]	0.15	0.15	0.15	0.15	0.15	0.15
IP protection class		67	67	67	67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Cleanroom class ISO 14644-1		5	5	5	5	5	5
Dimensions Ø D x Z	[mm]	80.6 x 40.5	80.6 x 40.5	80.6 x 50.9	80.6 x 50.9	80.6 x 50.9	80.6 x 50.9
Options and their characteristics							
High-temperature version		1321294	1321296	1321297	1321299	1321301	1321302
Min./max. ambient temperature	[°C]	5/130	5/130	5/130	5/130	5/130	5/130

① Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

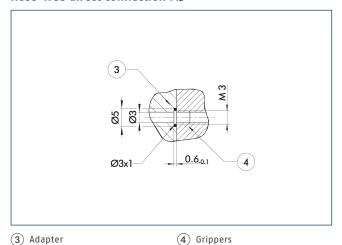
#### Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

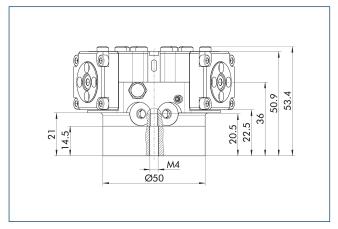
- As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S, E Air purge connection, or deaeration bore
- (1) Gripper connection
- (2) Finger connection
- 70 Wrench size
- 72 Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

#### Hose-free direct connection M3



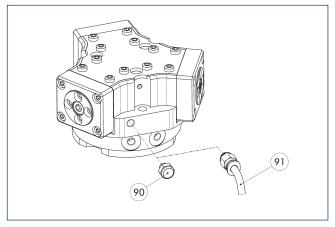
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

## **Gripping force maintenance version AS/IS**



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

## Connect the air purge connection

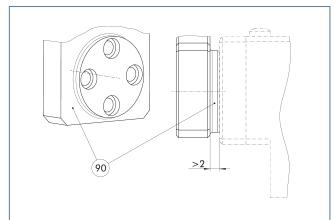


90 Sinter filter

(91) Hose for ventilation or air purge connection

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

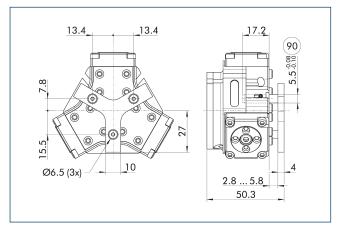
## Proposed jaw design



90 Step

In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

#### Spring-loaded pressure piece

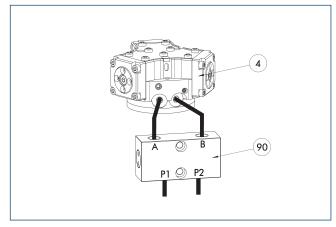


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description ID		Stroke	Min. force
		[mm]	[N]
Spring-loaded p	ressure piece		
A-DPZ-plus 50	0303731	3	18

#### SDV-P pressure maintenance valve



4 Grippers

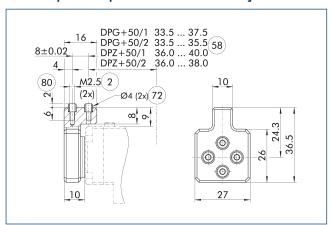
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter		
		[mm]		
Pressure maintenance	e valve			
SDV-P 04	0403130	6		
Pressure maintenance valve with air bleed screw				
SDV-P 04-E	0300120	6		

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

#### ZBA DPG-plus/DPZ-plus 50-40 intermediate jaw

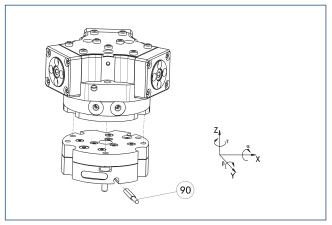


- (2) Finger connection
- (72) Fit for centering sleeves
- (58) Distance from center of gripper
- 80 Depth of the centering sleeve hole in the counter part

Optionally intermediate jaws can be used, enabling direct connection and alignment of top jaws and various standard accessories in Z-direction.

Description	ID	Material	- U	Scope of delivery
Intermediate jaw				
ZBA-DPG-DPZ-plus 50-40	0300191	Aluminum	PGN-plus 40	1

#### Tolerance compensation unit TCU

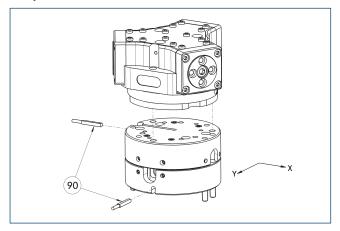


90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection
Compensation unit			
TCU-Z-050-3-0V	0324749	no	±1°/±1°/±1,5°

## Compensation unit AGE-F

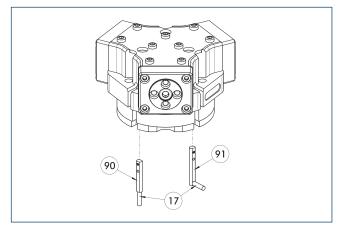


#### 90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-040-1	0324920	± 2	3	
AGE-F-XY-040-2	0324921	± 2	4	
AGE-F-XY-040-3	0324922	± 2	4.5	•

## **Electronic magnetic switch MMS**



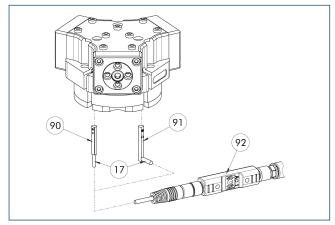
- 17) Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable o	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Programmable magnetic switch MMS 22-PI1



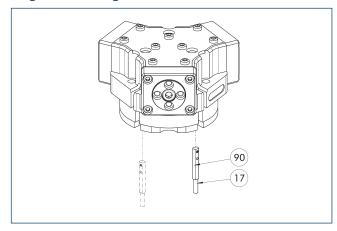
- (17) Cable outlet
- (91) Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...
- (92) Connector teaching tool ST

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	•
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI1-S-M8-PNP-SA	0301166	•
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch	with stainless	s steel housing
MMS 22-PI1-S-M8-PNP-HD	0301110	•
MMSK 22-PI1-S-PNP-HD	0301112	
Plug teaching tool		
ST-MMS 22-PI1-PNP	0301025	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

#### Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

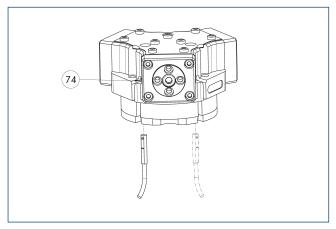
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch	1	
MMS 22-PI2-S-M8-PNP	0301180	•
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI2-S-M8-PNP-SA	0301186	•
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI2-S-M8-PNP-HD	0301130	•
MMSK 22-PI2-S-PNP-HD	0301132	
Plug teaching tool		
ST-MMS 22-PI2-PNP	0301026	

One sensor is required per unit for monitoring two positions.
 Extension cables and sensor distributors are optionally available.
 Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## MMS-P programmable magnetic switch



74 Limit stop for sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

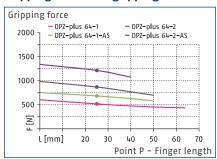
Description	ID	Often combined				
Programmable magnetic switch						
MMSK-P 22-S-PNP	0301371					
MMS-P 22-S-M8-PNP	0301370	•				
Connection cables						
KA GLN0804-LK-00500-A	0307767	•				
KA GLN0804-LK-01000-A	0307768					
KA WLN0804-LK-00500-A	0307765					
KA WLN0804-LK-01000-A	0307766					
Clip for connector/socket						
CLI-M8	0301463					
Sensor distributor						
V2-M8-4P-2XM8-3P	0301380					

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

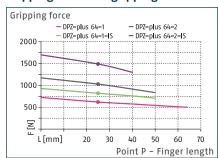
Sealed universal gripper



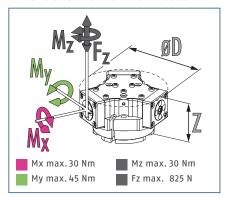
#### Gripping force 0.D. gripping



## **Gripping force I.D. gripping**



#### **Dimensions and maximum loads**



The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

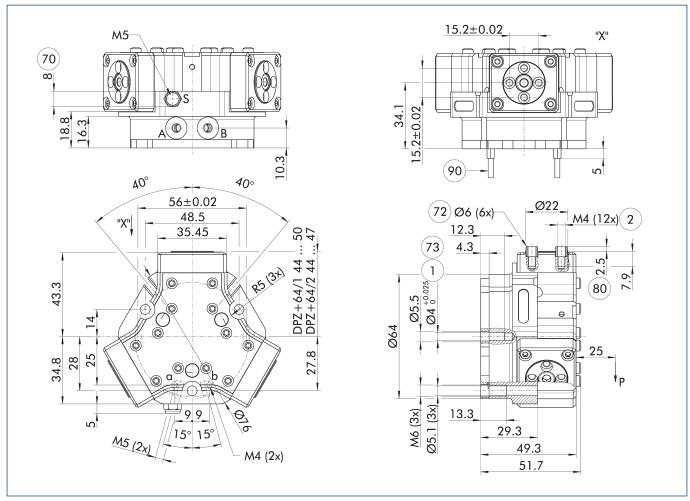
#### **Technical data**

Description		DPZ-plus 64-1	DPZ-plus 64-2	DPZ-plus 64-1-AS	DPZ-plus 64-2-AS	DPZ-plus 64-1-IS	DPZ-plus 64-2-IS
ID		1316280	1316282	1316283	1316284	1316286	1316287
Stroke per jaw	[mm]	6	3	6	3	6	3
Closing/opening force	[N]	520/620	870/1030	685/-	1215/-	-/820	-/1490
Min. spring force	[N]			165	345	200	460
Weight	[kg]	0.62	0.62	0.75	0.75	0.75	0.75
Recommended workpiece weight	[kg]	2.6	4.35	2.6	4.35	2.6	4.35
Cylinder volume per double stroke	[cm³]	25	25	48	48	48	48
Min./nom./max. operating pressure	[bar]	2.5/6/8	2.5/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	0.04/0.04	0.04/0.04	0.03/0.05	0.03/0.05	0.05/0.03	0.05/0.03
Max. permissible finger length	[mm]	64	50	50	40	50	40
Max. permissible weight per finger	[kg]	0.3	0.3	0.3	0.3	0.3	0.3
IP protection class		67	67	67	67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Cleanroom class ISO 14644-1		5	5	5	5	5	5
Dimensions Ø D x Z	[mm]	93.6 x 49.3	93.6 x 49.3	93.6 x 62.7	93.6 x 62.7	93.6 x 62.7	93.6 x 62.7
Options and their characteristics							
High-temperature version		1321310	1321311	1321312	1321313	1321318	1321319
Min./max. ambient temperature	[°C]	5/130	5/130	5/130	5/130	5/130	5/130
Power booster version		1316281					
Closing/opening force	[N]	849/935					
Weight	[kg]	0.92					
Maximum pressure	[bar]	6					
Max. permissible finger length	[mm]	40					

