

Hand in hand for tomorrow



## Product data sheet

Long-stroke gripper PSH 22

**Compact. Flexible. Fully encapsulated.**

## Long-stroke gripper PSH

2-finger parallel gripper with long jaw stroke and dirt-resistant round guidance

### Field of application

in contaminated work environments and for a large parts spectrum



### Advantages – Your benefits

**High maximum moments possible** suitable for using long gripper fingers

**Dirt-protected round guidances** sealed, for long strokes

**Fastening at two gripper sides with centering** for universal and flexible gripper assembly

**Air supply via hose-free direct connection or screw connections** for flexible pressure supply in all automated systems

**Comprehensive sensor accessory program** for versatile querying possibilities and stroke position monitoring



Sizes  
Quantity: 4



Weight  
0.77 .. 8.05 kg



Gripping force  
320 .. 1760 N



Stroke per jaw  
14 .. 100 mm



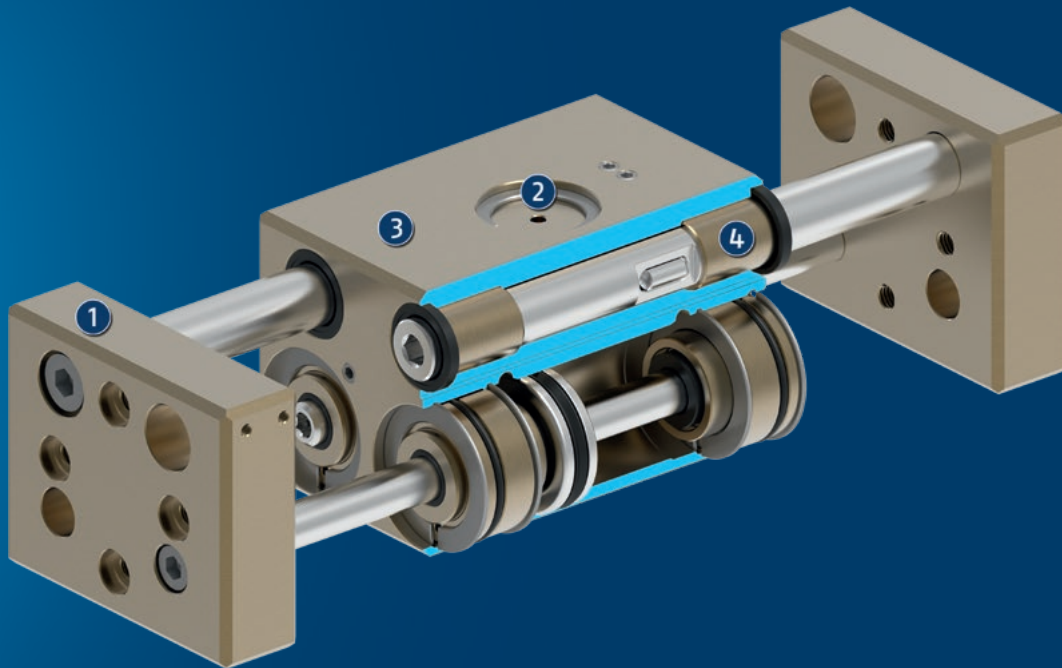
Workpiece weight  
1.6 .. 8.8 kg

## Functional description

By actuating the pistons with compressed air, the base jaws, which are located at the piston and the rack, are moved.

The jaw stroke is synchronized by means of rack and

pinion kinematics.



① **Base jaw**  
for the connection of workpiece-specific gripper fingers

② **Kinematics**  
Rack and pinion principle for centric gripping

③ **Housing**  
is weight-optimized due to the use of high-strength aluminum alloy