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

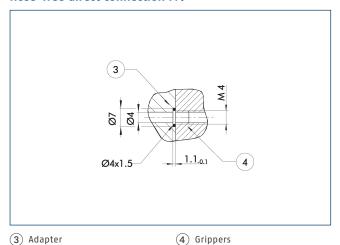
#### Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

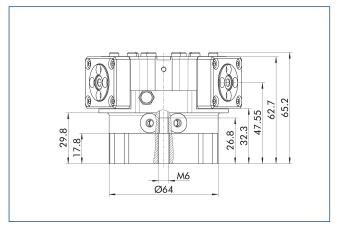
- As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S, E Air purge connection, or deaeration bore
- (1) Gripper connection
- (2) Finger connection
- 70 Wrench size
- 72 Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

#### Hose-free direct connection M4



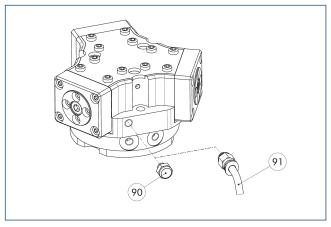
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

#### **Gripping force maintenance version AS/IS**



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

## Connect the air purge connection

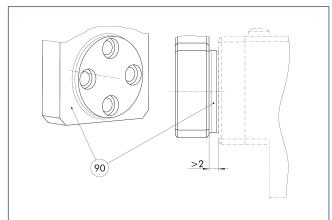


90 Sinter filter

(91) Hose for ventilation or air purge connection

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

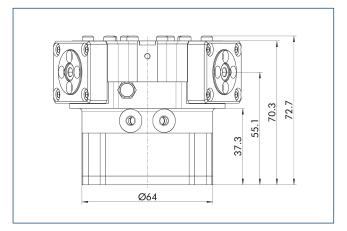
## Proposed jaw design



90 Step

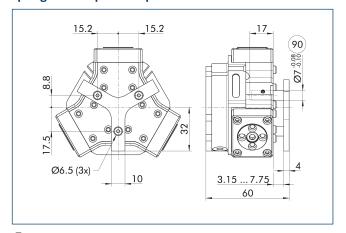
In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

#### **Power booster version**



The KVZ cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. Please consider that grippers which are equipped with a gripping force maintenance device are higher.

#### Spring-loaded pressure piece

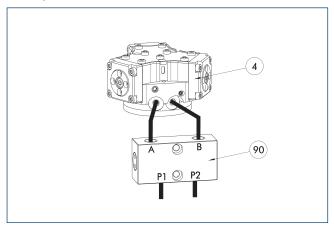


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
		[mm]	[N]
Spring-loaded pressure piece			
A-PZN-plus/DPZ-plus 64	0303720	4.6	11

#### SDV-P pressure maintenance valve



4 Grippers

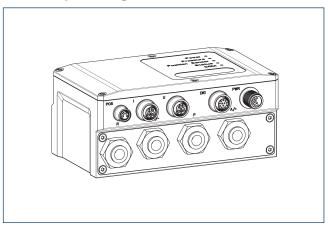
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter			
		[mm]			
Pressure maintenanc	e valve				
SDV-P 04	0403130	6			
SDV-P 07	0403131	8			
Pressure maintenance valve with air bleed screw					
SDV-P 04-E	0300120	6			
SDV-P 07-E	0300121	8			

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

#### **Pneumatic positioning device PPD**

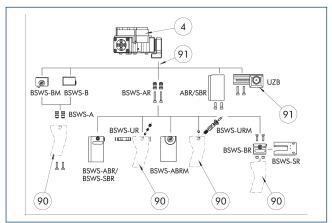


The PPD allows flexibility in all applications with pneumatic grippers through free positioning, gripping force and speed adjustment.

Description	ID
Pneumatic positioning device	
PPD 20-IOL	1540700
Adapter	
A GGN0804-1204-A	1540691
10-Link connection cable	
KA GGN1205-1212-IOL-00100-A	1540697
Voltage supply connection cable - cab	e track compa
KA GLN12B05-LK-01000-A	1540660
Cable extension	
KV GGN0804-I0-00150-A	1540662
KV GGN0804-10-00300-A	1540663
Assembly set	
Assembly set PPD	1540705

 In addition to the PPD, a position sensor (SCHUNK IO-Link sensor or analog sensor (4...20 mA)) is required.

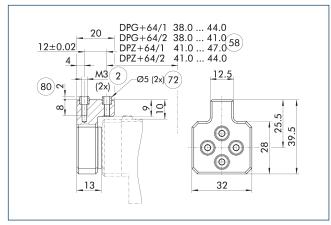
## Intermediate jaw interface



- (4) Grippers
- (90) Customized gripper fingers
- (91) Uniform screw connection pattern

By using the intermediate jaw, you have the possibility of directly connecting a wide range of accessories directly. This includes jaw quick-change systems, finger blanks, and universal intermediate jaws.

#### ZBA DPG-plus/DPZ-plus 64-50 intermediate jaw

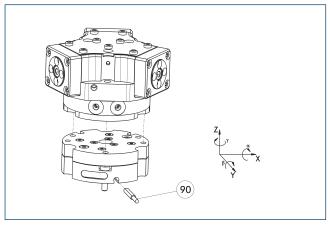


- (2) Finger connection
- (58) Distance from center of gripper (80) Dep
- (72) Fit for centering sleeves
  - 80 Depth of the centering sleeve hole in the counter part

Optionally intermediate jaws can be used, enabling direct connection and alignment of top jaws and various standard accessories in Z-direction.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-DPG-DPZ-plus 64-50	0300192	Aluminum	PGN-plus 50	1

#### **Tolerance compensation unit TCU**

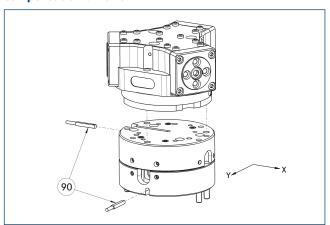


#### 90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-064-3-MV	0324766	yes	±1°/±1°/±1°	•
TCU-Z-064-3-0V	0324767	no	±1°/±1°/±1°	

#### Compensation unit AGE-F

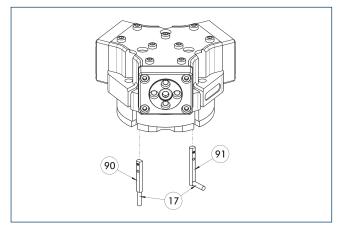


#### 90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-063-1	0324940	± 4	12	
AGE-F-XY-063-2	0324941	± 4	16	
AGE-F-XY-063-3	0324942	± 4	20	•

## **Electronic magnetic switch MMS**



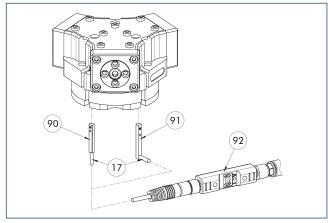
- (17) Cable outlet
- (91) Sensor MMS 22...-SA
- 90 Sensor MMS 22...

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable (	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

#### Programmable magnetic switch MMS 22-PI1



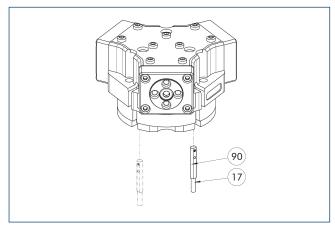
- (17) Cable outlet
- (91) Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...
- (92) Connector teaching tool ST

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined				
Programmable magnetic switch						
MMS 22-PI1-S-M8-PNP	0301160	•				
MMSK 22-PI1-S-PNP	0301162					
Programmable magnetic switch	with lateral c	able outlet				
MMS 22-PI1-S-M8-PNP-SA	0301166	•				
MMSK 22-PI1-S-PNP-SA	0301168					
Programmable magnetic switch	with stainles	s steel housing				
MMS 22-PI1-S-M8-PNP-HD	0301110	•				
MMSK 22-PI1-S-PNP-HD	0301112					
Plug teaching tool						
ST-MMS 22-PI1-PNP	0301025					

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

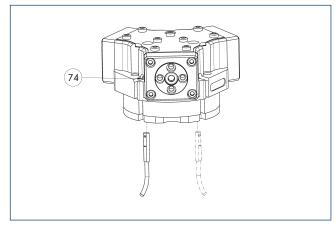
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

• • •		•	
Description	ID	Often combined	
Programmable magnetic switch			
MMS 22-PI2-S-M8-PNP	0301180	•	)
MMSK 22-PI2-S-PNP	0301182		
Programmable magnetic switch	with lateral c	able outlet	
MMS 22-PI2-S-M8-PNP-SA	0301186	•	)
MMSK 22-PI2-S-PNP-SA	0301188		
Programmable magnetic switch	with stainless	s steel housing	
MMS 22-PI2-S-M8-PNP-HD	0301130	•	)
MMSK 22-PI2-S-PNP-HD	0301132		
Plug teaching tool			
ST-MMS 22-PI2-PNP	0301026		

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

#### MMS-P programmable magnetic switch



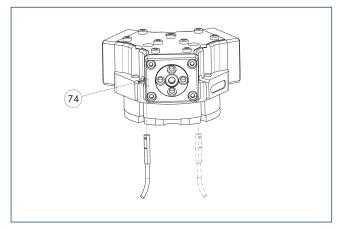
74) Limit stop for sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined				
Programmable magnetic switch						
MMSK-P 22-S-PNP	0301371					
MMS-P 22-S-M8-PNP	0301370	•				
Connection cables						
KA GLN0804-LK-00500-A	0307767	•				
KA GLN0804-LK-01000-A	0307768					
KA WLN0804-LK-00500-A	0307765					
KA WLN0804-LK-01000-A	0307766					
Clip for connector/socket						
CLI-M8	0301463					
Sensor distributor						
V2-M8-4P-2XM8-3P	0301380					

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## Programmable magnetic switch MMS-IO-Link



74 Limit stop for sensor

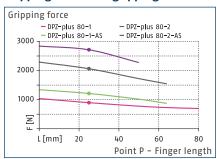
Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. The sensor is programmed for the gripper via the IO-Link interface or the ST plug teaching tool (not included in scope of delivery; ID 0301026). It is not possible to program the sensor using the Magnet teaching tool MT. An IO-Link master is required for operation.