④ **Round guidances**  
sealed, for long strokes

## General notes about the series

**Operating principle:** Rack and pinion principle

**Housing material:** hard-anodized, high strength aluminum

**Base jaw material:** hard-anodized, high strength aluminum

**Actuation:** pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

**Warranty:** 24 months

**Service life characteristics:** on request

**Scope of delivery:** Centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

**Gripping force maintenance:** possible with pressure maintenance valve SDV-P

**Gripping force:** is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

**Finger length:** is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

**Repeat accuracy:** is defined as a distribution of the end Position for 100 consecutive strokes.

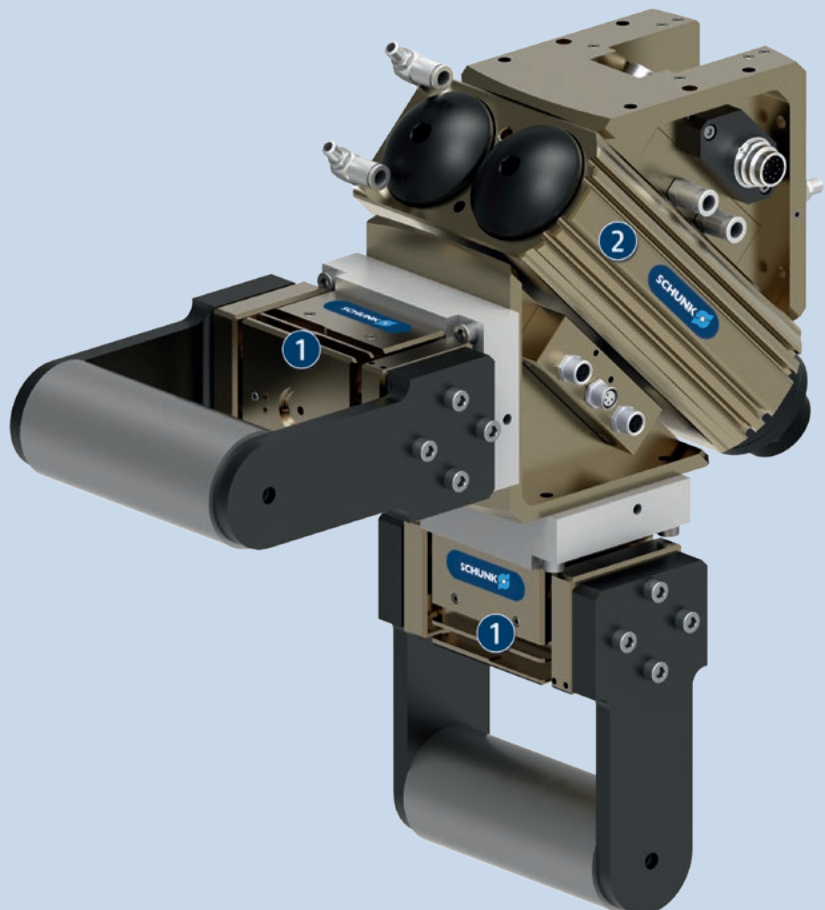
**Workpiece weight:** is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

**Closing and opening times:** are movement times of the base jaws only, without application-specific gripper fingers. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

## Application example

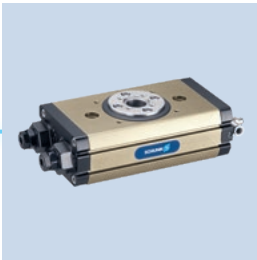
Rapid loading and unloading unit on a swivel head base. Due to the robustness of this unit, it is particularly suitable for use in machine tools.

- ❶ 2-finger parallel gripper PSH
- ❷ Swivel head SRH-plus

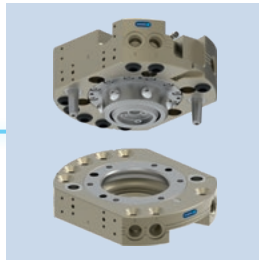


## SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Universal swivel unit



Tool changer



Tolerance compensation unit



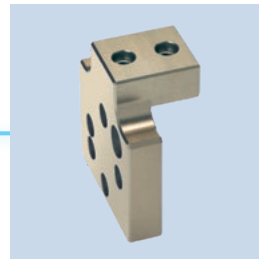
Pressure maintenance valve



Magnetic switches



Finger blank



Intermediate jaw



Jaw quick-change system



Inductive proximity switch

① For more information on these products can be found on the following product pages or at [schunk.com](https://www.schunk.com).

## Options and special information

**Finger position:** can be monitored by magnetic and/or inductive proximity switches. Unsynchronized version possible upon request as application-specific design.