Description	ID
Programmable mag	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

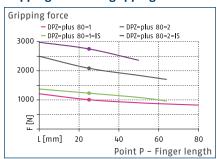
① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.



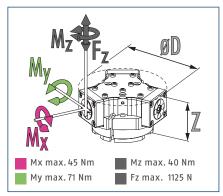
#### Gripping force 0.D. gripping



## **Gripping force I.D. gripping**



#### **Dimensions and maximum loads**



The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

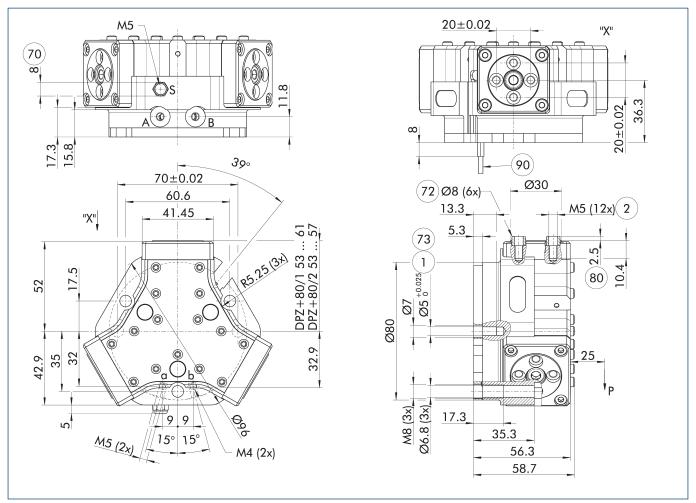
#### Technical data

Description		DPZ-plus 80-1	DPZ-plus 80-2	DPZ-plus 80-1-AS	DPZ-plus 80-2-AS	DPZ-plus 80-1-IS	DPZ-plus 80-2-IS
ID		1316288	1316290	1316291	1316292	1316293	1316295
Stroke per jaw	[mm]	8	4	8	4	8	4
Closing/opening force	[N]	900/1000	2070/2085	1215/-	2725/-	-/1330	-/2765
Min. spring force	[N]			315	655	330	680
Weight	[kg]	1.3	1.3	1.45	1.45	1.45	1.45
Recommended workpiece weight	[kg]	4.5	10.35	4.5	10.35	4.5	10.35
Cylinder volume per double stroke	[cm³]	60	60	108	108	108	108
Min./nom./max. operating pressure	[bar]	2.5/6/8	2.5/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	0.07/0.07	0.07/0.07	0.05/0.08	0.05/0.08	0.08/0.05	0.08/0.05
Max. permissible finger length	[mm]	80	64	64	50	64	50
Max. permissible weight per finger	[kg]	0.5	0.5	0.5	0.5	0.5	0.5
IP protection class		67	67	67	67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Cleanroom class ISO 14644-1		5	5	5	5	5	5
Dimensions Ø D x Z	[mm]	112 x 56.3	112 x 56.3	112 x 71.2	112 x 71.2	112 x 71.2	112 x 71.2
Options and their characteristics							
High-temperature version		1321320	1321321	1321323	1321324	1321325	1321328
Min./max. ambient temperature	[°C]	5/130	5/130	5/130	5/130	5/130	5/130
Power booster version		1316289					
Closing/opening force	[N]	1478/1545					
Weight	[kg]	1.6					
Maximum pressure	[bar]	6					
Max. permissible finger length	[mm]	50					

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

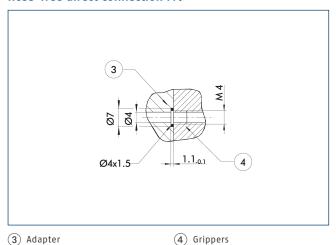
#### Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

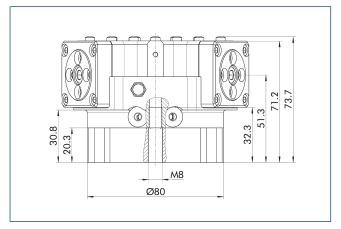
- As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S, E Air purge connection, or deaeration bore
- (1) Gripper connection
- (2) Finger connection
- 70 Wrench size
- 72 Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

#### Hose-free direct connection M4



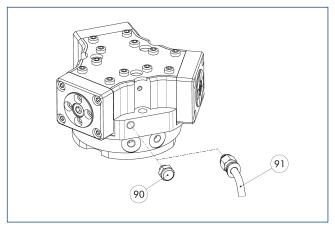
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

#### **Gripping force maintenance version AS/IS**



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

#### Connect the air purge connection

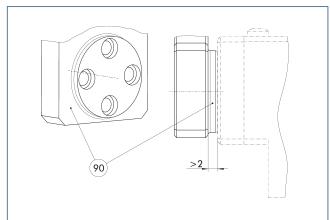


90 Sinter filter

(91) Hose for ventilation or air purge connection

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

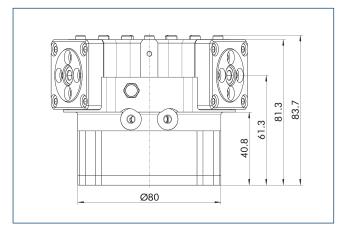
## Proposed jaw design



90 Step

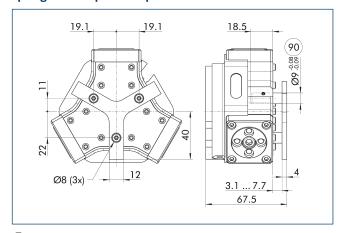
In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

#### **Power booster version**



The KVZ cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. Please consider that grippers which are equipped with a gripping force maintenance device are higher.

#### Spring-loaded pressure piece

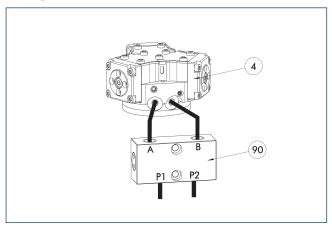


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
		[mm]	[N]
Spring-loaded pressure piece			
A-PZN-plus/DPZ-plus 80	0303721	4.6	18

#### SDV-P pressure maintenance valve



4 Grippers

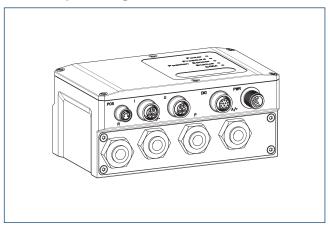
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter		
		[mm]		
Pressure maintenanc	e valve			
SDV-P 04	0403130	6		
SDV-P 07	0403131	8		
Pressure maintenance valve with air bleed screw				
SDV-P 04-E	0300120	6		
SDV-P 07-E	0300121	8		

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

#### **Pneumatic positioning device PPD**

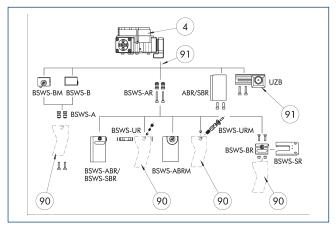


The PPD allows flexibility in all applications with pneumatic grippers through free positioning, gripping force and speed adjustment.

Description	ID
Pneumatic positioning device	
PPD 20-IOL	1540700
Adapter	
A GGN0804-1204-A	1540691
10-Link connection cable	
KA GGN1205-1212-IOL-00100-A	1540697
Voltage supply connection cable - ca	ble track comp
KA GLN12B05-LK-01000-A	1540660
Cable extension	
KV GGN0804-I0-00150-A	1540662
KV GGN0804-10-00300-A	1540663
Assembly set	
Assembly set PPD	1540705

 In addition to the PPD, a position sensor (SCHUNK IO-Link sensor or analog sensor (4...20 mA)) is required.

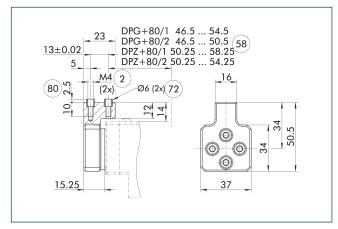
## Intermediate jaw interface



- (4) Grippers
- 90 Customized gripper fingers
- (91) Uniform screw connection pattern

By using the intermediate jaw, you have the possibility of directly connecting a wide range of accessories directly. This includes jaw quick-change systems, finger blanks, and universal intermediate jaws.