**High-temperature version V/HT:** for use in hot environments

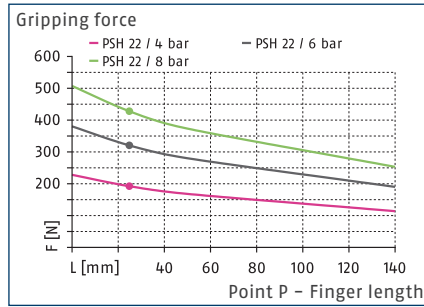
**ATEX version EX:** for explosive environments

**Additional versions:** Various options can be combined with each other. Numerous additional options are also available – just tell us what your task is!

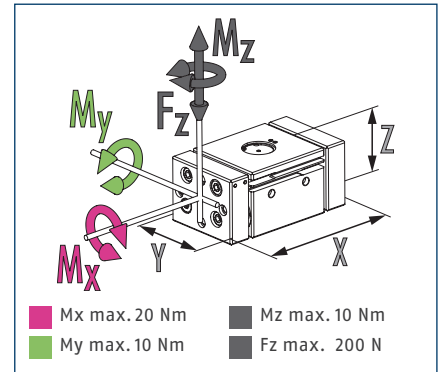
**Food-grade lubrication:** The product contains food-compliant lubricants as standard. The requirements of EN 1672-2:2020 are not fully met. The relevant NSF certificates are available at <https://info.nsf.org/USDA/Listings.asp> using the lubricant information in the operating manual.



### Gripping force



### Dimensions and maximum loads



① The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

### Technical data

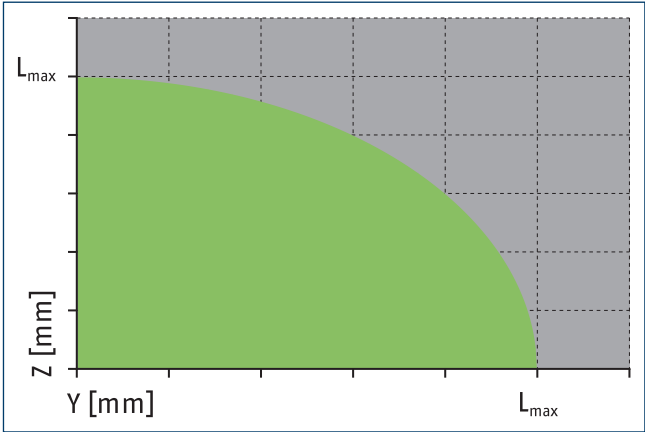
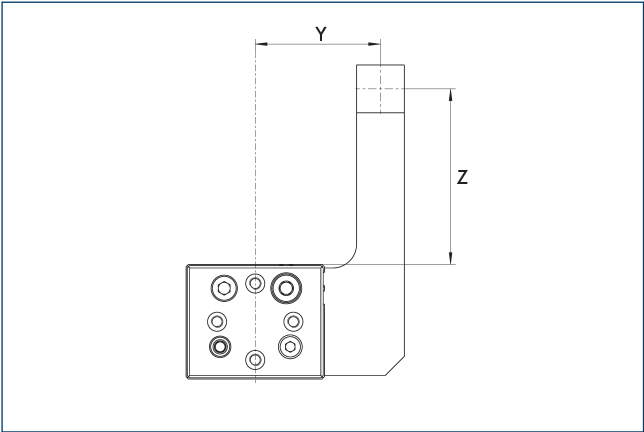
Description		PSH 22-1	PSH 22-2
ID		0302122	0302123
Stroke per jaw	[mm]	28	14
Closing/opening force	[N]	320/320	320/320
Weight	[kg]	0.95	0.77
Recommended workpiece weight	[kg]	1.6	1.6
Cylinder volume per double stroke	[cm³]	36	18
Min./nom./max. operating pressure	[bar]	3/6/8	3/6/8
Closing/opening time	[s]	0.15/0.15	0.12/0.12
Max. permissible finger length	[mm]	140	140
Max. permissible weight per finger	[kg]	0.8	0.8
IP protection class		67	67
Min./max. ambient temperature	[°C]	5/90	5/90
Repeat accuracy	[mm]	0.1	0.1
Dimensions X x Y x Z	[mm]	137 x 58 x 48	95 x 58 x 48
<b>Options and their characteristics</b>			
High-temperature version		39302122	39302123
Min./max. ambient temperature	[°C]	5/130	5/130