#### ZBA DPG-plus/DPZ-plus 80-64 intermediate jaw

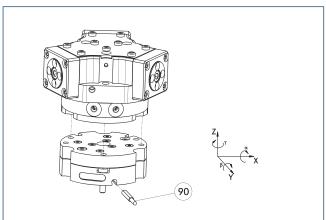


- (2) Finger connection
- 72 Fit for centering sleeves
- 58 Distance from center of gripper
- 80 Depth of the centering sleeve hole in the counter part

Optionally intermediate jaws can be used, enabling direct connection and alignment of top jaws and various standard accessories in Z-direction.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-DPG-DPZ-plus 80-64	0300193	Aluminum	PGN-plus 64	1

#### **Tolerance compensation unit TCU**

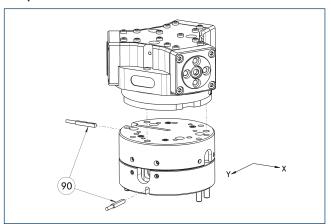


#### 90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-080-3-MV	0324784	yes	±1°/±1°/±1°	•
TCU-Z-080-3-0V	0324785	no	±1°/±1°/±1°	

#### Compensation unit AGE-F

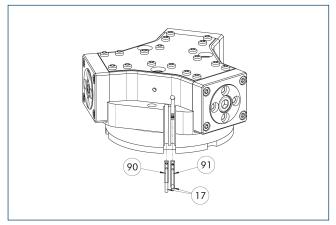


#### 90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-063-1	0324940	± 4	12	
AGE-F-XY-063-2	0324941	± 4	16	
AGE-F-XY-063-3	0324942	± 4	20	•

## **Electronic magnetic switch MMS**



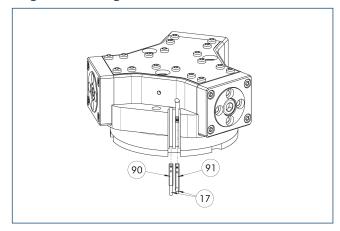
- (17) Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches wit	th lateral cable	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Reed Switches		
RMS 22-S-M8	0377720	•
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

#### Programmable magnetic switch MMS 22-PI1



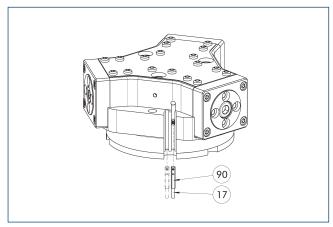
- (17) Cable outlet
- **91** Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

		-		
Description	ID	Often combined		
Programmable magnetic switch				
MMS 22-PI1-S-M8-PNP	0301160	•		
MMSK 22-PI1-S-PNP	0301162			
Programmable magnetic switch with lateral cable outlet				
MMS 22-PI1-S-M8-PNP-SA	0301166	•		
MMSK 22-PI1-S-PNP-SA	0301168			
Programmable magnetic switch with stainless steel housing				
MMS 22-PI1-S-M8-PNP-HD	0301110	•		
MMSK 22-PI1-S-PNP-HD	0301112			

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

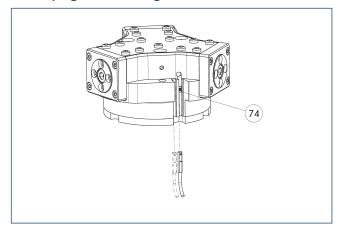
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined		
Programmable magnetic switch				
MMS 22-PI2-S-M8-PNP	0301180	•		
MMSK 22-PI2-S-PNP	0301182			
Programmable magnetic switch with lateral cable outlet				
MMS 22-PI2-S-M8-PNP-SA	0301186	•		
MMSK 22-PI2-S-PNP-SA	0301188			
Programmable magnetic switch with stainless steel housing				
MMS 22-PI2-S-M8-PNP-HD	0301130	•		
MMSK 22-PI2-S-PNP-HD	0301132			

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

#### MMS-P programmable magnetic switch



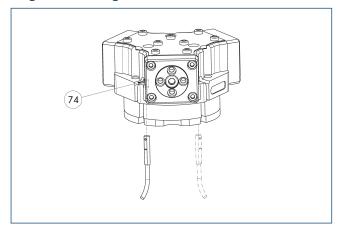
(74) Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined		
Programmable magnetic switch				
MMSK-P 22-S-PNP	0301371			
MMS-P 22-S-M8-PNP	0301370	•		
Connection cables				
KA GLN0804-LK-00500-A	0307767	•		
KA GLN0804-LK-01000-A	0307768			
KA WLN0804-LK-00500-A	0307765			
KA WLN0804-LK-01000-A	0307766			
Clip for connector/socket				
CLI-M8	0301463			
Sensor distributor				
V2-M8-4P-2XM8-3P	0301380			

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

# Programmable magnetic switch MMS-IO-Link



74 Limit stop for sensor

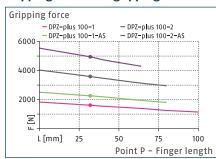
Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. The sensor is programmed for the gripper via the IO-Link interface, Magnet teaching tool MT (included in scope of delivery; ID 0301030) or the ST plug teaching tool (not included in scope of delivery; ID 0301026). An IO-Link master is required for operation.

Description	ID
Programmable mag	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

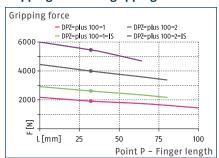
① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.



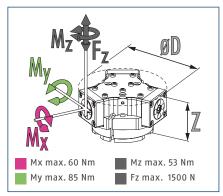
## Gripping force 0.D. gripping



# **Gripping force I.D. gripping**



#### **Dimensions and maximum loads**



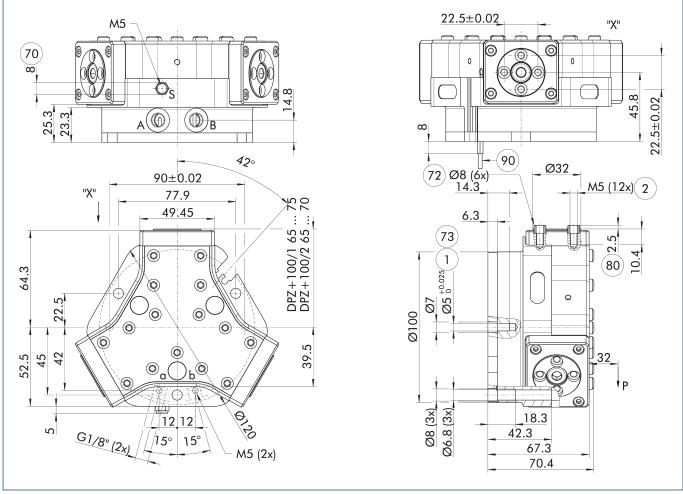
The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

#### **Technical data**

Description		DPZ-plus 100-1	DPZ-plus 100-2	DPZ-plus 100-1-AS	DPZ-plus 100-2-AS	DPZ-plus 100-1-IS	DPZ-plus 100-2-IS
ID		1316296	1316297	1316299	1316300	1316301	1316302
Stroke per jaw	[mm]	10	5	10	5	10	5
Closing/opening force	[N]	1620/1920	3600/4000	2265/-	4950/-	-/2620	-/5460
Min. spring force	[N]			645	1350	700	1460
Weight	[kg]	1.9	1.9	2.3	2.3	2.3	2.3
Recommended workpiece weight	[kg]	8.1	18	8.1	18	8.1	18
Cylinder volume per double stroke	[cm³]	120	120	210	210	210	210
Min./nom./max. operating pressure	[bar]	2.5/6/8	2.5/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	0.13/0.13	0.13/0.13	0.13/0.25	0.13/0.25	0.25/0.13	0.25/0.13
Max. permissible finger length	[mm]	100	80	80	64	80	64
Max. permissible weight per finger	[kg]	0.95	0.95	0.95	0.95	0.95	0.95
IP protection class		67	67	67	67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Cleanroom class ISO 14644-1		5	5	5	5	5	5
Dimensions Ø D x Z	[mm]	137.8 x 67.3	137.8 x 67.3	137.8 x 87.2	137.8 x 87.2	137.8 x 87.2	137.8 x 87.2
Options and their characteristics							
High-temperature version		1321329	1321331	1321332	1321334	1321336	1321340
Min./max. ambient temperature	[°C]	5/130	5/130	5/130	5/130	5/130	5/130

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.
It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

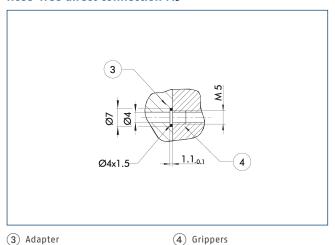
## Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

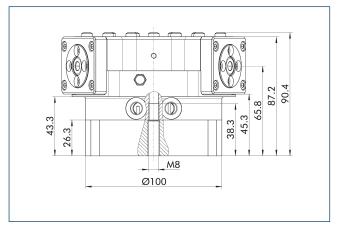
- As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S, E Air purge connection, or deaeration bore
- (1) Gripper connection
- (2) Finger connection
- (70) Wrench size
- 72 Fit for centering sleeves
- (73) Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

#### Hose-free direct connection M5



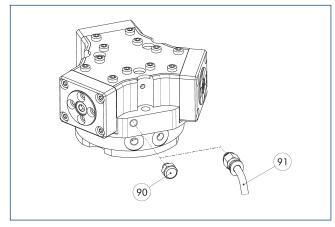
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

# **Gripping force maintenance version AS/IS**



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

## Connect the air purge connection

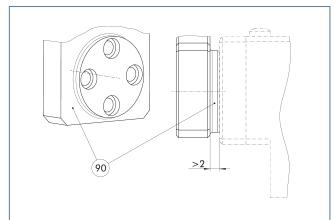


90 Sinter filter

(91) Hose for ventilation or air purge connection

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

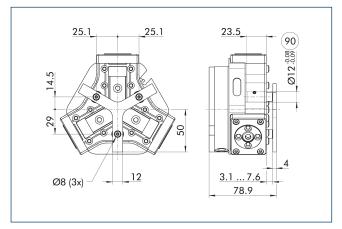
# Proposed jaw design



90 Step

In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

# Spring-loaded pressure piece

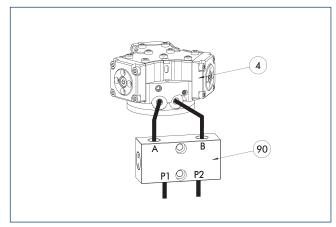


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
		[mm]	[N]
Spring-loaded pressure piece			
A-PZN-plus/DPZ-plus 100	0303722	4.5	35

# SDV-P pressure maintenance valve



4 Grippers

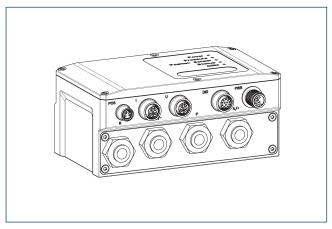
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter		
		[mm]		
Pressure maintenance valve				
SDV-P 04	0403130	6		
SDV-P 07	0403131	8		
Pressure maintenance valve with air bleed screw				
SDV-P 04-E	0300120	6		
SDV-P 07-E	0300121	8		

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

# **Pneumatic positioning device PPD**

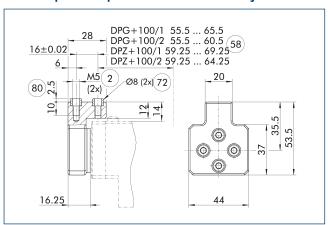


The PPD allows flexibility in all applications with pneumatic grippers through free positioning, gripping force and speed adjustment.

Description	ID	
Pneumatic positioning device		
PPD 20-IOL	1540700	
Adapter		
A GGN0804-1204-A	1540691	
10-Link connection cable		
KA GGN1205-1212-IOL-00100-A	1540697	
Voltage supply connection cable - cab	le track compa	atible
KA GLN12B05-LK-01000-A	1540660	
Cable extension		
KV GGN0804-I0-00150-A	1540662	
KV GGN0804-10-00300-A	1540663	
Assembly set		
Assembly set PPD	1540705	

① In addition to the PPD, a position sensor (SCHUNK IO-Link sensor or analog sensor (4...20 mA)) is required.

## ZBA DPG-plus/DPZ-plus 100-80 intermediate jaw

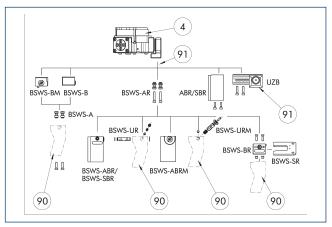


- 2 Finger connection
- (72) Fit for centering sleeves
- (58) Distance from center of gripper
- 80 Depth of the centering sleeve hole in the counter part

Optionally intermediate jaws can be used, enabling direct connection and alignment of top jaws and various standard accessories in Z-direction.

Description	ID	Material		Scope of delivery
Intermediate jaw				
ZBA-DPG-DPZ-plus 100-80	0300194	Aluminum	PGN-plus 80	1

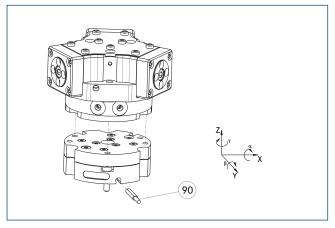
# Intermediate jaw interface



- (4) Grippers
- 90 Customized gripper fingers
- (91) Uniform screw connection pattern

By using the intermediate jaw, you have the possibility of directly connecting a wide range of accessories directly. This includes jaw quick-change systems, finger blanks, and universal intermediate jaws.

# Tolerance compensation unit TCU

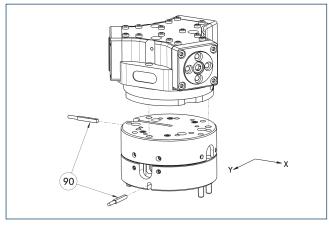


## 90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-100-2-MV	0324798	yes	±1°/±1°/±1°	•
TCU-Z-100-2-0V	0324799	no	±1°/±1°/±1°	

# Compensation unit AGE-F

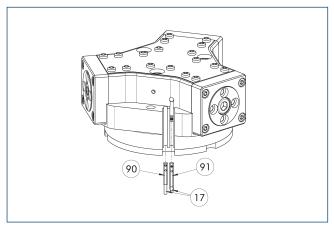


# 90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-080-1	0324960	± 5	39	
AGE-F-XY-080-2	0324961	± 5	85	
AGE-F-XY-080-3	0324962	± 5	90	•

# **Electronic magnetic switch MMS**



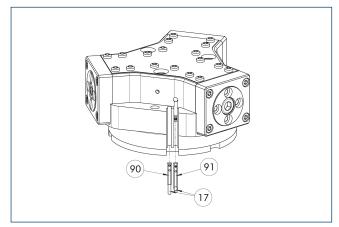
- $\widehat{17}$  Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch	,	
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable o	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Reed Switches		
RMS 22-S-M8	0377720	•
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

# Programmable magnetic switch MMS 22-PI1



(17) Cable outlet

(91) Sensor MMS 22 ..-PI1-...-SA

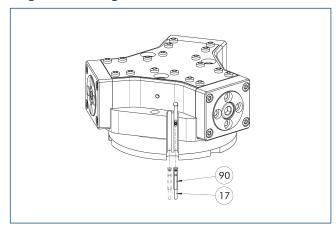
90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined		
Programmable magnetic switch				
MMS 22-PI1-S-M8-PNP	0301160	•		
MMSK 22-PI1-S-PNP	0301162			
Programmable magnetic switch	with lateral c	able outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	•		
MMSK 22-PI1-S-PNP-SA	0301168			
Programmable magnetic switch with stainless steel housing				
MMS 22-PI1-S-M8-PNP-HD	0301110	•		
MMSK 22-PI1-S-PNP-HD	0301112			

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

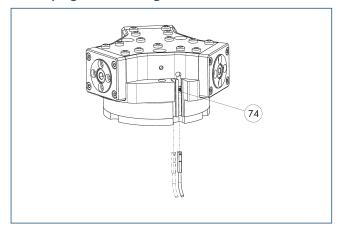
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined			
Programmable magnetic switch					
MMS 22-PI2-S-M8-PNP	0301180	•			
MMSK 22-PI2-S-PNP	0301182				
Programmable magnetic switch	Programmable magnetic switch with lateral cable outlet				
MMS 22-PI2-S-M8-PNP-SA	0301186	•			
MMSK 22-PI2-S-PNP-SA	0301188				
Programmable magnetic switch with stainless steel housing					
MMS 22-PI2-S-M8-PNP-HD	0301130	•			
MMSK 22-PI2-S-PNP-HD	0301132				

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## MMS-P programmable magnetic switch



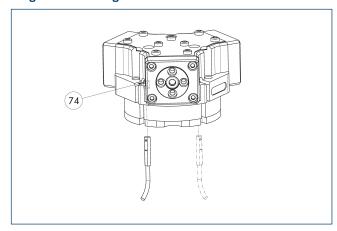
## (74) Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic swit	ch	
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	•
Connection cables		
KA GLN0804-LK-00500-A	0307767	•
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
Clip for connector/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## Programmable magnetic switch MMS-I0-Link



#### 74) Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. The sensor is programmed for the gripper via the IO-Link interface, Magnet teaching tool MT (included in scope of delivery; ID 0301030) or the ST plug teaching tool (not included in scope of delivery; ID 0301026). An IO-Link master is required for operation.

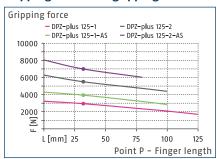
Description	ID
Programmable mag	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

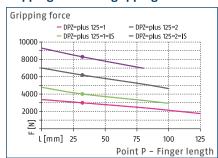
Sealed universal gripper



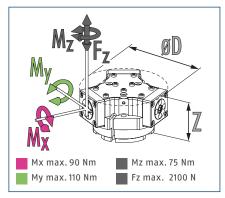
## Gripping force 0.D. gripping



# **Gripping force I.D. gripping**



#### **Dimensions and maximum loads**



The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

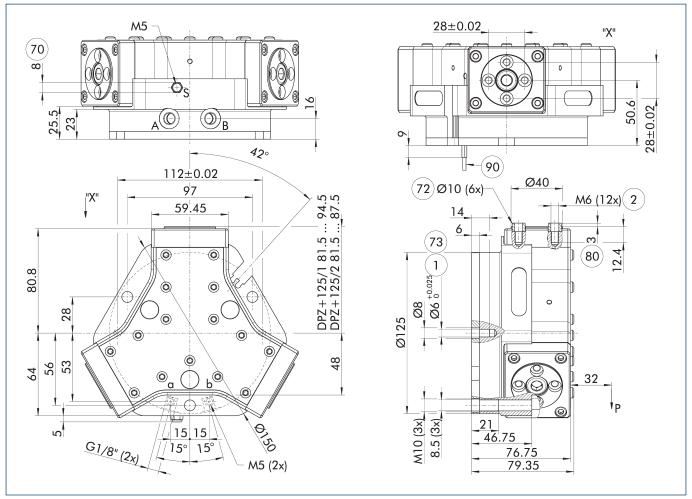
#### **Technical data**

Description		DPZ-plus 125-1	DPZ-plus 125-2	DPZ-plus 125-1-AS	DPZ-plus 125-2-AS	DPZ-plus 125-1-IS	DPZ-plus 125-2-IS
ID		1316303	1316304	1316306	1316307	1316308	1316309
Stroke per jaw	[mm]	13	6	13	6	13	6
Closing/opening force	[N]	2945/3000	5510/6200	3940/-	7000/-	-/4015	-/8300
Min. spring force	[N]			995	1490	1015	2100
Weight	[kg]	3.5	3.5	4.7	4.7	4.7	4.7
Recommended workpiece weight	[kg]	14.7	27.5	14.7	27.5	14.7	27.5
Cylinder volume per double stroke	[cm³]	230	230	383	383	383	383
Min./nom./max. operating pressure	[bar]	2.5/6/8	2.5/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	0.25/0.25	0.25/0.25	0.22/0.45	0.22/0.45	0.45/0.22	0.45/0.22
Max. permissible finger length	[mm]	125	100	100	80	100	80
Max. permissible weight per finger	[kg]	1.75	1.75	1.75	1.75	1.75	1.75
IP protection class		67	67	67	67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Cleanroom class ISO 14644-1		5	5	5	5	5	5
Dimensions Ø D x Z	[mm]	172.2 x 76.75	172.2 x 76.75	172.2 x 101.15	172.2 x 101.15	172.2 x 101.15	172.2 x 101.15
Options and their characteristics							
High-temperature version		1321341	1321342	1321343	1321344	1321345	1321346
Min./max. ambient temperature	[°C]	5/130	5/130	5/130	5/130	5/130	5/130

① Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

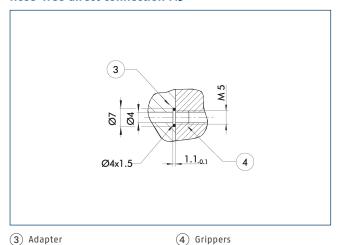
## Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

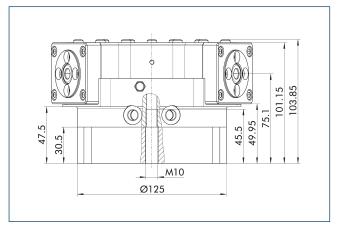
- As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S, E Air purge connection, or deaeration bore
- (1) Gripper connection
- (2) Finger connection
- (70) Wrench size
- 72 Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

#### Hose-free direct connection M5



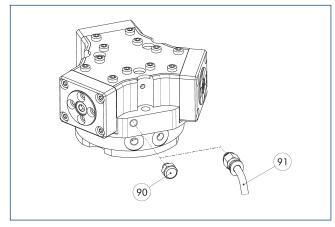
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

# **Gripping force maintenance version AS/IS**



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

# Connect the air purge connection

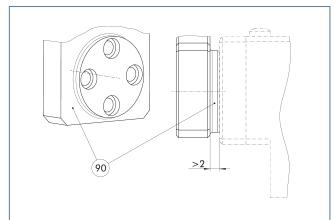


90 Sinter filter

(91) Hose for ventilation or air purge connection

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

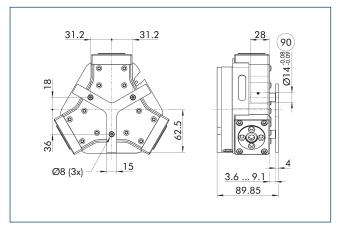
# Proposed jaw design



90 Step

In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

# Spring-loaded pressure piece

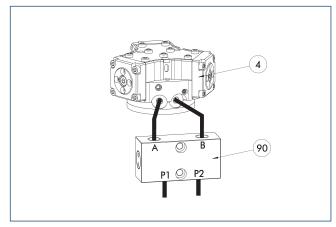


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
		[mm]	[N]
Spring-loaded pressure piece			
A-PZN-plus/DPZ-plus 125	0303723	5.5	105

# SDV-P pressure maintenance valve



4 Grippers

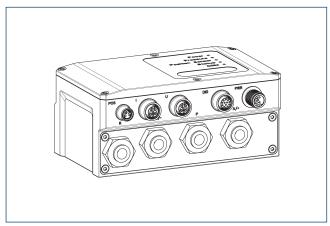
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance	e valve	
SDV-P 04	0403130	6
SDV-P 07	0403131	8
Pressure maintenance	e valve with a	ir bleed screw
SDV-P 04-E	0300120	6
SDV-P 07-E	0300121	8

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

# **Pneumatic positioning device PPD**

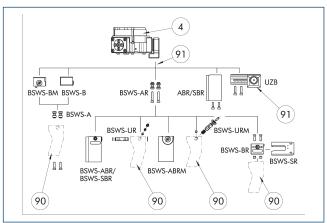


The PPD allows flexibility in all applications with pneumatic grippers through free positioning, gripping force and speed adjustment.

Description	ID
Pneumatic positioning device	
PPD 20-IOL	1540700
Adapter	
A GGN0804-1204-A	1540691
10-Link connection cable	
KA GGN1205-1212-IOL-00100-A	1540697
Voltage supply connection cable - c	able track comp
KA GLN12B05-LK-01000-A	1540660
Cable extension	
KV GGN0804-I0-00150-A	1540662
KV GGN0804-10-00300-A	1540663
Assembly set	
Assembly set PPD	1540705

① In addition to the PPD, a position sensor (SCHUNK IO-Link sensor or analog sensor (4...20 mA)) is required.

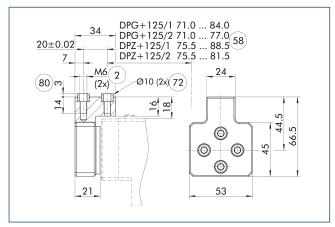
# Intermediate jaw interface



- 4 Grippers
- 90 Customized gripper fingers
- (91) Uniform screw connection pattern

By using the intermediate jaw, you have the possibility of directly connecting a wide range of accessories directly. This includes jaw quick-change systems, finger blanks, and universal intermediate jaws.

# ZBA DPG-plus/DPZ-plus 125-100 intermediate jaw

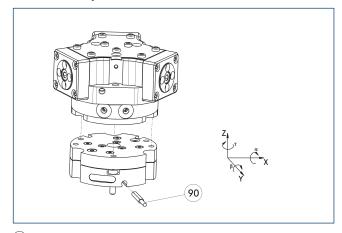


- 2 Finger connection
- 58 Distance from center of gripper
- 72) Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part

Optionally intermediate jaws can be used, enabling direct connection and alignment of top jaws and various standard accessories in Z-direction.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-DPG-DPZ-plus 125-100	0300195	Aluminum	PGN-plus 100	1

## Tolerance compensation unit TCU

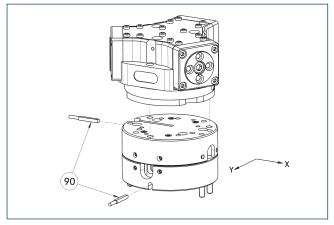


90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-125-3-MV	0324820	yes	±1°/±1°/±1°	•
TCU-Z-125-3-0V	0324821	no	±1°/±1°/±1°	

## Compensation unit AGE-F

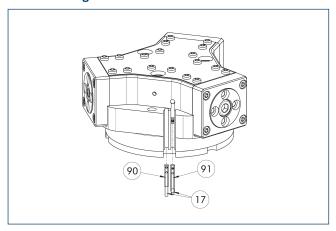


## 90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-080-1	0324960	± 5	39	
AGE-F-XY-080-2	0324961	± 5	85	
AGE-F-XY-080-3	0324962	± 5	90	•

# **Electronic magnetic switch MMS**



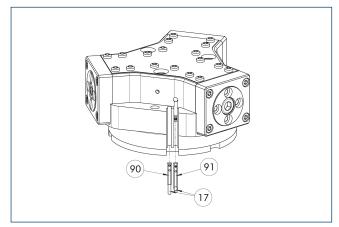
- $\widehat{17}$  Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

301032	
301032	
	•
301034	
teral cable c	outlet
301042	•
301044	
301622	•
301623	
301594	
301502	
301463	
301495	
301496	
301497	•
301775	•
301746	
301751	
t 3 3 3 3 3 3 3 3 3 3 3	eral cable of 01042 01044 01622 01623 01594 01502 01463 01495 01497 01775 01746

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

# Programmable magnetic switch MMS 22-PI1



(17) Cable outlet

(91) Sensor MMS 22 ..-PI1-...-SA

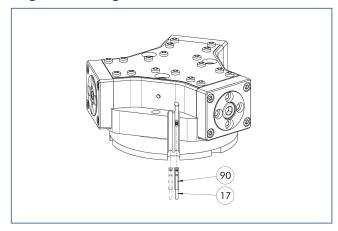
90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined			
Programmable magnetic switch					
MMS 22-PI1-S-M8-PNP	0301160	•			
MMSK 22-PI1-S-PNP	0301162				
Programmable magnetic switch with lateral cable outlet					
MMS 22-PI1-S-M8-PNP-SA	0301166	•			
MMSK 22-PI1-S-PNP-SA	0301168				
Programmable magnetic switch with stainless steel housing					
MMS 22-PI1-S-M8-PNP-HD	0301110	•			
MMSK 22-PI1-S-PNP-HD	0301112				

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

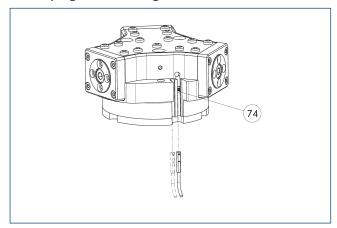
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined			
Programmable magnetic switch					
MMS 22-PI2-S-M8-PNP	0301180	•			
MMSK 22-PI2-S-PNP	0301182				
Programmable magnetic switch	Programmable magnetic switch with lateral cable outlet				
MMS 22-PI2-S-M8-PNP-SA	0301186	•			
MMSK 22-PI2-S-PNP-SA	0301188				
Programmable magnetic switch with stainless steel housing					
MMS 22-PI2-S-M8-PNP-HD	0301130	•			
MMSK 22-PI2-S-PNP-HD	0301132				

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## MMS-P programmable magnetic switch



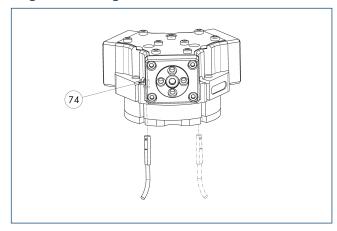
## (74) Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined			
Programmable magnetic switch					
MMSK-P 22-S-PNP	0301371				
MMS-P 22-S-M8-PNP	0301370	•			
Connection cables					
KA GLN0804-LK-00500-A	0307767	•			
KA GLN0804-LK-01000-A	0307768				
KA WLN0804-LK-00500-A	0307765				
KA WLN0804-LK-01000-A	0307766				
Clip for connector/socket					
CLI-M8	0301463				
Sensor distributor					
V2-M8-4P-2XM8-3P	0301380				

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## Programmable magnetic switch MMS-I0-Link



#### 74) Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. The sensor is programmed for the gripper via the IO-Link interface, Magnet teaching tool MT (included in scope of delivery; ID 0301030) or the ST plug teaching tool (not included in scope of delivery; ID 0301026). An IO-Link master is required for operation.