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

[illegible]

91) MMS 30... sensor

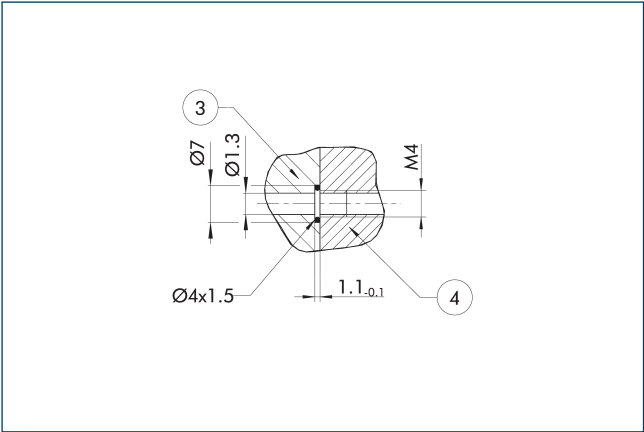
Maximum permitted finger projection



■ Permitted range      ■ Inadmissible range

L<sub>max</sub> is equivalent to the maximum permitted finger length, see the technical data table.

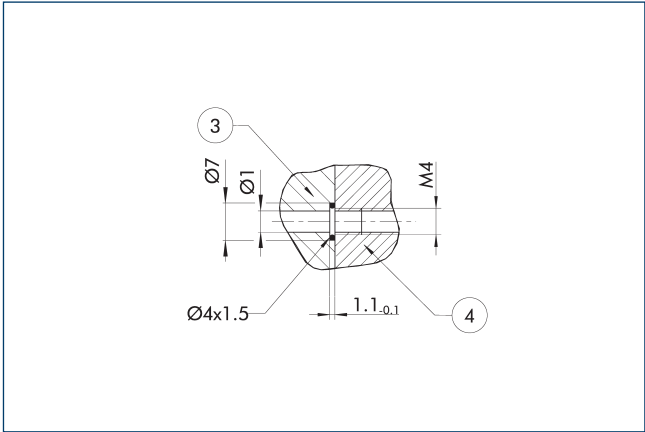
Hose-free direct connection M4 stroke variant PSH 22-1



③ Adapter      ④ Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

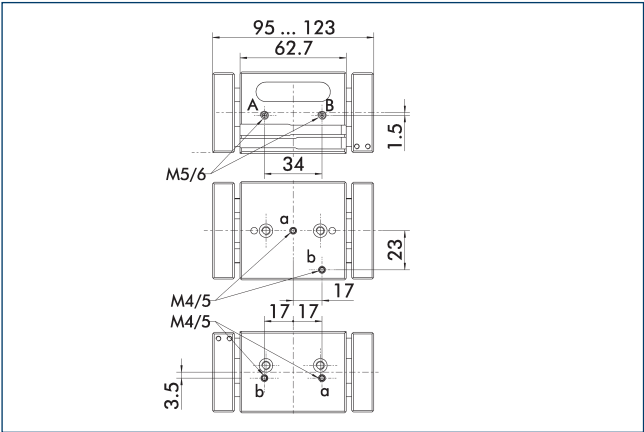
Hose-free direct connection M4 stroke variant PSH 22-2



③ Adapter      ④ Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

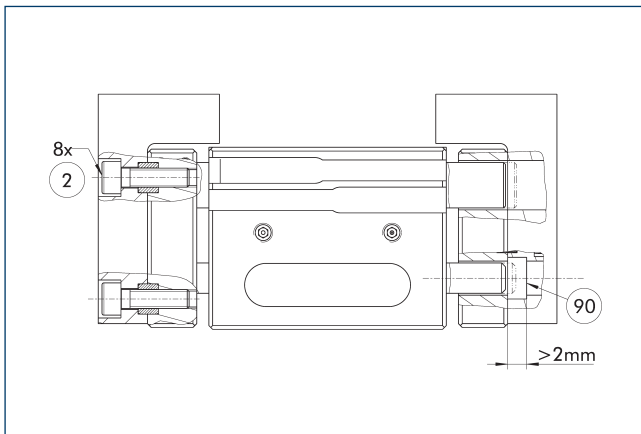
Stroke variant PSH 22-2



The drawing shows changes in dimensions of the version with a different stroke compared to the version shown in the main view.