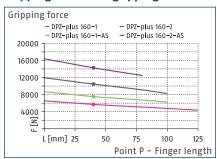
Description	ID
Programmable mag	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

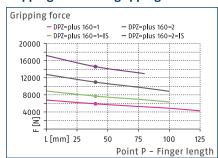
Sealed universal gripper



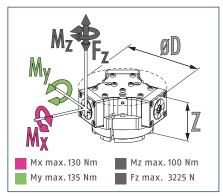
## Gripping force 0.D. gripping



# Gripping force O.D. gripping



#### **Dimensions and maximum loads**



The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

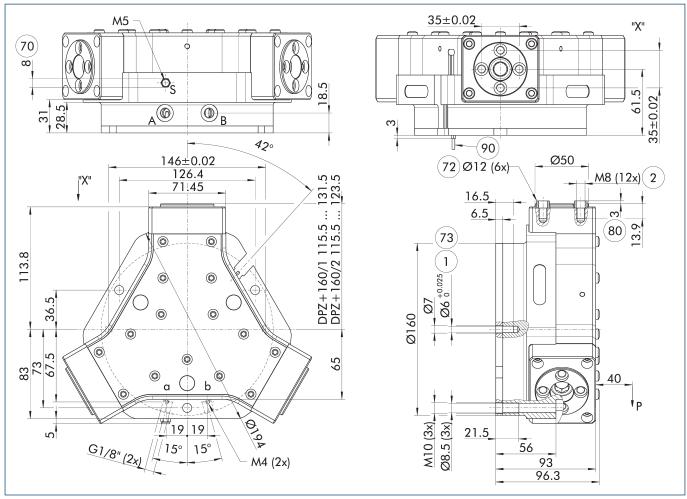
#### **Technical data**

Description		DPZ-plus 160-1	DPZ-plus 160-2	DPZ-plus 160-1-AS	DPZ-plus 160-2-AS	DPZ-plus 160-1-IS	DPZ-plus 160-2-IS
ID		1316310	1316312	1316313	1316314	1316315	1316316
Stroke per jaw	[mm]	16	8	16	8	16	8
Closing/opening force	[N]	5700/5880	10450/10950	7530/-	14260/-	-17865	-/15070
Min. spring force	[N]			1830	3810	1985	4120
Weight	[kg]	7.9	7.9	9.7	9.7	9.7	9.7
Recommended workpiece weight	[kg]	28.5	52	28.5	52	28.5	52
Cylinder volume per double stroke	[cm³]	520	520	875	875	875	875
Min./nom./max. operating pressure	[bar]	2.5/6/8	2.5/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	0.6/0.6	0.6/0.6	0.5/1	0.5/1	1/0.5	1/0.5
Max. permissible finger length	[mm]	125	100	100	80	100	80
Max. permissible weight per finger	[kg]	3	3	3	3	3	3
IP protection class		67	67	67	67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.02	0.02	0.02	0.02	0.02	0.02
Cleanroom class ISO 14644-1		5	5	5	5	5	5
Dimensions Ø D x Z	[mm]	238.6 x 93	238.6 x 93	238.6 x 122.9	238.6 x 122.9	238.6 x 122.9	238.6 x 122.9
Options and their characteristics							
High-temperature version		1321347	1321350	1321351	1321352	1321354	1321355
Min./max. ambient temperature	[°C]	5/130	5/130	5/130	5/130	5/130	5/130

① Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

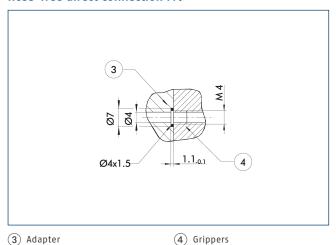
## Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

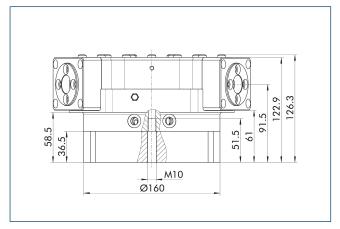
- As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S, E Air purge connection, or deaeration bore
- (1) Gripper connection
- 2 Finger connection
- 70 Wrench size
- 72 Fit for centering sleeves
- (73) Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

#### Hose-free direct connection M4



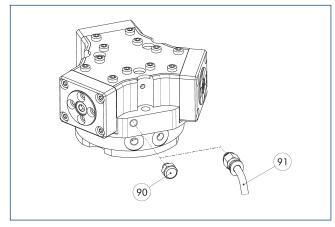
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

# **Gripping force maintenance version AS/IS**



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

## Connect the air purge connection

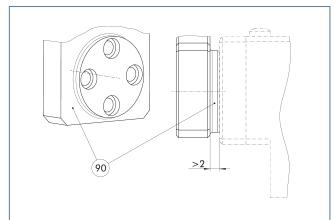


90 Sinter filter

(91) Hose for ventilation or air purge connection

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

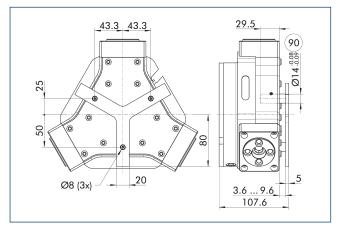
# Proposed jaw design



90 Step

In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

# Spring-loaded pressure piece

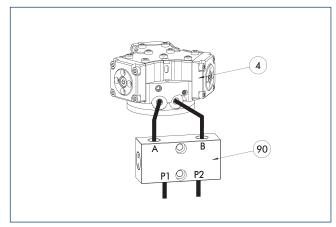


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
		[mm]	[N]
Spring-loaded pressure piece			
A-PZN-plus/DPZ-plus 160	0303724	6	150

# SDV-P pressure maintenance valve



4 Grippers

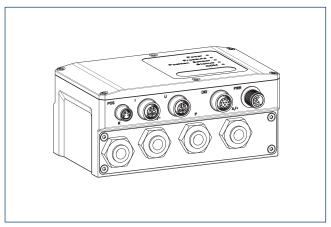
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance	e valve	
SDV-P 04	0403130	6
SDV-P 07	0403131	8
Pressure maintenance	e valve with a	ir bleed screw
SDV-P 04-E	0300120	6
SDV-P 07-E	0300121	8

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

# **Pneumatic positioning device PPD**

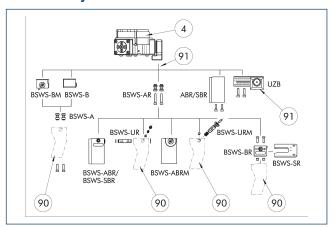


The PPD allows flexibility in all applications with pneumatic grippers through free positioning, gripping force and speed adjustment.

Description	ID
Pneumatic positioning device	
PPD 40-IOL	1540701
Adapter	
A GGN0804-1204-A	1540691
IO-Link connection cable	
KA GGN1205-1212-IOL-00100-A	1540697
Voltage supply connection cable - cab	le track compa
KA GLN12B05-LK-01000-A	1540660
Cable extension	
KV GGN0804-I0-00150-A	1540662
KV GGN0804-10-00300-A	1540663
Assembly set	
Assembly set PPD	1540705

① In addition to the PPD, a position sensor (SCHUNK IO-Link sensor or analog sensor (4...20 mA)) is required.

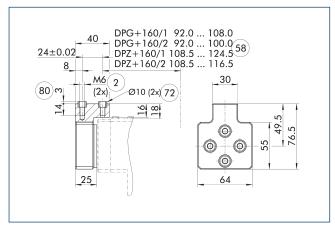
# Intermediate jaw interface



- 4 Grippers
- 90 Customized gripper fingers
- (91) Uniform screw connection pattern

By using the intermediate jaw, you have the possibility of directly connecting a wide range of accessories directly. This includes jaw quick-change systems, finger blanks, and universal intermediate jaws.

# ZBA DPG-plus/DPZ-plus 160-125 intermediate jaw

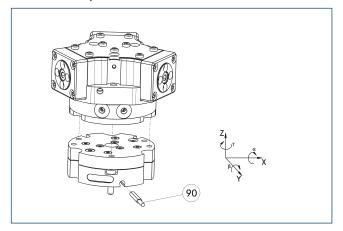


- 2 Finger connection
- 58 Distance from center of gripper
- 72) Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part

Optionally intermediate jaws can be used, enabling direct connection and alignment of top jaws and various standard accessories in Z-direction.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-DPG-DPZ-plus 160-125	0300196	Aluminum	PGN-plus 125	1

## Tolerance compensation unit TCU

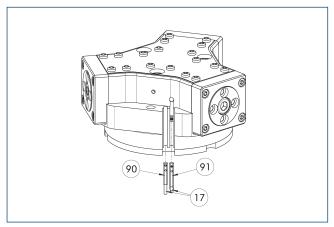


90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-160-3-MV	0324838	yes	±1°/±1°/±1°	•
TCU-Z-160-3-0V	0324839	no	±1°/±1°/±1°	

# **Electronic magnetic switch MMS**



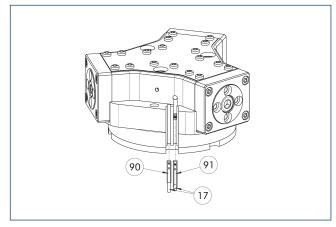
- (17) Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable (	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Programmable magnetic switch MMS 22-PI1



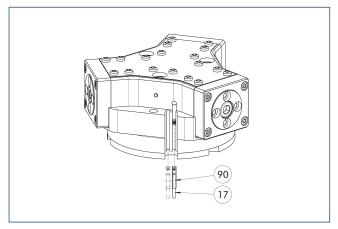
- (17) Cable outlet
- **91**) Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	•
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI1-S-M8-PNP-SA	0301166	•
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI1-S-M8-PNP-HD	0301110	•
MMSK 22-PI1-S-PNP-HD	0301112	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

# Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

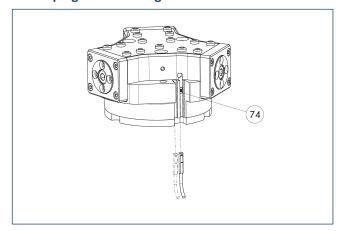
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics integrated in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	•
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI2-S-M8-PNP-SA	0301186	•
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch	with stainless	s steel housing
MMS 22-PI2-S-M8-PNP-HD	0301130	•
MMSK 22-PI2-S-PNP-HD	0301132	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## MMS-P programmable magnetic switch



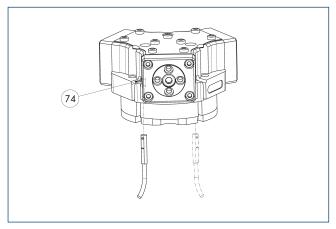
74) Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic switc	h	
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	•
Connection cables		
KA GLN0804-LK-00500-A	0307767	•
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
Clip for connector/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

# Programmable magnetic switch MMS-IO-Link



## 74 Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. The sensor is programmed for the gripper via the IO-Link interface, Magnet teaching tool MT (included in scope of delivery; ID 0301030) or the ST plug teaching tool (not included in scope of delivery; ID 0301026). An IO-Link master is required for operation.

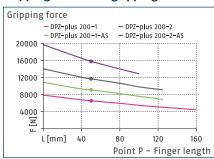
Description	ID
Programmable mag	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

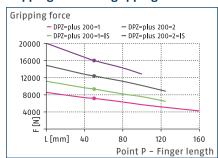
Sealed universal gripper



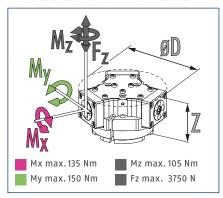
## Gripping force 0.D. gripping



# **Gripping force I.D. gripping**



#### **Dimensions and maximum loads**



The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

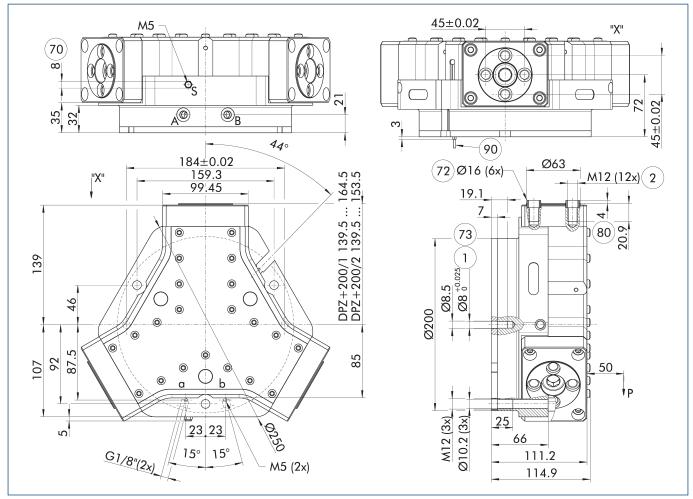
#### **Technical data**

Description		DPZ-plus 200-1	DPZ-plus 200-2	DPZ-plus 200-1-AS	DPZ-plus 200-2-AS	DPZ-plus 200-1-IS	DPZ-plus 200-2-IS
ID		1316317	1316318	1316320	1316321	1316322	1316323
Stroke per jaw	[mm]	25	14	25	14	25	14
Closing/opening force	[N]	6750/7160	12060/12410	9300/-	16500/-	-/9910	-/17150
Min. spring force	[N]			2550	4440	2750	4740
Weight	[kg]	15.6	15.6	20.1	20.1	20.1	20.1
Recommended workpiece weight	[kg]	33.5	60	33.5	60	33.5	60
Cylinder volume per double stroke	[cm³]	1040	1040	1725	1725	1725	1725
Min./nom./max. operating pressure	[bar]	2.5/6/8	2.5/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	1.5/1.5	1.5/1.5	1.2/1.8	1.2/1.8	1.8/1.2	1.8/1.2
Max. permissible finger length	[mm]	160	125	125	100	125	100
Max. permissible weight per finger	[kg]	5.5	5.5	5.5	5.5	5.5	5.5
IP protection class		67	67	67	67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.05	0.05	0.05	0.05	0.05	0.05
Cleanroom class ISO 14644-1		5	5	5	5	5	5
Dimensions Ø D x Z	[mm]	295.3 x 110.9	295.3 x 110.9	295.3 x 146.9	295.3 x 146.9	295.3 x 146.9	295.3 x 146.9
Options and their characteristics							
High-temperature version		1321356	1321357	1321358	1321360	1321361	1321362
Min./max. ambient temperature	[°C]	5/130	5/130	5/130	5/130	5/130	5/130

① Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

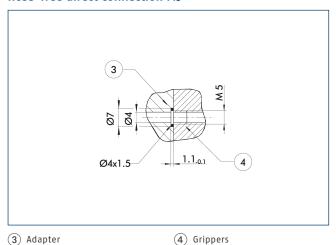
## Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

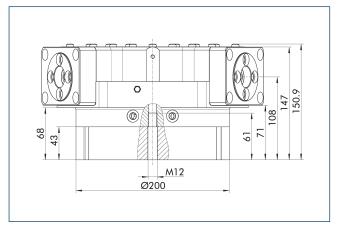
- As an alternative/in addition to spring-assisted mechanical gripping force maintenance, the SDV-P pressure maintenance valve can be used for I.D. and O.D. gripping (see "Accessories" section of catalog).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S, E Air purge connection, or deaeration bore
- (1) Gripper connection
- (2) Finger connection
- 70 Wrench size
- 72 Fit for centering sleeves
- (73) Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

#### Hose-free direct connection M5



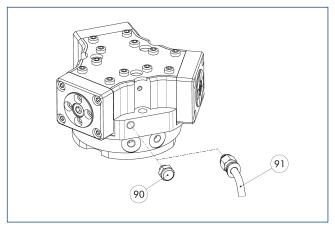
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

## **Gripping force maintenance version AS/IS**



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. In the AS/S variant this acts as a closing force, in the IS variant as an opening force. Besides this, gripping force maintenance can be used to increase gripping force or for single actuated gripping.

## Connect the air purge connection

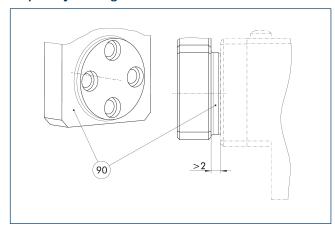


90 Sinter filter

(91) Hose for ventilation or air purge connection

Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

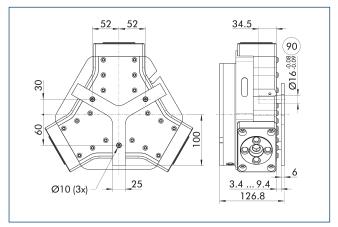
## Proposed jaw design



90 Step

In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

# Spring-loaded pressure piece

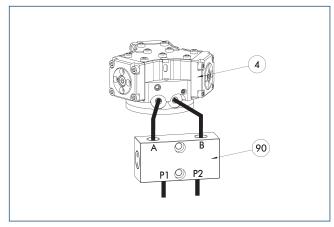


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force		
		[mm]	[N]		
Spring-loaded pressure piece					
A-PZN-plus/DPZ-plus 200	0303725	6	200		

# SDV-P pressure maintenance valve



4 Grippers

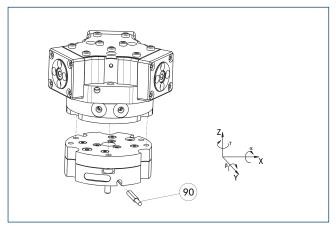
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter		
		[mm]		
Pressure maintenance valve				
SDV-P 04	0403130	6		
SDV-P 07	0403131	8		
Pressure maintenance valve with air bleed screw				
SDV-P 04-E	0300120	6		
SDV-P 07-E	0300121	8		

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

# Tolerance compensation unit TCU

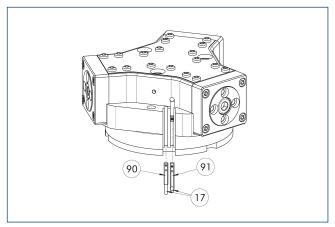


## 90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-200-3-MV	0324856	yes	±1°/±1°/±1°	•
TCU-Z-200-3-0V	0324857	no	±1°/±1°/±1°	

# **Electronic magnetic switch MMS**



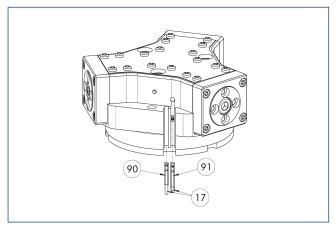
- 17) Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined		
Electronic magnetic switch				
MMS 22-S-M8-PNP	0301032	•		
MMSK 22-S-PNP	0301034			
Electronic magnetic switches with	lateral cable o	outlet		
MMS 22-S-M8-PNP-SA	0301042	•		
MMSK 22-S-PNP-SA	0301044			
Reed Switches				
RMS 22-S-M8	0377720	•		
Connection cables				
KA BG08-L 3P-0300-PNP	0301622	•		
KA BG08-L 3P-0500-PNP	0301623			
KA BW08-L 3P-0300-PNP	0301594			
KA BW08-L 3P-0500-PNP	0301502			
Clip for connector/socket				
CLI-M8	0301463			
Cable extension				
KV BW08-SG08 3P-0030-PNP	0301495			
KV BW08-SG08 3P-0100-PNP	0301496			
KV BW08-SG08 3P-0200-PNP	0301497	•		
Sensor distributor				
V2-M8	0301775	•		
V4-M8	0301746			
V8-M8	0301751			

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

# Programmable magnetic switch MMS 22-PI1



- 17) Cable outlet
- 91) Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery, ID 0301030) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

ID	Often combined				
Programmable magnetic switch					
0301160	•				
0301162					
Programmable magnetic switch with lateral cable outlet					
0301166	•				
0301168					
Programmable magnetic switch with stainless steel housing					
0301110	•				
0301112					
	0301160 0301162 with lateral c 0301166 0301168 with stainles:				

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.



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