## Finger design

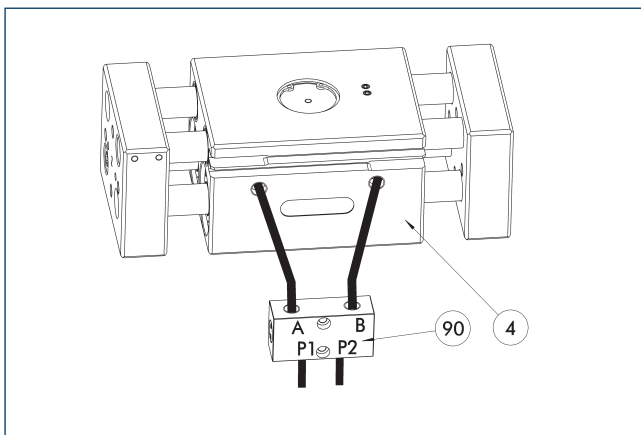


② Finger connection

⑨⑩ Recess

When closing the gripper completely, the piston rod can project beyond the end. If the entire closing stroke is required in the application, the recess is essential.

## SDV-P pressure maintenance valve



④ Grippers

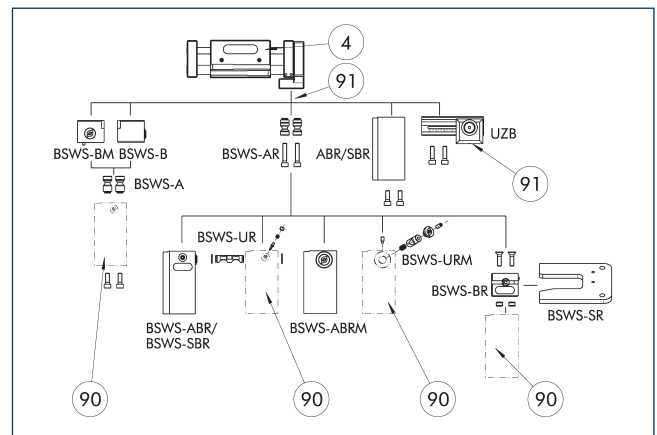
⑨⑩ SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance valve		
SDV-P 04	0403130	6
Pressure maintenance valve with air bleed screw		
SDV-P 04-E	0300120	6

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at [schunk.com](http://schunk.com).

## Intermediate jaw interface



④ Grippers

⑨⑩ Customized gripper fingers

⑨⑩ Uniform screw connection pattern

By using the intermediate jaw, you have the possibility of directly connecting a wide range of accessories directly. This includes jaw quick-change systems, finger blanks, and universal intermediate jaws.

- | Description      | ID      | Material | Finger interface | Scope of delivery |
|------------------|---------|----------|------------------|-------------------|
| Intermediate jaw |         |          |                  |                   |
| ZBA-PSH-22-80    | 0300225 | Aluminum | PGN-plus 80      | 2                 |

Technical drawing of the FPS-S 13 fire protection system, showing a side view and a top view.

**Side View Dimensions:**

- Overall height: 24.5 PSH 22/1
- Overall width: 22.5 PSH 22/2
- Bottom flange width: 75 PSH 22/1
- Bottom flange depth: 47.5 PSH 22/2
- Bottom flange thickness: 0.5
- Top flange height: 10

**Top View Dimensions:**

- Overall width: 22.5 PSH 22/2
- Overall height: 24.5 PSH 22/1

The drawing includes a label "FPS-S 13" pointing to the side view of the unit.

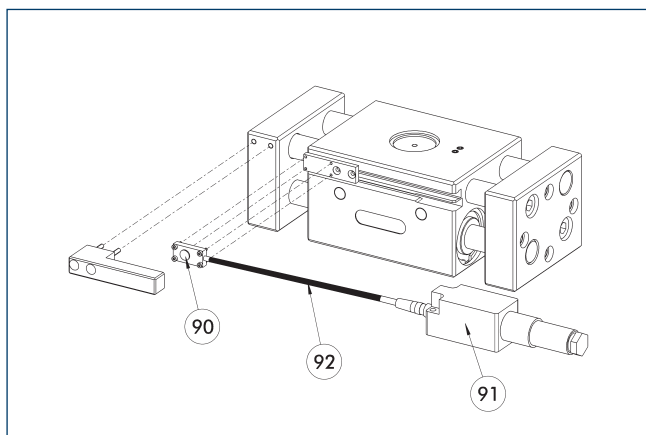
Description	ID	
Attachment kit for FPS		
AS-FPS-PSH 22-1	0301736	
AS-FPS-PSH 22-2	0301737	

- 
- This diagram illustrates the assembly of the extruder. It shows a motor unit with a gear train (labeled 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100) and a filament guide (labeled 101, 102, 103, 104, 105, 106, 107, 108, 109, 110, 111, 112, 113, 114, 115, 116, 117, 118, 119, 120, 121, 122, 123, 124, 125, 126, 127, 128, 129, 130, 131, 132, 133, 134, 135, 136, 137, 138, 139, 140, 141, 142, 143, 144, 145, 146, 147, 148, 149, 150, 151, 152, 153, 154, 155, 156, 157, 158, 159, 160, 161, 162, 163, 164, 165, 166, 167, 168, 169, 170, 171, 172, 173, 174, 175, 176, 177, 178, 179, 180, 181, 182, 183, 184, 185, 186, 187, 188, 189, 190, 191, 192, 193, 194, 195, 196, 197, 198, 199, 200). The components are shown in an exploded view, indicating their relative positions and assembly order.

Description	ID	Often combined
Attachment kit for proximity switch		
HG-PSH 22-1	0300754	
HG-PSH 22-2	0300755	
Inductive proximity switch		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	●
IN-C 80-S-M8-PNP	0301475	
INK 80-S	0301550	
INK 80-SL	0301579	

- 10

## Flexible position sensor



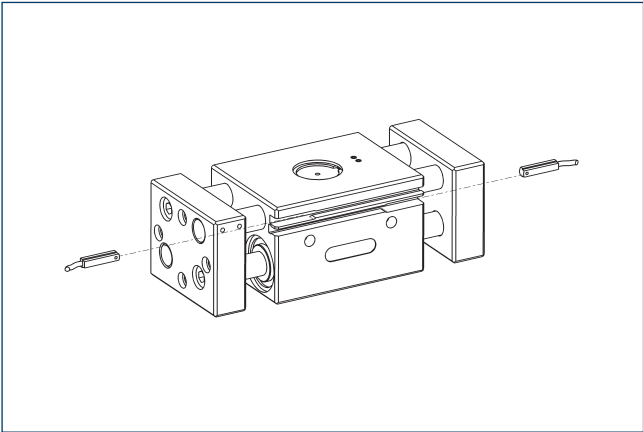
- 90 FPS-S sensor                      92 Cable extension  
 91 FPS-F5 evaluation electronic

Flexible position monitoring of up to five positions.

Description	ID	Often combined
Attachment kit for FPS		
AS-FPS-PSH 22-1	0301736	
AS-FPS-PSH 22-2	0301737	
Sensor		
FPS-S 13	0301705	
Evaluation electronics		
FPS-F5	0301805	●
Cable extension		
KV BG08-SG08 3P-0050	0301598	
KV BG08-SG08 3P-0100	0301599	

- ⓘ When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available – see catalog chapter "Accessories."

Electronic magnetic switch MMS



End position monitoring for mounting in the T-slot

Description	ID	Often combined
Electronic magnetic switch		
MMS 30-S-M12-PNP	0301571	
MMS 30-S-M8-PNP	0301471	●
MMSK 30-S-PNP	0301563	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
Clip for connector/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

❗ Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.





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